

Biol635/Math635/Biol432/Math430  
Fall 2021

Homework 1

**Answer the following questions.**

- Justify your answers.
- Explain your results.
- Provide the necessary calculations in a clear way.
- Provide the codes you used (if any).

Consider the following *modified logistic equation with a threshold*. This equation has many applications. In particular, it can be used to describe the transition of a system from a resting state ( $V_{rest}$ ) to an activated state ( $V_{act}$ ) when they exist

$$\frac{dV}{dt} = F(V). \quad (1)$$

The existence of these states depends on the model parameters. In (1)  $t$  represents time,  $V$  is the dependent variable (e.g., voltage), and the function  $F(V)$  is given by

$$F(V) = -r V \left(1 - \frac{V}{T}\right) \left(1 - \frac{V}{K}\right) + I_{app}. \quad (2)$$

The parameters  $r, K, T$  and  $I_{app}$  constants,  $r, K, T > 0$  and  $T < K$ . For  $I_{app} = 0$ , eq (1) has three equilibria ( $V_{eq}$ ):  $V_{rest} = 0$ ,  $V_{th} = T$  and  $V_{sat} = K$  (resting, threshold and saturation equilibria, respectively). The parameter  $I_{app}$  represents the input given to the system (e.g., applied DC current). The three equilibria ( $V_{rest}$ ,  $V_{th}$  and  $V_{sat}$ ) depend on  $I_{app}$  and may cease to exist for certain ranges of values of  $I_{app}$ . The parameter  $r$  represents the rate constant (inverse of the time constant for the unbiased case  $I_{app} = 0$ ). The units depend on the problem at hand. If the model is intended for the dynamics of a neuron, then the units of  $t$  are milliseconds (ms) and the units of  $V$  are millivolts (mV).

1. Write a code to solve numerically the ODE (1)-(2) (or adapt the template code provided in the course website). The simulation output for each set of parameter values must be
  - (a) A graph of the solution  $V(t)$ .
  - (b) The equilibrium value(s)  $V_{eq} = \lim_{t \rightarrow \infty} V(t)$
  - (c) A graph of  $F$  as a function of  $V$ .
    - Each simulation should be run long enough (large enough value of  $t$ ) so that  $V(t)$  reaches values close enough to  $V_{eq}$ , but not too long so the changes in  $V(t)$  are clearly shown.
    - Plot the two graphs as two panels in the same graph.
    - Use correct labels for the axes.
    - The fonts should be large enough (suggested: “fontsize” = 24)
2. Consider the following parameter values:  $r = 1$ ,  $T = 0.25$ ,  $K = 1$ . Perform simulations as described above for  $V(0) = 0.01$  and three values of  $I$ :  $I = 0$ ,  $I = 0.05$ ,  $I = 0.1$ .
3. (Graduate level) Consider the following parameter values and initial condition:  $r = 1$ ,  $T = 0.4$ ,  $K = 1$ ,  $I = [0, 0.2]$  with intervals  $\Delta I = 0.02$  (11 values), and  $X(0) = 0.25$ 
  - (a) Simulate the model as described above in **ascending** order of the values of  $I_{app}$ . Plot the graph of  $V_{eq}$  as a function of  $I$ .
  - (b) Simulate the model as described above in **descending** order of the values of  $I_{app}$ . Plot the graph of  $V_{eq}$  as a function of  $I_{app}$ .
4. (Graduate level) Consider the following parameter values and initial condition:  $r = 1$ ,  $T = 0.4$ ,  $K = 1$ ,  $I_{app} = [0, 0.2]$  with intervals  $\Delta I = 0.02$  (11 values)
  - (a) Simulate the model as described above in **ascending** order of the values of  $I$ . For  $I = 0$  use  $V(0) = 0$ . For  $I_{app} > 0$  set  $V(0)$  equal to  $V_{eq}$  in the simulation for the previous value of  $I_{app}$ .
  - (b) Simulate the model as described above in **descending** order of the values of  $I_{app}$ . For  $I_{app} = 0.2$  set  $V(0)$  equal to the value of  $V_{eq}$  computed in the previous simulation for  $I_{app} = 0.2$ . For  $I_{app} < 0.2$  set  $V(0)$  equal to  $V_{eq}$  in the previous simulation.
  - (c) Plot a single graph with all the values of  $V_{eq}$  as a function of  $I_{app}$ .