

# *Solving Systems using Laplace Transforms*

Lesson #19

6CT.5-7

# *Inversion of the LT by Partial Fraction Expansion*

$$F(s) = \frac{N(s)}{D(s)} = \frac{F_0(s^m + b_1s^{m-1} + \dots + b_m)}{(s^n + a_1s^{n-1} + \dots + a_n)}$$

Like a System Function

$$\frac{V_2(s)}{V_1(s)} = H(s) = \frac{B(s)}{A(s)}$$

Simple Roots:

$$F(s) = \frac{N(s)}{(s-s_1)(s-s_2)\dots(s-s_n)}; s_1 \neq s_2 \neq \dots \neq s_n$$

$$F(s) = \frac{K_1}{(s-s_1)} + \frac{K_2}{(s-s_2)} + \dots + \frac{K_n}{(s-s_n)}$$

$$f(t) = (K_1e^{s_1t} + K_2e^{s_2t} + \dots + K_n e^{s_nt})u(t)$$

## *Finding the Ks*

$$F(s) = \frac{N(s)}{D(s)} = \frac{N(s)}{(s-s_1)(s-s_2)\cdots(s-s_n)}$$
$$= \frac{K_1}{(s-s_1)} + \frac{K_2}{(s-s_2)} + \cdots + \frac{K_n}{(s-s_n)}$$

$$K_1 = (s-s_1)F(s)|_{s=s_1} = (s-s_1)\frac{N(s)}{D(s)}|_{s=s_1} = (s-s_1)\left[\frac{K_1}{(s-s_1)} + \frac{K_2}{(s-s_2)} + \cdots + \frac{K_n}{(s-s_n)}\right]|_{s=s_1}$$
$$= K_1 + \frac{(s-s_1)K_2}{(s-s_2)} + \cdots + \frac{(s-s_1)K_n}{(s-s_n)}|_{s=s_1} = K_1$$

⋮

$$K_n = (s-s_n)F(s)|_{s=s_n} = (s-s_n)\frac{N(s)}{D(s)}|_{s=s_n}$$

## *Example*

$$\begin{aligned} F(s) &= \frac{2s^2 + 13s + 17}{(s+1)(s+3)} \\ &= 2 + \frac{N(s)}{(s+1)(s+3)} \quad \boxed{\therefore f(t) = 2\delta(t) + [3e^{-t} + 2e^{-3t}]u(t)} \\ &= 2 + \frac{K_1}{(s+1)} + \frac{K_2}{(s+3)} \\ K_1 &= \frac{2(-1)^2 + 13(-1) + 17}{(-1+3)} = \frac{6}{2} = 3 \\ K_2 &= \frac{2(-3)^2 + 13(-3) + 17}{(-3+1)} = \frac{-4}{-2} = 2 \end{aligned}$$

# Complex Roots

$$F(s) = \frac{\mathbf{K}_1}{s - \mathbf{s}_1} + \frac{\mathbf{K}_1^*}{s - \mathbf{s}_1^*} + \dots + \frac{\mathbf{K}_n}{s - \mathbf{s}_n} + \frac{\mathbf{K}_n^*}{s - \mathbf{s}_n^*}$$

Roots are complex conjugates but the coefficients must also be complex conjugates so that  $f(t)$  is real.

Therefore, if

$$\mathcal{L}^{-1}[F(s)] = \mathcal{L}^{-1}\left[\frac{\mathbf{K}_1}{s - \mathbf{s}_1} + \frac{\mathbf{K}_1^*}{s - \mathbf{s}_1^*}\right] = \mathcal{L}^{-1}\left[\frac{\mathbf{K}_1}{s - \mathbf{s}_1}\right] + \mathcal{L}^{-1}\left[\frac{\mathbf{K}_1^*}{s - \mathbf{s}_1^*}\right]$$

$$= (\mathbf{K}_1 e^{\mathbf{s}_1 t} + \mathbf{K}_1^* e^{\mathbf{s}_1^* t}) u(t)$$

$$= (K_1 e^{j\gamma} e^{\sigma t + j\omega t} + K_1 e^{-j\gamma} e^{\sigma t - j\omega t}) u(t);$$

where  $\mathbf{K}_1 = K_1 e^{j\gamma}$  and  $\mathbf{s}_1 = \sigma + j\omega$

$$\mathcal{L}^{-1}[F(s)] = K_1 e^{\sigma t} [e^{j(\omega t + \gamma)} + e^{-j(\omega t + \gamma)}] u(t)$$

