

1 **Functional electrical therapy: Retraining**
2 **grasping in spinal cord injury**

3
4 **Milos R. Popovic^{1,2}, T. Adam Thrasher^{1,2}, Marlene E.**
5 **Adams², Veronica Takes², Vera Zivanovic² and**
6 **Mark I. Tonack²**

7
8 ¹ Institute of Biomaterials and Biomedical Engineering, University of
9 Toronto, Canada

10 ² Lyndhurst Centre, Toronto Rehabilitation Institute, Canada

11
12 ***Corresponding Author:***

13 Dr. T. Adam Thrasher

14 Rehabilitation Engineering Laboratory

15 Toronto Rehabilitation Institute

16 520 Sutherland Drive

17 Toronto, Ontario

18 M4G 3V9, Canada

19 Phone: +1-416-597-3422 ext. 6304

20 Fax: +1-416-425-9923

1 E-mail: adam.thrasher@utoronto.ca

2 Web site: www.toronto-fes.ca

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ABSTRACT

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3 **Objective:** To determine the clinical efficacy of functional electrical
4 therapy in the rehabilitation of grasping function for quadriplegics.

5 **Study design:** Randomized intervention-versus-control trial.

6 **Setting:** Rehabilitation hospital for spinal cord injury in Toronto, Canada.

7 **Methods:** 21 people with new spinal cord injuries ranging from C3 to C7
8 were randomly assigned to two groups: Control (N=9) and Intervention
9 (N=12). The intervention was functional electrical therapy, which consisted
10 of repetitive grasping exercises using a neuroprosthesis that applied surface
11 electrical stimulation to the arm to generate and/or assist grasping
12 movements. It was applied by registered Occupational Therapists in a
13 clinical setting. Main outcome measures were: Functional Independence
14 Measure (FIM), Spinal Cord Independence Measure (SCIM), and the
15 Rehabilitation Engineering Laboratory Hand Function Test. Consumer
16 perceptions of functional electrical therapy were assessed via qualitative
17 interviews.

18 **Results:** Differences between the Control and Intervention groups could be
19 observed although they are not significant due to an insufficient number of
20 participants. Consumer perceptions were positive, including improved
21 Activities of Daily Living and self-satisfaction.

1 **Conclusion:** Functional electrical therapy has the potential to be an
2 effective treatment modality to restore grasping function in quadriplegia. It
3 can be implemented by occupational therapists in a clinical setting. Further
4 research is required to establish suitable indications for participant selection.
5 In addition, a larger number of participants is needed to demonstrate
6 statistical significance of the Functional Electrical Therapy.

7

8 **Key Words:** Neuroprosthesis, functional electrical stimulation, functional
9 electrical therapy, spinal cord injury, quadriplegia, grasping and hand
10 functions

11

12 **INTRODUCTION**

13

14 In recent decades, a number of Functional Electrical Stimulation (FES)
15 devices have been developed to assist people with severe motor paralysis to
16 improve grasping function¹. Some neuroprostheses for grasping have been
17 successfully commercialized, and are intended for everyday use^{2,3}. The
18 available neuroprostheses for grasping are able to restore two useful styles
19 of grasping: the palmar and the lateral grasp. Palmar grasp is used to hold
20 larger and heavier objects such as cans and bottles between the palm of the
21 hand and the four fingers. Lateral grasp is used to hold smaller and thinner
22 objects such as keys, paper, and compact discs between the thumb and

1 forefinger. Lateral grasp is generated by flexing the fingers to provide
2 opposition followed by thumb flexion. Palmar grasp is generated by forming
3 the opposition between the thumb and the palm, followed by simultaneous
4 flexion of both the thumb and the fingers.

5 It has been reported that many patients who use FES on a regular
6 basis experience significant carry-over in function that persists even when
7 the device is not in use⁴⁻⁷. A neurological mechanism for such changes has
8 been hypothesized⁸. Now, the potential role of neuroprostheses as
9 therapeutic interventions in clinical practice is beginning to be realized.
10 Applications of FES that attempt to harness this therapeutic effect have been
11 dubbed Functional Electrical Therapy (FET)⁹. The basic FET approach is to
12 regularly use a neuroprosthesis to facilitate functional exercises in a clinical
13 environment for a period of several weeks. The goal is increased function,
14 with a concomitant increase in independence and quality of life.

15 Neuroprostheses for grasping have been successfully implemented in
16 rehabilitation programs for severe hemiplegia¹⁰ and acute quadriplegia¹¹. To
17 date, all studies on the application of FET to the Spinal Cord Injury (SCI)
18 population have been case series conducted without a control group. The
19 present study represents the first randomized intervention-versus-control
20 design to be applied to FET in SCI, which is necessary to establish the
21 efficacy of FET as an intervention compared to conventional physiotherapy
22 and occupational therapy techniques.

1

2

METHODS

3

4 The study presented herein describes a randomized intervention-versus-
5 control trial. The method for analyzing data was specified in the protocol
6 before the study begun. The study received ethical approvals from the
7 University of Toronto and the Toronto Rehabilitation Institute ethics boards.
8 The patients were invited to participate in the study and they gave consent
9 before the inclusion/exclusion criteria were applied. After the participants
10 were admitted to the program and baseline assessments were made, they
11 were randomly assigned to control and intervention groups. A flow chart
12 indicating the order of recruitment, therapies, and assessments that were
13 applied to all participants is shown in Figure 1.

14 So far, a total of 21 participants with SCI at most 8-months post-
15 injury at the time of recruitment have completed the study. Demographic
16 and neurological data for all participants are given in Table 1. Participants
17 were recruited from the in-patient population at the SCI unit at the Toronto
18 Rehabilitation Institute. Participants included both motor complete (ASIA A
19 and B) and incomplete (ASIA C and D) SCI.

20 After they were admitted to the program, the participants were
21 *randomly assigned* to two groups: *Control group*, which was administered
22 only conventional physiotherapy and occupational therapy; and *Intervention*

1 *group*, which was administered FET in addition to conventional
2 physiotherapy and occupational therapy.

3 Participants were randomized using two sets of sealed envelopes. An
4 eligible participant first selected from an unmarked set of 40 envelopes.
5 Each unmarked envelope contained a single sheet of paper with a printed
6 number in the range of 1 to 40. In the second set of envelopes, which were
7 marked with numbers from 1 to 40, single sheets of paper indicating either
8 “control” or “intervention” were sealed. Thus, twenty randomly selected
9 numbers in the range of 1 to 40 were assigned to the Control group, and the
10 remaining 20 numbers were assigned to the Intervention group.
11 Randomization of the numbers was done using the *randperm* function in
12 Matlab (The Mathworks Inc., Natick, MA) seeded with an arbitrary clock
13 value. After the participant selected a random number from the set of
14 unmarked envelopes, the corresponding marked envelope was opened
15 revealing the group to which the participant was assigned. Opened
16 envelopes were destroyed immediately. This method ensured that the
17 randomization process could not be contaminated.

18 Both Control and Intervention groups were administered their
19 respective therapies for 12 weeks, five days per week, one session per day
20 and 45 minutes per session.

21

22 **Conventional Therapy**

1 The control group received conventional occupational therapy pertaining to
2 hand function. The conventional occupational therapy included: muscle
3 facilitation exercises emphasizing the normal movement treatment
4 approach; task-specific, repetitive functional training; strengthening and
5 motor control training using resistance to available arm motion to increase
6 strength; stretching exercises; electrical stimulation applied primarily for
7 muscle strengthening (this is not FES or FET); training in activities of daily
8 living including self-care involving compensatory upper extremity
9 movements as appropriate; and caregiver training.

10

11 **Functional Electrical Therapy**

12

13 **Hardware**

14 The Compex Motion electric stimulator was used as a hardware platform for
15 the neuroprosthesis for reaching and grasping¹².

16

17 **Treatment Protocol**

18 The intervention group received both conventional occupational therapy and
19 FET pertaining to hand function. Ethical concerns prohibit the evaluation of
20 FET without conventional occupational therapy.

