

Department of Electrical and Computer Engineering
ECE 673 - Random Signal Analysis I

Reading

Shanmugan & Breipohl, Chapter 6.1, 6.2.

Homework 8

1. Problem 6.1

Given $P(H_0) = 1/2$ (i.e. $P(H_1) = 1/2$ also) and

$$\begin{aligned} f_{Y|H_0}(y|H_0) &= 1, \quad 0 \leq y \leq 1 \\ f_{Y|H_1}(y|H_1) &= 2y, \quad 0 \leq y \leq 1 \end{aligned}$$

a. The MAP decision rule is

$$\begin{aligned} \Pr[H_0|y] &\underset{H_1}{\overset{H_0}{\gtrless}} \Pr[H_1|y] \\ f_{Y|H_0}(y|H_0) \Pr[H_0] &\underset{H_1}{\overset{H_0}{\gtrless}} f_{Y|H_1}(y|H_1) \Pr[H_1] \\ \frac{f_{Y|H_0}(y|H_0)}{f_{Y|H_1}(y|H_1)} &\underset{H_1}{\overset{H_0}{\gtrless}} \frac{\Pr[H_1]}{\Pr[H_0]} \\ \frac{1}{2y} &\underset{H_1}{\overset{H_0}{\gtrless}} 1 \\ \frac{1}{2} &\underset{H_1}{\overset{H_0}{\gtrless}} y \end{aligned}$$

b. The average probability of error is

$$\begin{aligned} \Pr(D_1|H_0) &= \Pr(y \geq \frac{1}{2}|H_0) = \int_{\frac{1}{2}}^1 f_{Y|H_0}(y|H_0) dy = \int_{\frac{1}{2}}^1 1 dy = \frac{1}{2} \\ \Pr(D_0|H_1) &= \Pr(y \leq \frac{1}{2}|H_1) = \int_0^{\frac{1}{2}} f_{Y|H_1}(y|H_1) dy = \int_0^{\frac{1}{2}} 2y dy = \frac{1}{4} \\ P_e &= \Pr(H_0) \Pr(D_1|H_0) + \Pr(H_1) \Pr(D_0|H_1) = \left(\frac{1}{2}\right) \left(\frac{1}{2}\right) + \left(\frac{1}{2}\right) \left(\frac{1}{4}\right) = \frac{3}{8} \end{aligned}$$

2. **Problem 6.2**

A coin is tossed 8 times to decide if the coin is fair or not. The two hypotheses are

$$\begin{aligned} H_0 : & \quad \text{Fair coin, } \Pr[\text{head}] = 0.5 \\ H_1 : & \quad \text{Unfair coin, } \Pr[\text{head}] = 0.4 \end{aligned}$$

Therefore, the conditional pmfs are

$$\begin{aligned} p(n|H_0) \sim \text{Binomial}(8, 0.5) &= \binom{8}{n} 0.5^n (1 - 0.5)^{8-n} = \frac{8!}{n!(8-n)!} 0.5^8 \\ p(n|H_1) \sim \text{Binomial}(8, 0.4) &= \binom{8}{n} 0.4^n (1 - 0.4)^{8-n} = \frac{8!}{n!(8-n)!} 0.4^n 0.6^{8-n} \end{aligned}$$

a. Assumeing $\Pr(H_0) = 0.5$ (i.e. $\Pr(H_1) = 0.5$ also), the MAP decision rule is

$$\begin{aligned} \Pr[H_0|n] &\underset{H_1}{\overset{H_0}{\gtrless}} \Pr[H_1|n] \\ p(n|H_0) \Pr[H_0] &\underset{H_1}{\overset{H_0}{\gtrless}} p(n|H_1) \Pr[H_1] \\ \frac{p(n|H_0)}{p(n|H_1)} &\underset{H_1}{\overset{H_0}{\gtrless}} \frac{\Pr[H_1]}{\Pr[H_0]} \\ \frac{0.5^8}{0.4^n 0.6^{8-n}} &\underset{H_1}{\overset{H_0}{\gtrless}} 1 \\ \left(\frac{0.5}{0.6}\right)^8 &\underset{H_1}{\overset{H_0}{\gtrless}} \left(\frac{0.4}{0.6}\right)^n \quad \text{i.e. } n > 3 \text{ choose } H_0, n \leq 3 \text{ choose } H_1. \end{aligned}$$

b.

$$\begin{aligned} \Pr(D_1|H_0) &= \Pr(n \leq 3|H_0) = \sum_{n=0}^3 p(n|H_0) = \sum_{n=0}^3 \frac{8!}{n!(8-n)!} 0.5^8 = 0.3633 \\ \Pr(D_0|H_1) &= \Pr(n > 3|H_1) = \sum_{n=4}^8 p(n|H_1) = \sum_{n=4}^8 \frac{8!}{n!(8-n)!} 0.4^n 0.6^{8-n} = 0.4079 \\ P_e &= \Pr(H_0) \Pr(D_1|H_0) + \Pr(H_1) \Pr(D_0|H_1) \\ &= (0.5)(0.3633) + (0.5)(0.4079) = 0.3846 \end{aligned}$$