$$= 2K_1 e^{\sigma t} \cos(\omega t + \gamma) u(t)$$

$$= 2 \operatorname{Re}[\mathbf{K}_1 e^{\mathbf{s}_1 t}] u(t)$$

# *Multiple Roots*

$$F(s) = \frac{N(s)}{D(s)} = \frac{N(s)}{(s-s_1)^P D_1(s)}$$

where  $D_1(s) = (s-s_1)(s-s_2)\cdots(s-s_n)$

$$= \frac{M_0}{(s-s_1)^P} + \frac{M_1}{(s-s_1)^{P-1}} + \cdots + \frac{M_{P-1}}{(s-s_1)} + \frac{R(s)}{D_1(s)}$$

$$f(t) = \left\{ \frac{M_0}{(P-1)!} t^{P-1} + \frac{M_1}{(P-2)!} t^{P-2} + M_{P-1} \right\} e^{-s_1 t} u(t) + f_1(t)$$

$$M_0 = (s-s_1)^P F(s) \Big|_{s=s_1}$$

$$M_1 = \frac{d}{ds} \left\{ (s-s_1)^P F(s) \right\} \Big|_{s=s_1} = \frac{d}{ds} \left\{ (s-s_1)^P \frac{M_0}{(s-s_1)^P} + \frac{M_1}{(s-s_1)^{P-1}} + \cdots + \frac{M_{P-1}}{(s-s_1)} + \frac{R(s)}{D_1(s)} \right\} \Big|_{s=s_1}$$

$$= \frac{d}{ds} \left\{ M_0 + (s-s_1)M_1 + \cdots + (s-s_1)^{P-1}M_{P-1} + (s-s_1)^P \frac{R(s)}{D_1(s)} \right\} \Big|_{s=s_1}$$

$$= 0 + M_1 + \cdots + (P-1)(s-s_1)^{P-2}M_{P-1} + (P)(s-s_1)^{P-1} \frac{R(s)}{D_1(s)} \Big|_{s=s_1} = M_1$$

⋮

$$M_k = \frac{1}{k!} \frac{d^k}{ds^k} \left\{ (s-s_1)^P F(s) \right\} \Big|_{s=s_1}$$

## *An Example*

$$F(s) = \frac{3s^2 + 39s + 138}{(s+4)^2(s+2)}$$

$$= \frac{M_0}{(s+4)^2} + \frac{M_1}{s+4} + \frac{K_1}{s+2}$$

$$K_1 = (s+2)F(s) \Big|_{s=-2} = \frac{3(-2)^2 + 39(-2) + 138}{(-2+4)^2} = \frac{72}{4} = 18$$

$$M_0 = (s+4)^2 F(s) \Big|_{s=-4} = \frac{3(-4)^2 + 39(-4) + 138}{(-4+2)} = \frac{30}{-2} = -15$$

$$M_1 = \frac{d}{ds} \{(s+4)^2 F(s)\} \Big|_{s=-4} = \frac{d}{ds} \left\{ \frac{3s^2 + 39s + 138}{(s+2)} \right\} \Big|_{s=-4} =$$

$$= \left\{ \frac{6s + 39}{s+2} - \frac{3s^2 + 39s + 138}{(s+2)^2} \right\} \Big|_{s=-4}$$

$$= \frac{15}{-2} - \frac{30}{4} = -15$$

$$\therefore f(t) = [-15(t+1)e^{-4t} + 18e^{-2t}]u(t)$$

## *Another Example*

$$F(s) = \frac{3s^2 + 17s + 47}{(s+2)(s^2 + 4s + 29)} = \frac{3s^2 + 17s + 47}{(s+2)(s+2-j5)(s+2+j5)}$$

$$= \frac{K_1}{(s+2)} + \frac{\mathbf{K}_2}{(s+2-j5)} + \frac{\mathbf{K}_2^*}{(s+2+j5)}$$

$$K_1 = (s+2)F(s)|_{s=-2} = \frac{3(-2)^2 + 17(-2) + 47}{[(-2)^2 + 4(-2) + 29]} = \frac{25}{25} = 1$$

$$\mathbf{K}_2 = (s+2-j5)F(s)|_{s=-2+j5}$$

$$= \frac{3(-2+j5)^2 + 17(-2+j5) + 47}{(-2+j5+2)(-2+j5+2+j5)}$$

$$= \frac{(-63-j60) + (-34+j85) + 47}{(j5)(j10)}$$

$$= \frac{(-50+j25)}{(-50)} = 1 - j0.5$$

$$= 1.116 \angle -0.46$$

$$\mathbf{K}_2^* = 1 + j.5 = 1.116 \angle 0.46$$

$$\therefore f(t) = [1 + 2.232 \cos(5t - 0.46)]e^{-2t}u(t)$$



## *One More Example*

$$\begin{aligned}
 F(s) &= \frac{s^2}{(s^2 + 1)^2} = \frac{s^2}{(s - j)^2 (s + j)^2} \\
 &= \frac{\mathbf{M}_0}{(s - j)^2} + \frac{\mathbf{M}_0^*}{(s + j)^2} + \frac{\mathbf{M}_1}{s - j} + \frac{\mathbf{M}_1^*}{s + j} \\
 \mathbf{M}_0 &= (s - j)^2 F(s) \Big|_{s=j} = \frac{j^2}{(j + j)^2} = \frac{-1}{(2j)^2} = \frac{1}{4}
 \end{aligned}$$