21

1 ***Pre-FET Muscle Strengthening***

2 Due to the quadriplegia, many people with SCI are unable to voluntarily
3 contract or control some upper extremity muscles. This lack of muscle use
4 causes significant changes in the physiology of inactive muscles. Typically
5 with time, muscle strength decreases and the fiber ratio changes towards fast
6 fiber predominance. This process occurs relatively quickly, resulting in a
7 significant loss of original muscle strength only weeks after the onset of
8 injury. The longer that these muscles remain inactive, the more severe is the
9 muscle strength deterioration. Therefore, before the start of the functional
10 training, and when required, the patient participated in a muscle-
11 strengthening program.

12 The muscle-strengthening program is standard practice in our
13 laboratory. It is used to stop and reverse muscle atrophy by actively
14 exercising muscles via electrical stimulation. It consisted of five phases and
15 was carried out with standard surface stimulation technology. Self-adhesive
16 surface stimulation electrodes were placed on the participant's arm above
17 the muscles/nerves that were stimulated, as shown in Figure 2. The
18 following muscles/nerves were stimulated: *flexor digitorum superficialis m.*
19 and the *flexor digitorum profundus m.* (finger flexion); *median nerve* or
20 *thenar m.*, and *flexor pollicis longus m.* (thumb opposition and flexion);
21 *extensor digitorum m.* (finger extension); *flexor carpi radialis m.* and *flexor*
22 *carpi ulnaris m.* (wrist flexion); *extensor carpi radialis longus* and *brevis*

1 *m.*, and *extensor carpi ulnaris m.* (wrist extension). The stimulation
2 parameters used on these muscles/nerves were: 1) balanced, biphasic,
3 current regulated electrical pulses; 2) pulse amplitude from 8 to 50 mA
4 (typical values 17-26mA); 3) pulse width 250 μ s; and 4) pulse frequency
5 from 20 to 70 Hz (typical value 40 Hz).

6 It is important to mention that prior to the muscle-strengthening
7 program, the participant was assessed to determine which muscles could be
8 stimulated using surface FES technology and which combination of muscle
9 contractions generated the palmar and/or the lateral grasp. The muscles that
10 could generate one or both grasps were stimulated during the muscle-
11 strengthening program. Other muscles in the forearm and hand were not
12 trained during the muscle-strengthening program. The necessity for each of
13 the muscle strengthening phases was determined by manual testing of the
14 corresponding grasp or release strength. Participants were considered to
15 have sufficient strength to advance to the next phase if they were able to
16 grasp/release a small cylindrical object against manual resistance applied to
17 the object by the therapist (approximately 0.5 to 1.0 Nm torque).

18

19

20 Phases of the muscles strengthening program:

21

1 **PHASE 1:** 15 minutes of 10 s full muscle contraction (pulse
2 characteristics: balanced, biphasic, current regulated electrical pulses;
3 amplitude from 8 to 50 mA; pulse width 250 μ s; and pulse frequency 40 Hz)
4 followed by 10 s of muscle relaxation (pulse characteristics: balanced
5 biphasic current regulated electrical pulses; amplitude $\frac{1}{2}$ of the amplitude
6 used during full muscle stimulation; pulse width 250 μ s; and pulse
7 frequency 1 Hz). This stimulation protocol was carried out until the
8 stimulated muscle generated solid tetanic contractions against manual
9 resistance during all “full muscle stimulation” phases.

10 **PHASE 2:** 15 minutes of 30 s full muscle contraction (same pulse
11 parameters as in Phase 1) followed by 30 s of muscle relaxation (same pulse
12 parameters as in Phase 1). This stimulation protocol was carried out until the
13 stimulated muscle generated solid tetanic contractions against manual
14 resistance during all “full muscle stimulation” phases.

15 **PHASE 3:** 15 minutes of 60 s full muscle contraction (same pulse
16 parameters as in Phase 1) followed by 60 s of muscle relaxation (same pulse
17 parameters as in Phase 1). This stimulation protocol was carried out until the
18 stimulated muscle generated solid tetanic contractions against manual
19 resistance during all “full muscle stimulation” phases.

20 **PHASE 4:** 15 minutes of 120 s full muscle contraction (same pulse
21 parameters as in Phase 1 except for frequency, it was reduced to 20-25 Hz)
22 followed by 60 s of muscles relaxation (same pulse parameters as in Phase

1) This stimulation protocol was carried out until the stimulated muscle generated solid tetanic contractions against manual resistance during all “full muscle stimulation” phases.

PHASE 5: 15 minutes of 180 s full muscle contraction (same pulse parameters as in Phase 4) followed by 60 s of muscle relaxation (same pulse parameters as in Phase 4). This stimulation protocol was carried out until the stimulated muscle generated solid tetanic contractions against manual resistance during all “full muscle stimulation” phases.

FET-Functional Training Intervention

FET was applied and supervised by two registered occupational therapists. Each participant in the Intervention group was asked to execute a one-handed task (e.g. reaching and grasping a pen). The participant would first try to execute the task unassisted. The components/sequences of the task that the participant was unable to carry out him/herself had to be assisted by the neuroprosthesis. Hence, the functional training for the Intervention group began by designing a stimulation protocol that could assist or generate the palmar and/or the lateral grasp on demand. In other words, the stimulation sequence (protocol) was developed for each participant individually using a Compex Motion stimulator that allowed the participant, who otherwise could not grasp, to do so with the FES system. No splinting

1 was used during the application of FET. The electrodes were placed with
2 great care to produce only the desired movements. Therefore, it was not
3 necessary to block wrist flexion or extension.

4 The command for activating the stimulation sequence was issued
5 with a push button. By pressing a push button the participant commanded
6 hand opening and closing, and also select the type of grasp to be executed¹².
7 Stimulation parameters that were used in these trials were: 1) balanced,
8 biphasic, current regulated electrical pulses; 2) pulse amplitude from 8 to
9 50 mA (typical values 17-26 mA); 3) pulse width 250 μ s; and 4) pulse
10 frequency from 20 to 70 Hz (typical value 40 Hz). Once the individualized
11 neuroprosthesis for grasping was developed for a participant, he/she was
12 trained with the systems to perform grasping and releasing of everyday
13 objects, such as a soft drink can, pencil, credit-card, etc. The participant
14 was asked to repeat the same hand task 30 to 50 times during a 45-minute
15 treatment session. During the intervention, the occupational therapist
16 adjusted the placement of electrodes and guided the hand movements. The
17 occupational therapist ensured that all movements were functional, efficient
18 and used normal movement patterns. An independent hand strengthening
19 and stretching program was provided as needed to facilitate normal hand
20 function.

21 The first signs of functional recovery were observed four to six
22 weeks after the onset of the FET program. As soon as the participant

1 showed signs of recovery of either the voluntary extension or flexion in a
2 stimulated muscle group, he/she was encouraged to make an effort to
3 produce the movement voluntarily, which was previously facilitated by the
4 FET. As the participant showed improved strength and range of motion, the
5 FET for that muscle group was phased out and moved to another muscle
6 group that was still paralyzed and needed to be “reactivated”. The order in
7 which muscle groups were sequentially “reactivated” was patient dependent.

8

9 **Outcome Measures**

10 **Functional/Independence Tests**

11 The following tests were administered to all participants in the study before
12 and after the intervention (both Control and Intervention groups). All tests
13 were performed *without* stimulation.

