Lecture Problem-Solving Friction and Centripe (HR&W, Chapters http://web.njit.edu/~ Physics 105; Summ	7 Factics: etal Motion 5-6) sirenko/ her 2006	Newton's Laws 1. If no net force acts on a body, then the body's velocity cannot change. 2. The net force on a body is equal to the product of the body's mass and acceleration. 3. When two bodies interact, the force on the bodies from each other are always equal in magnitude and opposite in direction $(\mathbf{F}_{12} = -\mathbf{F}_{21})$. Force is a vector Force has direction and magnitude Mass connects Force and acceleration: $\vec{F}_{tot} = 0 \Leftrightarrow \vec{T} = 0$ (constant velocity) $\vec{F}_{tot} = m\vec{T}$ for any object $\vec{F}_{tot,x} = ma_x$ $\vec{F}_{tot,y} = ma_y$ $\vec{F}_{tot,z} = ma_z$ $\vec{F}_{tot,z} = ma_z$
<u>How do we jump ?</u>		Forces:
A standing person	jumping person	\rightarrow Gravitational Force: $\mathbf{F}_{g} = \mathbf{mg}$ down to the ground
$ \begin{array}{ccc} & \text{No acceleration} \\ & \overrightarrow{N} & \Rightarrow \\ & & \text{Net force is zero} \\ \end{array} $	Acceleration \Rightarrow $F_{NET} = ma$	>Tension Force: T along the string >Spring Force: $F_s = -kx$ >Normal Force: N perpendicular to the support >Friction Force V > Static: maximum value $f_s = u_s N_s$
$\mathbf{m}\mathbf{g}$ $\mathbf{F}_{\mathrm{NET}} = \mathbf{N} - \mathbf{m}\mathbf{g} = 0$	\vec{ng} N -mg=ma > 0	> Static; maximum value $\mathbf{f}_s = \mu_{st} \mathbf{N}$ opposite to the component of other forces parallel to the support > Kinetic; value $\mathbf{f}_k = \mu_{kin} \mathbf{N}$ opposite to the velocity, parallel to the support $\mu_{st} > \mu_{kin}$
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Inertial Frame; There are no Pseudo Forces: $T \cos \theta = mg$ $T \sin \theta = ma$ a =g·tan θ Non-inertial Frame Inertial Frame а Pseudo Forces θ а Lecture 7a Andrei Sirenko, NJIT 9 Lecture 7a Andrei Sirenko, NJIT 10

Non-Inertial Frame; There is a Pseudo Force: ma Newton's Laws do not work !!!



<u>Combination of Forces:</u> Net Force Dealing with Multiple Forces