3. **Problem 6.3**

Given $\Pr(H_0) = 0.999$ (i.e. $\Pr(H_1) = 0.001$) and

$$\begin{aligned} f_{Y|H_0}(y|H_0) &= \frac{y}{N_0} \exp\left(-\frac{y^2}{2N_0}\right), \quad y > 0 \\ f_{Y|H_1}(y|H_1) &\approx \sqrt{\frac{y}{2\pi AN_0}} \exp\left[-\frac{(y-A)^2}{2N_0}\right], \quad y > 0 \end{aligned}$$

The MAP decision rule is

$$\begin{aligned}
 \Pr[H_0|y] & \underset{H_1}{\overset{H_0}{\gtrsim}} \Pr[H_1|y] \\
 f_{Y|H_0}(y|H_0) \Pr[H_0] & \underset{H_1}{\overset{H_0}{\gtrsim}} f_{Y|H_1}(y|H_1) \Pr[H_1] \\
 \frac{f_{Y|H_0}(y|H_0)}{f_{Y|H_1}(y|H_1)} & \underset{H_1}{\overset{H_0}{\gtrsim}} \frac{\Pr[H_1]}{\Pr[H_0]} \\
 \frac{\frac{y}{N_0} \exp\left(-\frac{y^2}{2N_0}\right)}{\sqrt{\frac{y}{2\pi AN_0}} \exp\left[-\frac{(y-A)^2}{2N_0}\right]} & \underset{H_1}{\overset{H_0}{\gtrsim}} \frac{0.001}{0.999} \\
 \sqrt{\frac{2\pi Ay}{N_0}} \exp\left(\frac{A^2 - 2Ay}{2N_0}\right) & \underset{H_1}{\overset{H_0}{\gtrsim}} \frac{1}{999}
 \end{aligned}$$

4. Problem 6.5

The noise N is $\mathcal{N}(0, 1/9)$, which means

$$f_N(n) = \frac{3}{\sqrt{2\pi}} \exp\left(-\frac{9n^2}{2}\right).$$

Given $\Pr(H_0) = \Pr(H_1) = 1/2$ and

$$\begin{aligned}
 H_0 : & \quad Y = N \\
 H_1 : & \quad Y = 2 + N
 \end{aligned}$$

we have

$$\begin{aligned}
 f_{Y|H_0}(y|H_0) &= \frac{3}{\sqrt{2\pi}} \exp\left(-\frac{9n^2}{2}\right), \\
 f_{Y|H_1}(y|H_1) &= \frac{3}{\sqrt{2\pi}} \exp\left(-\frac{9(n-2)^2}{2}\right)
 \end{aligned}$$

a. The MAP decision rule is

$$\begin{aligned}
 \Pr[H_0|y] & \underset{H_1}{\overset{H_0}{\gtrsim}} \Pr[H_1|y] \\
 f_{Y|H_0}(y|H_0) \Pr[H_0] & \underset{H_1}{\overset{H_0}{\gtrsim}} f_{Y|H_1}(y|H_1) \Pr[H_1] \\
 \frac{f_{Y|H_0}(y|H_0)}{f_{Y|H_1}(y|H_1)} & \underset{H_1}{\overset{H_0}{\gtrsim}} \frac{\Pr[H_1]}{\Pr[H_0]} \\
 \frac{\frac{3}{\sqrt{2\pi}} \exp\left(-\frac{9n^2}{2}\right)}{\frac{3}{\sqrt{2\pi}} \exp\left(-\frac{9(n-2)^2}{2}\right)} & \underset{H_1}{\overset{H_0}{\gtrsim}} 1 \\
 1 & \underset{H_1}{\overset{H_0}{\gtrsim}} y
 \end{aligned}$$

b. The average probability of error is

$$\Pr(D_1|H_0) = \Pr(y \geq 1|H_0) = \int_1^{\infty} f_{Y|H_0}(y|H_0)dy = Q\left(\frac{|0-1|}{1/3}\right) = Q(3)$$

$$\Pr(D_0|H_1) = \Pr(y < 1|H_1) = \int_{-\infty}^1 f_{Y|H_1}(y|H_1)dy = Q\left(\frac{|2-1|}{1/3}\right) = Q(3)$$

$$P_e = \Pr(H_0)\Pr(D_1|H_0) + \Pr(H_1)\Pr(D_0|H_1) = \left(\frac{1}{2}\right)Q(3) + \left(\frac{1}{2}\right)Q(3) = Q(3)$$