- 14 1. Functional Independence Measure (FIM) – total score¹³.
- 15 2. Spinal Cord Independence Measure (SCIM) – total score¹⁴.
- 16 3. Rehabilitation Engineering Laboratory Hand Function Test (REL
17 test) of each arm – total score¹⁰. This test was developed to
18 evaluate improvements in the gross motor function of the unilateral
19 grasp due to neuroprosthesis for grasping treatment. The REL test
20 was the only nonstandard test applied in this study. In summary,
21 the hand functions that were tested with the REL test are: *lateral or*

- 1 *pulp pinch*, and *palmar* grasps. This test consists of five
2 components:
- 3 i. Objects – An ordinal scale representing the lifting of several
4 ordinary objects using different hand positions (0 to 56).
 - 5 ii. Blocks – An ordinal scale representing the lifting of wooden
6 blocks with varying degrees of slipperiness and weight (0 to
7 18).
 - 8 iii. Cylinder – A numerical measurement of the maximum torque
9 generated by a palmar grip on a 3 cm diameter cylinder.
 - 10 iv. Credit card – A numerical measurement of the maximum
11 force resisted by a pinch grasp on a credit card.
 - 12 v. Wooden bar – A numerical measurement of the eccentric
13 load that can be held in a pronated palmar grip, measured
14 using an axe handle of approximately 3 cm diameter and 50
15 cm length.

16

17 **Scoring:** With exception to the *instrumented cylinder*, *credit card*
18 *attached to a dynamometer* and *wooden bar*, all test objects were
19 placed on a desk 20 to 30 cm in front of the participant, one after
20 another. The participant was requested to pick up the objects, lift
21 them in front of his/her chest and move the objects from supination, to
22 neutral and then to pronation position. In each position, the

1 participant was told to hold the object for 20 to 30 s. If the participant
2 was unable to hold the object in any of these three positions, then
3 he/she received 0 points for that position. The participant received 1
4 point if they could hold the object for a short period of time (2 to 10 s)
5 and then eventually drop it. Finally, participants received 2 points if
6 he/she was able to hold the object for 20 to 30 s in the intended hand
7 position. The *instrumented cylinder*, *credit card attached to a*
8 *dynamometer* and *wooden bar* were used to measure torque generated
9 by the palmar grasp, force produced by the pinch grasp, and
10 exocentric load that the palmar grasp can sustain, respectively.

11

12 **Statistical Analysis**

13 Changes in the outcome measures were tested for statistical significance
14 using a Wilcoxon rank-sum test, which is non-parametric and robust to non-
15 normal distributions of data. Participants with motor complete SCI were
16 analyzed separately from participants with motor incomplete SCI. The
17 allotment to these two groups was based on admission diagnosis and the
18 physician's clinical observations.

19

20 **Consumer Perceptions**

21 All participants in the Intervention group attended a face-to-face interview
22 session. Interviews were carried out two weeks after completing

1 intervention and prior to permanent discharge from in-patient rehabilitation
2 services. The purpose of the interviews was to provide an opportunity for
3 participants to describe their experiences and perceptions of using the
4 neuroprosthesis. Specific attention was directed toward documenting both
5 positive and negative attributes of the intervention as well as determining
6 how participants perceived impact on their quality of life. Interviews lasted
7 from 30 to 60 minutes; all discussions were recorded on audiocassettes.
8 General, open-ended questions were supported by prompts and follow-up
9 questions.

10 In a qualitative research approach the data analysis proceeds in
11 parallel with the data collection. This analytical process is based on well-
12 established procedures in the social sciences¹⁵⁻¹⁷. Based on the method of
13 inductive analysis, the interview tapes were systematically scrutinized and
14 emergent themes and sub-themes were identified. Once thematic saturation
15 was accomplished, data analysis was terminated. A trained qualitative
16 researcher, a staff research scientist that was not involved in any other
17 aspect of the study, conducted this data collection and analysis.

18

19

RESULTS

20

1 Improvements between baseline and post-treatment scores were seen in all
2 tests and groups with two exceptions: the credit card force test for
3 participants with incomplete SCI and the blocks test for participants with
4 complete SCI. The differences between mean scores obtained at baseline
5 and at the end of the intervention period for the individuals with complete
6 SCI are shown in Figure 3. Figure 4 shows the changes over the course of
7 treatment for the participants with incomplete SCI. As indicated by the error
8 bars, there was a great deal of variance between participants in most
9 measures. Due to the low number of subjects, no significant differences
10 were found between the Control and Intervention groups. Figures 5 and 6
11 show “Box and Whisker” plots of all quantitative outcome measures at
12 baseline and the end of treatment separated by group and type of injury
13 (complete and incomplete SCI). The data so far suggests that greater
14 improvements are seen in hand function when FET is added to the therapy
15 program.

16 The qualitative interviews revealed that all participants in the
17 Intervention group decided to enter the study because they wanted to see if
18 the treatment regime would affect their function in a positive manner. The
19 sub-themes identified are summarized in Table 2. Some just wanted the
20 opportunity to be involved in as much therapy as possible – regardless of the
21 type of therapy. All participants articulated advantages or outcomes that
22 they did not expect. All participants stated that the functional changes they

1 experienced were important, regardless of degree, because improvement
2 enhanced their personal independence. Respondents reported that the
3 success with FET motivated them to work harder in other facets of their
4 rehabilitation. In addition, they often described feeling a sense of self-
5 satisfaction and improved well-being. Participants did not identify any
6 negative aspects of using the neuroprosthesis. In fact, all individuals
7 indicated that they would prefer to continue to use the equipment because of
8 their positive experiences. However, participants did explain that there were
9 some negative aspects of testing for the correct location of the electrodes
10 and that initially there was some minimal pain, which one got used to
11 eventually. Most participants felt that donning and doffing the equipment
12 could be improved. All participants felt that FES interventions should be a
13 regular part of rehabilitation programs and further suggested that the
14 equipment should be available for outpatient and fitness programs.

15

16

DISCUSSION

17

18 We compared the outcomes of four groups of SCI individuals with upper
19 extremity paralysis or paresis. One group consisted of individuals with
20 complete SCI that received conventional occupational therapy, which is
21 commonly a part of their rehabilitation. The second group consisted of
22 individuals with complete SCI that were administered FET combined with

1 conventional occupational therapy. The third group consisted of individuals
2 with incomplete SCI that were administered conventional occupational
3 therapy. The fourth group was individuals with incomplete SCI that were
4 administered FET combined with conventional occupational therapy. These
5 preliminary results show that the subjects who were treated with the
6 neuroprosthesis for grasping showed overall better outcomes compared to
7 the controls, but the improvements are not statistically significant.

8 Our treatment protocol stresses the importance of applying a surface
9 FET intervention that can be tailored and adjusted to patients' needs on a
10 daily basis and can evolve as the patients improve their function.
11 Furthermore, our findings suggest that if a participant who attempts to
12 execute a grasping task is assisted with the FET to carry out that task, he/she
13 is effectively voluntarily generating the motor command (desire to move the
14 arm, i.e. *command input*). It is suggested that FET is providing the afferent
15 feedbacks (*system's output*), indicating that the command was executed
16 successfully. We hypothesize that by providing both the command input and
17 system's output to the central nervous system (CNS) repetitively for
18 prolonged periods of time, this type of treatment facilitates functional
19 reorganization and retraining of intact parts of the of CNS and allows them
20 to take over the function of the damaged part of the CNS⁸. It is important to
21 add that during the intervention the participants were performing grasping
22 tasks repetitively. We believe that diversity of meaningful tasks combined

1 with high repetition may play an important role in retraining grasping
2 functions.

3 The results presented in this article indicate that patients with SCI
4 show considerable improvements in FIM scores if they were trained with
5 FET compared to controls. This result is very different from the one we
6 have reported in the study where FET was applied to patients with severe
7 hemiplegia¹⁰. This finding can be easily explained because individuals with
8 SCI usually have bilateral disability, which is not the case with individuals
9 with hemiplegia. Individuals with hemiplegia, with time and intensive
10 therapy, learn how to reach and grasp objects using the healthy arm. Hence,
11 in these subjects, improving the function in the disabled arm does not
12 produce significant changes in FIM scores. However, in SCI individuals,
13 who typically have bilateral disability, even minute changes in the hand
14 function precipitate in measurable improvements in FIM and SCIM scores.
15 This clearly explains why participants who had FET therapy and have
16 improved hand function considerably have shown improvements in FIM and
17 SCIM scores. Therefore, these results suggest that FET applied to hand
18 function in SCI individuals has a potential to positively impact performance
19 in activities of daily living and to provide needed independence measured
20 by FIM and SCIM.