$$\begin{aligned}
 \mathbf{M}_1 &= \frac{d}{ds} (s - j)^2 F(s) \Big|_{s=j} = \frac{d}{ds} \frac{s^2}{(s + j)^2} \Big|_{s=j} \\
 &= \left\{ \frac{2s}{(s + j)^2} - \frac{2s^2}{(s + j)^3} \right\} \Big|_{s=j} = \frac{2j}{(j + j)^2} - \frac{2j^2}{(j + j)^3} \\
 &= \frac{2j}{-4} - \frac{-2}{-8j} = -\frac{j}{2} - \frac{1}{4j} = -\frac{j}{2} + \frac{j}{4} = -\frac{j}{4}
 \end{aligned}$$

$$f(t) = 2 \frac{1}{4} \left[ t \cos t + \cos\left(t - \frac{\pi}{2}\right) \right] u(t) = \frac{1}{2} \left[ t \cos t + \cos\left(t - \frac{\pi}{2}\right) \right] u(t)$$

## Solving a System with LT

$$V(t) = i(t)R + L \frac{di(t)}{dt}$$

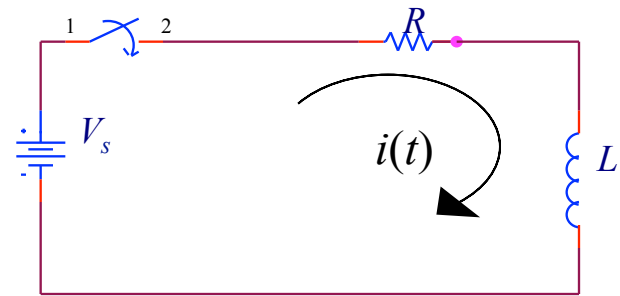
$$\frac{di}{dt} + \frac{R}{L}i = \frac{V(t)}{L} = \frac{Vu(t)}{L}$$

$$\mathcal{L}\left[\frac{di}{dt} + \frac{R}{L}i\right] = \mathcal{L}\left[\frac{V(t)}{L}\right] = \mathcal{L}\left[\frac{Vu(t)}{L}\right]$$

$$sI(s) + \frac{R}{L}I(s) = \frac{V/s}{L}$$

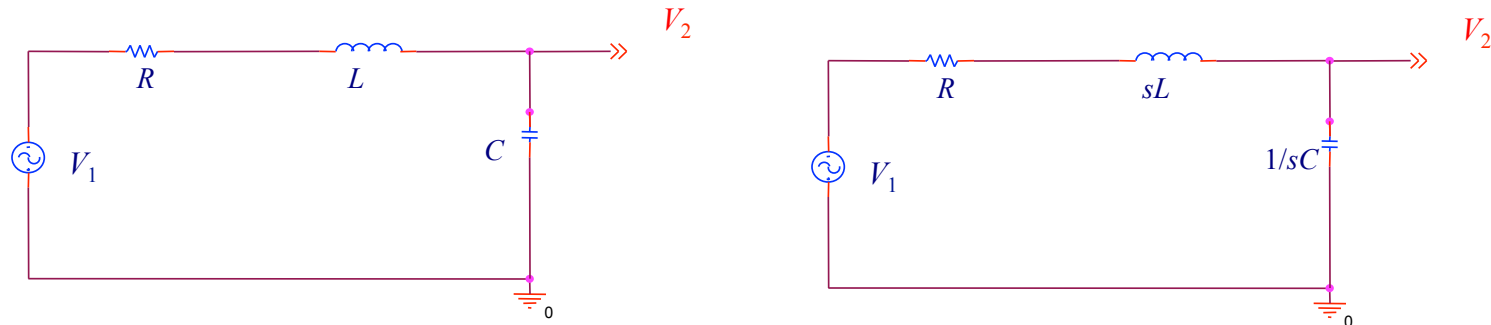
$$I(s) = \frac{V/sL}{s + R/L} = \frac{V/L}{s(s + R/L)}$$