21 Another very important and unexpected finding is that individuals
22 with complete SCI appear to benefit relatively more from FET compared to

1 individuals with incomplete SCI. In other words, the relative changes in the
2 outcome measures are higher in individuals with complete SCI compared to
3 individuals with incomplete SCI. This finding suggests that individuals
4 with complete SCI who were unable to perform a function on their own
5 prior to the intervention were stimulated with the FET to improve the
6 function beyond what is achievable with conventional therapy. This
7 strengthens our hypothesis that by providing both the command input and
8 system's output to the CNS repetitively for prolonged periods of time, this
9 type of treatment facilitates functional reorganization and retraining of intact
10 parts of the of CNS and allows them to take over the function of the
11 damaged part of the CNS. Since individuals with complete SCI had no
12 means to generate the "output" signals for CNS, unlike some individuals
13 with incomplete SCI, the FET's assistance in generating these signals was
14 instrumental in achieving the desired functional recovery. These findings
15 also suggest that the change most likely was central (CNS) instead of
16 peripheral (muscle strengthening). This finding supports results obtained in
17 a similar study with severe stroke individuals¹⁰.

18 In closing, the results suggest that people with SCI can benefit
19 functionally from FET. We have also demonstrated that FET can be applied
20 practically and efficiently in a rehabilitation setting with suitable equipment
21 and training of therapists.

22

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2

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20

1 TABLE 1 – Participants' demographic and neurological data

Complete SCI Control Group –received conventional occupational therapy					
Subject	Sex	Age	Neurological level at baseline	Cause of injury*	Intervention start date in days after SCI
AABE	M	44	C6	Fall	243
AABO	M	49	C7	MVA	158
AABX	M	58	C5	Fall	41
AADA	M	24	C6	Fall	26
Incomplete SCI Control Group –received conventional occupational therapy					
Subject	Sex	Age	Neurological level at baseline	Cause of injury*	Intervention start date in days after SCI
AABN	M	51	C3	Fall	76
AABP	M	64	C3	MVA	15
AACX	M	56	C3	Fall	33
AADC	M	63	C4	Fall	41
AADH	M	70	C4	MVA	53
Complete SCI Intervention Group – received the neuroprosthesis (FET) intervention					
Subject	Sex	Age	Neurological level at baseline	Cause of injury*	Intervention start date in days after SCI
AAAO	M	25	C5	MVA	86
AAAR	M	20	C7	MVA	27
AAAY	M	26	C4	Bicycle	84
AABI	M	32	C6	MVA	31
AABS	M	40	C6	Diving	19
AABW	M	16	C5	Wrestling	28
Incomplete SCI Intervention Group – received the neuroprosthesis (FET) intervention					
Subject	Sex	Age	Neurological level at baseline	Cause of injury*	Intervention start date in days after SCI
AAAG	M	60	C5	Fall	142
AAAN	M	21	C6	MVA	64
AABD	M	65	C4	Fall	31
AABT	M	37	C6	Fall	15
AACC	M	21	C7	Diving	28
AACK	M	35	C6	Fall	27

2 * MVA – Motor Vehicle Accident

3

1

2 TABLE 2 – Consumer Perceptions: Summary of sub-themes identified from
3 qualitative interviews

Improvements/Positive Outcomes

- Increased flexibility
- Sense of enhanced strength hands and fingers
- Improved dexterity
- Reduced chronic pain
- Enhanced sense of well being
- Enhanced Motivation

Impact on Quality of Life

- Improved Activities of Daily Living – grasping objects, dressing, eating etc.
- Increased Independence
- Enhanced sense of well-being
- Improved Self Esteem

Disadvantages of Neuroprosthesis for Grasping

- None identified

4

5

1 **Figure Captions**

2

3 **Figure 1:** Flow chart of the recruitment, therapies, and assessments that
4 were applied to all participants.

5

6 **Figure 2:** Individualized placement of stimulation electrodes for: (a) thumb
7 and finger flexors; (b) finger extensors.

8

9 **Figure 3:** Increases in outcome measures for participants with complete
10 SCI: 1) REL Test – object manipulation; 2) REL Test – wooden blocks; 3)
11 REL Test – cylinder torque; 4) REL Test – credit card pulling force; 5) REL
12 Test – eccentric load on wooden bar; 6) FIM; and 7) SCIM tests. The black
13 bars represent the differences for the Control Group, and the shaded bars
14 represent the differences for the Intervention Group.

15

16 **Figure 4:** Increases in outcome measures for participants with incomplete
17 SCI.

18

19 **Figure 5:** Complete SCI participants' box-and-whisker plots of the scaled
20 data for REL Tests: object manipulation, wooden blocks, torques, forces,
21 and eccentric load; FIM; and SCIM tests: a) Control group scores before
22 treatment; b) Intervention group scores before treatment; c) Control group

1 scores after treatment; and d) Intervention group scores after treatment.

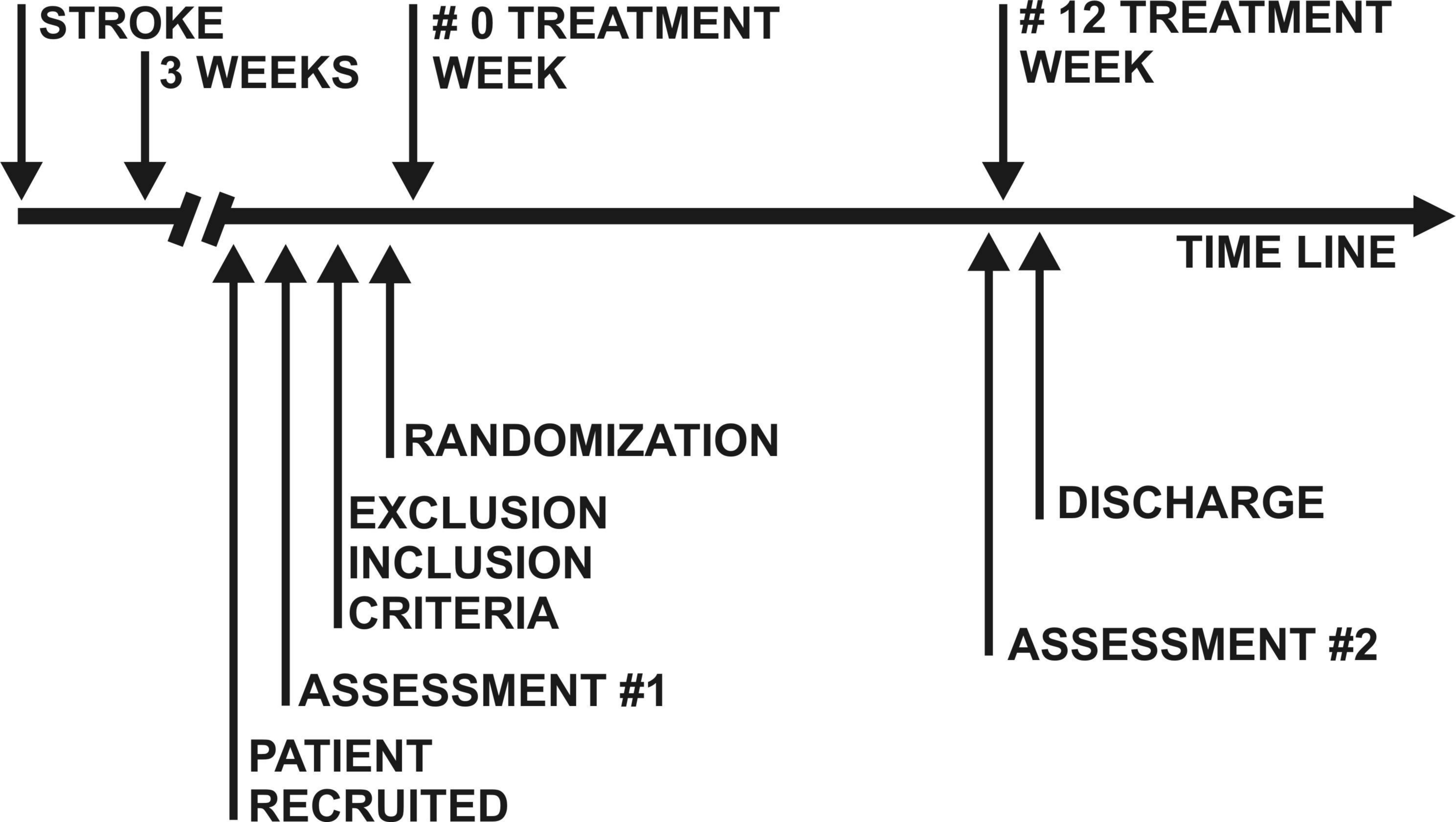
2 Bold horizontal lines represent medians.

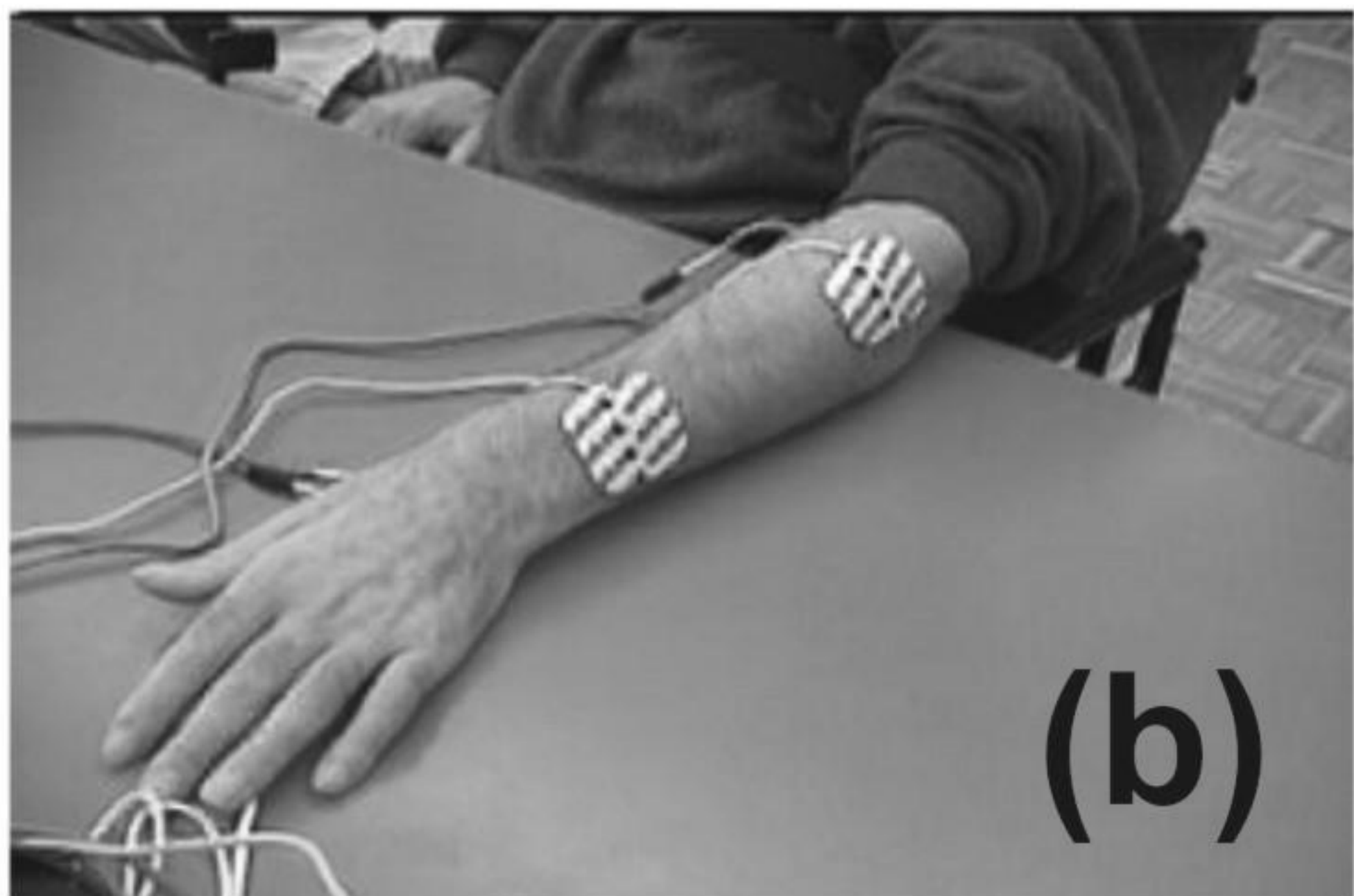
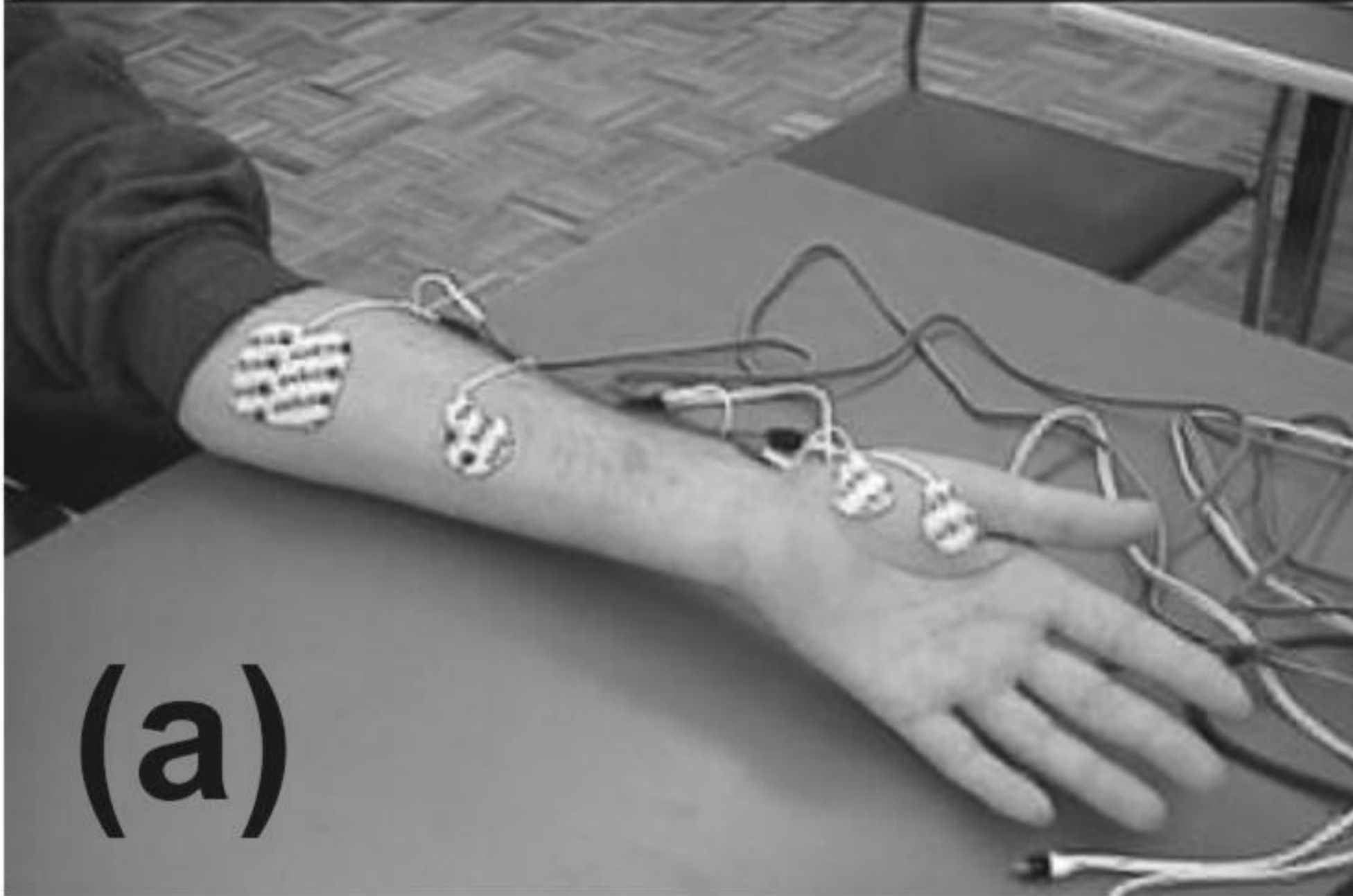
3