$$I(s) = \frac{V/R}{s} - \frac{V/R}{(s + R/L)}$$



$$i(t) = \frac{V}{R} (1 - e^{-\frac{R}{L}t}) u(t)$$

# Replacing Circuit Element With Their LT Equivalents



Note based on the previous example, we can replace circuit elements with their LT equivalents

$$R \rightarrow R$$

$$L \rightarrow sL$$

$$C \rightarrow 1/(sC)$$

$$\frac{V_2(s)}{V_1(s)} = \frac{1/sC}{R + sL + 1/sC}$$

And we get, solving for  $V_2(s)/V_1(s)$

$$= \frac{1/LC}{s^2 + (R/L)s + 1/LC}$$

## Example Continued

Let's choose  $R=5$ ,  $L=1\text{h}$ ,  $C=1/6\text{f}$ , and let's solve for  $h(t)$ , [i.e.,  $v_1(t)=\delta(t)$ ] and then  $v_2(t)=u(t)$

$$H(s) = \frac{6}{s^2 + 5s + 6} = \frac{6}{(s+3)(s+2)}$$
$$= \frac{K_1}{s+3} + \frac{K_2}{s+2}$$

$$K_1 = \frac{6}{(s+2)} \Big|_{s=-3} = \frac{6}{(-3+2)} = -6$$

$$K_2 = \frac{6}{(s+3)} \Big|_{s=-2} = \frac{6}{(-2+3)} = 6$$

$$h(t) = 6[e^{-2t} - e^{-3t}]u(t)$$

$$V_2(s) = \frac{6}{s^2 + 5s + 6} V_1(s) = \frac{6}{s(s+3)(s+2)}$$
$$= \frac{K_1}{s+3} + \frac{K_2}{s+2} + \frac{K_3}{s}$$

$$K_1 = \frac{6}{s(s+2)} \Big|_{s=-3} = \frac{6}{(-3)(-3+2)} = 2$$

$$K_2 = \frac{6}{s(s+3)} \Big|_{s=-2} = \frac{6}{(-2)(-2+3)} = -3$$

$$K_3 = \frac{6}{(s+2)(s+3)} \Big|_{s=0} = \frac{6}{(2)(3)} = 1$$

$$v_2(t) = [1 + 2e^{-3t} - 3e^{-2t}]u(t)$$

## *Poles of the Response*

$$\frac{V_2(s)}{V_1(s)} = \frac{B(s)}{A(s)}$$

$$V_2(s) = \frac{B(s)}{A(s)} V_1(s) = \frac{B(s)}{A(s)} \frac{V_1^N(s)}{V_1^D(s)}$$

The poles of  $H(s) = B(s) / A(s)$  (zeros of  $A(s)$ ) are associated with the solutions to the source free response.

The poles of  $V_1(s)$  (zeros of  $V_1^D(s)$ ) are associated with the solutions to the source response.

# *Homework*

- Problems: 3.3,

A LTI system is described as

$$H(s) = 5.263 \frac{s + 1.9}{(s + 10)(s + 1)}$$

Find the impulse response :  $h(t)$

Draw the Bode plot for  $0.01 \leq f \leq 100$ cycles/min

- 3.4b,

The unit impulse response is given as

$$h(t) = (0.7e^{-5t} + 0.2e^{-t} + 0.1e^{-0.1t})u(t)$$

Find the response due to a unit step function.

# *Homework*

- Problems: 3.12c

A LTI system is described as

$$\dot{y} + 3y = x(t)$$

Find the response due to  $(1 + 2e^{-t})u(t)$

- 3.13c

A LTI system is described as

$$\ddot{y} + 8\dot{y} + 15y = 5x(t)$$

Find the response due to a unit step :  $x(t) = u(t)$

# *Homework*

- Problems: 3.18a&c

A LTI system is described as

$$Y(s) = \frac{2}{s(s^2 + 3s + 2)}$$

Find the poles of the system

Find  $y(t)$

- 3.23

A LTI system is described as

$$H(s) = \frac{10}{(s + 4)(s + 2)^3}$$

Find  $h(t)$



## *Homework*

- Find the inverse transforms for:

$$(a) \frac{1 - e^{-3s}}{s(s+2)}; (b) \frac{-s^2 + 9s + 10}{s(s+2)(s+5)}$$

$$(c) \frac{90s - 800}{(s^2 + 100)(s + 4)}; (d) \frac{s + 2}{[(s + 1)^2 + 1]^2}$$

$$(e) \frac{s^3 + 8s^2 + 18s + 12}{(s^2 + 2s + 2)(s^2 + 6s + 10)}; (f) \frac{s^2 + 4s + 3}{(s + 2)(s + 4)}$$