4 **Figure 6:** Incomplete SCI participants' box-and-whisker plots. Bold

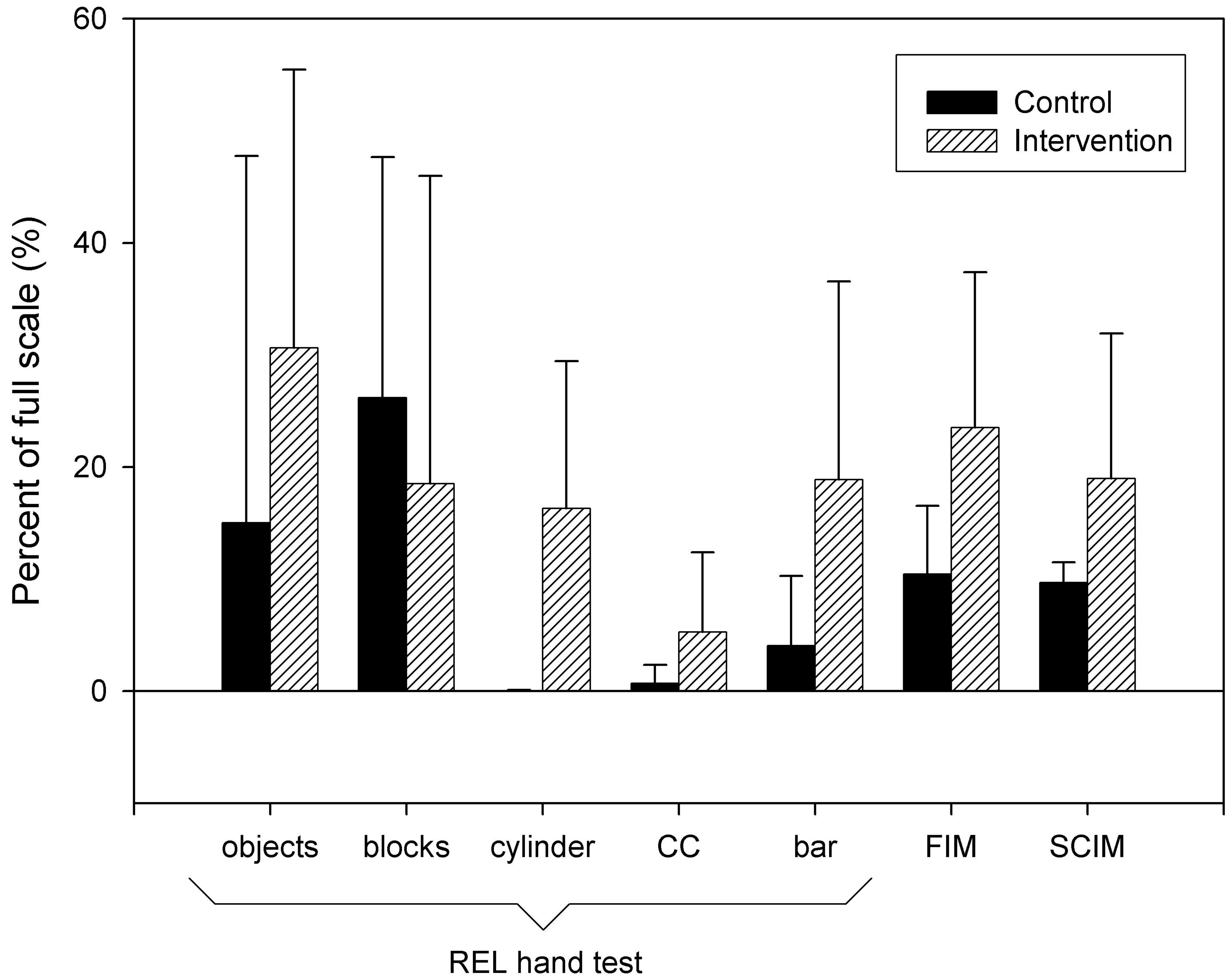
5 horizontal lines represent medians.

6

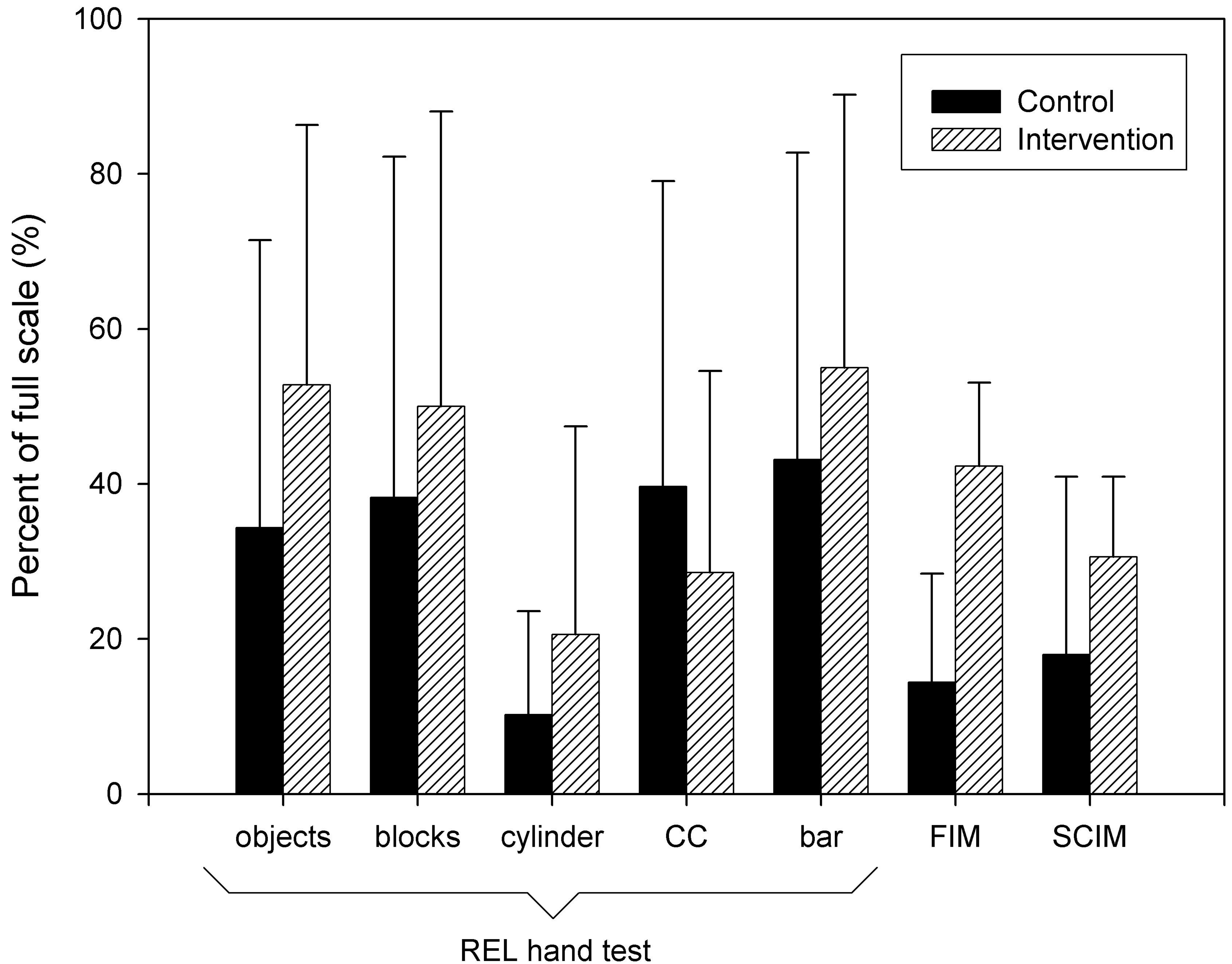




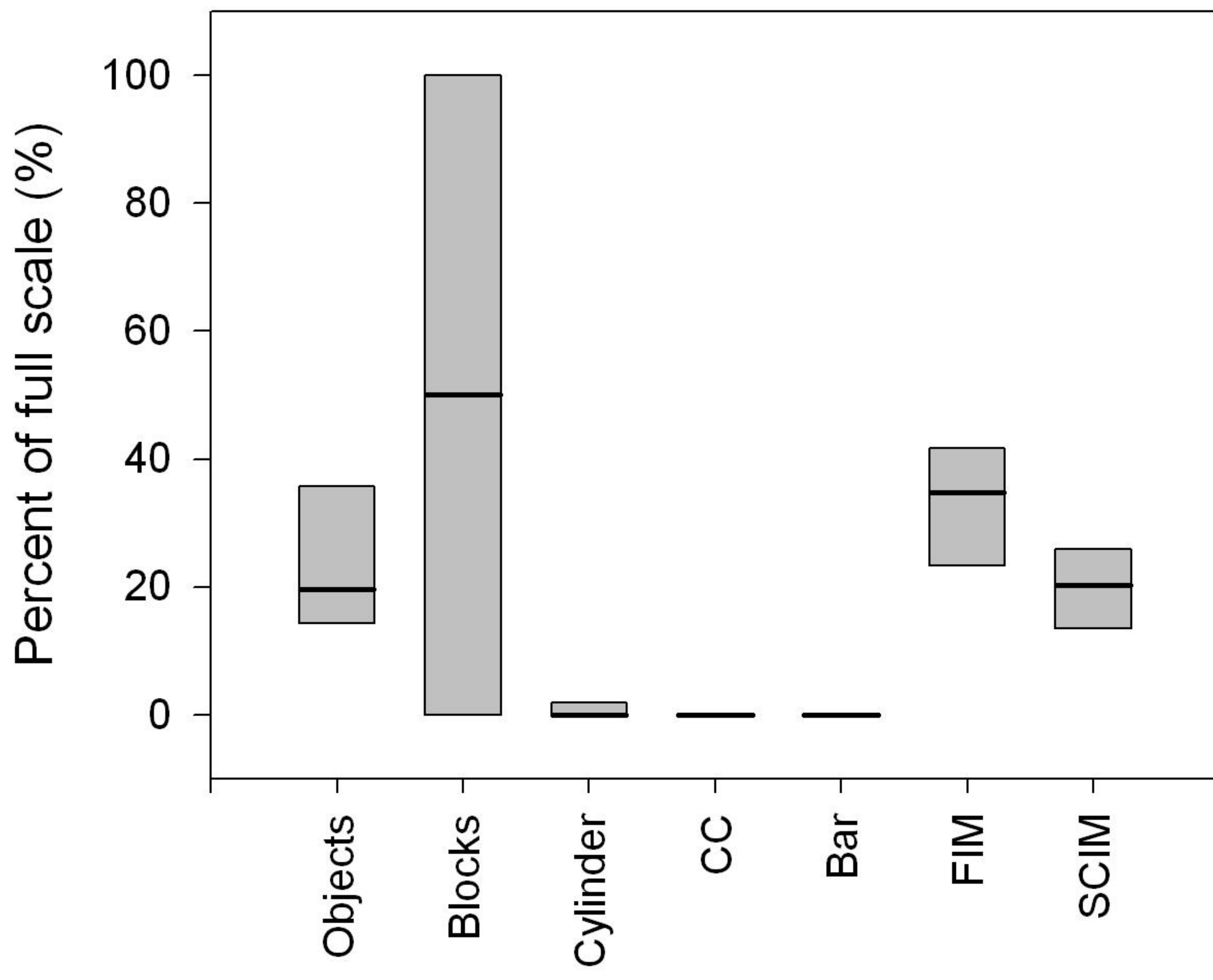
Increase from baseline to post-treatment (Complete SCI only)



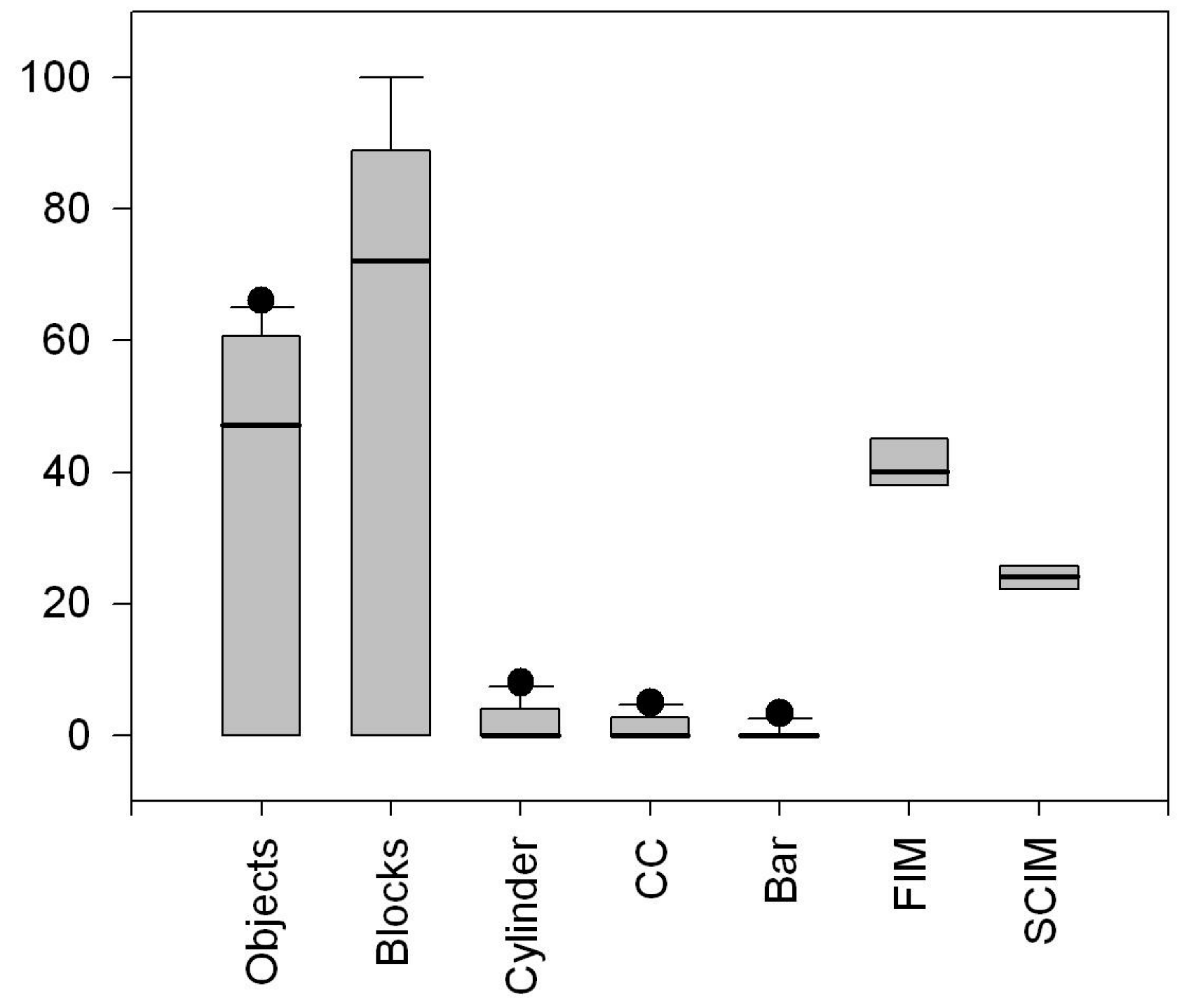
Increase from baseline to post-treatment (Incomplete SCI only)



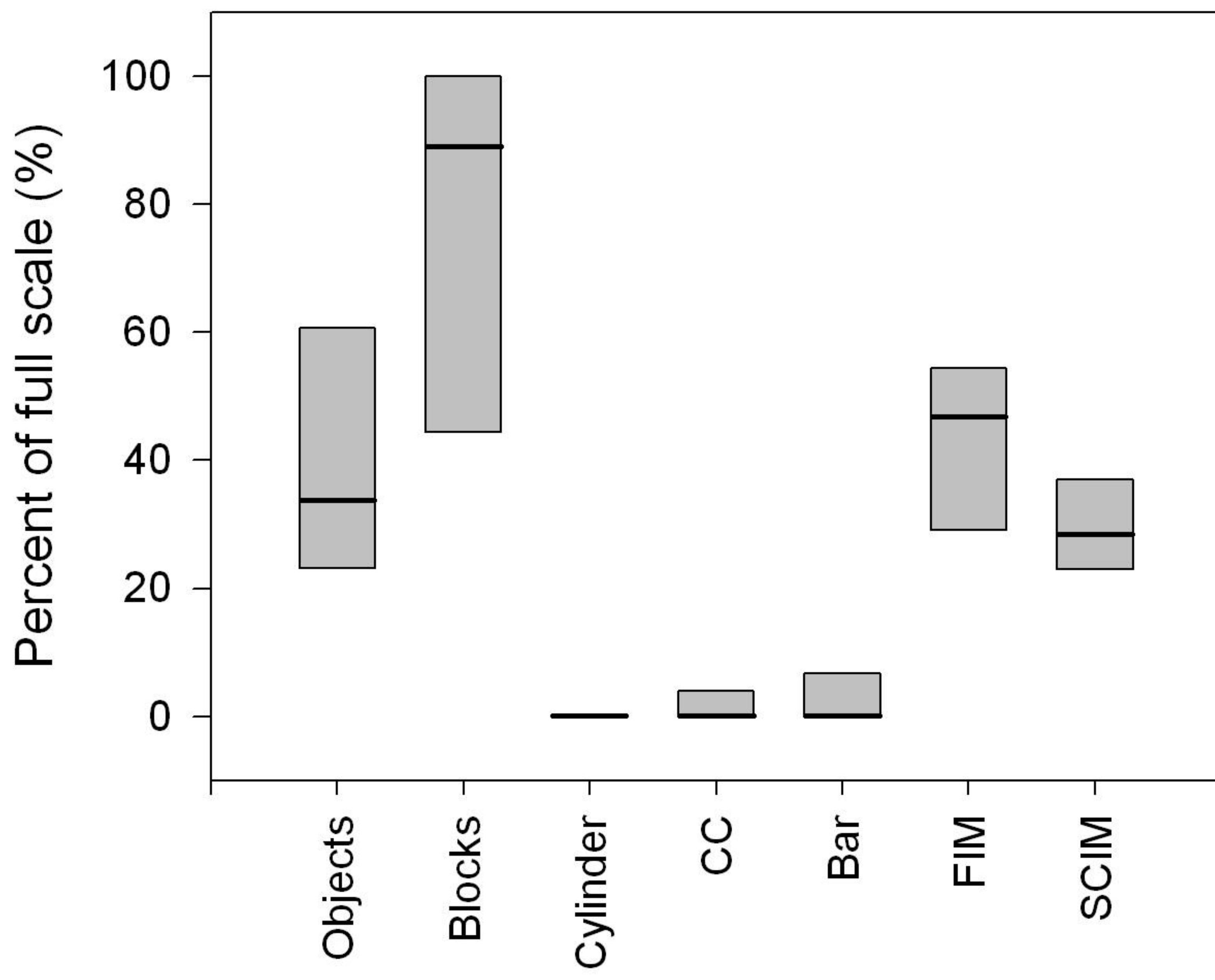
Control group - baseline



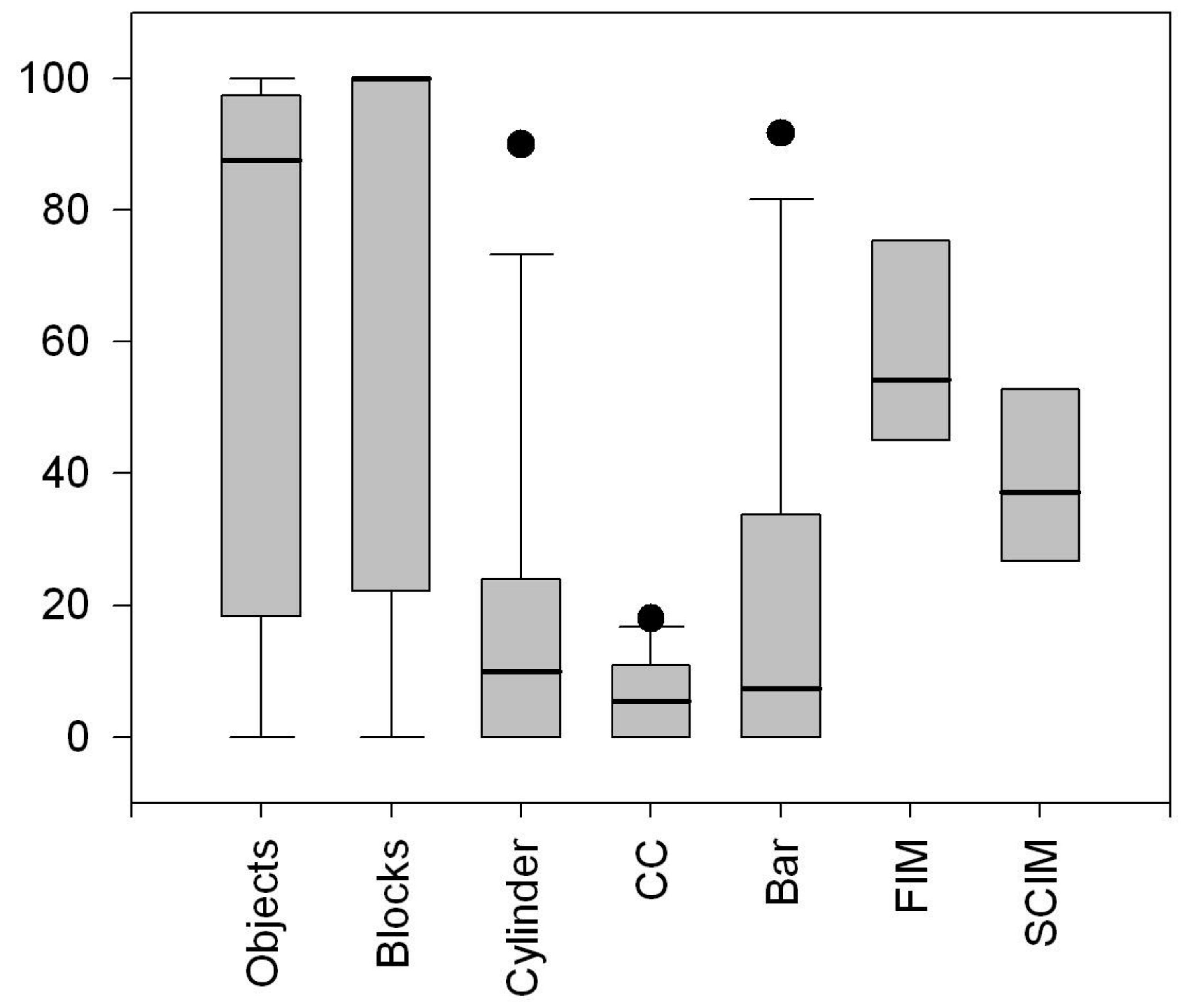
Intervention group - baseline



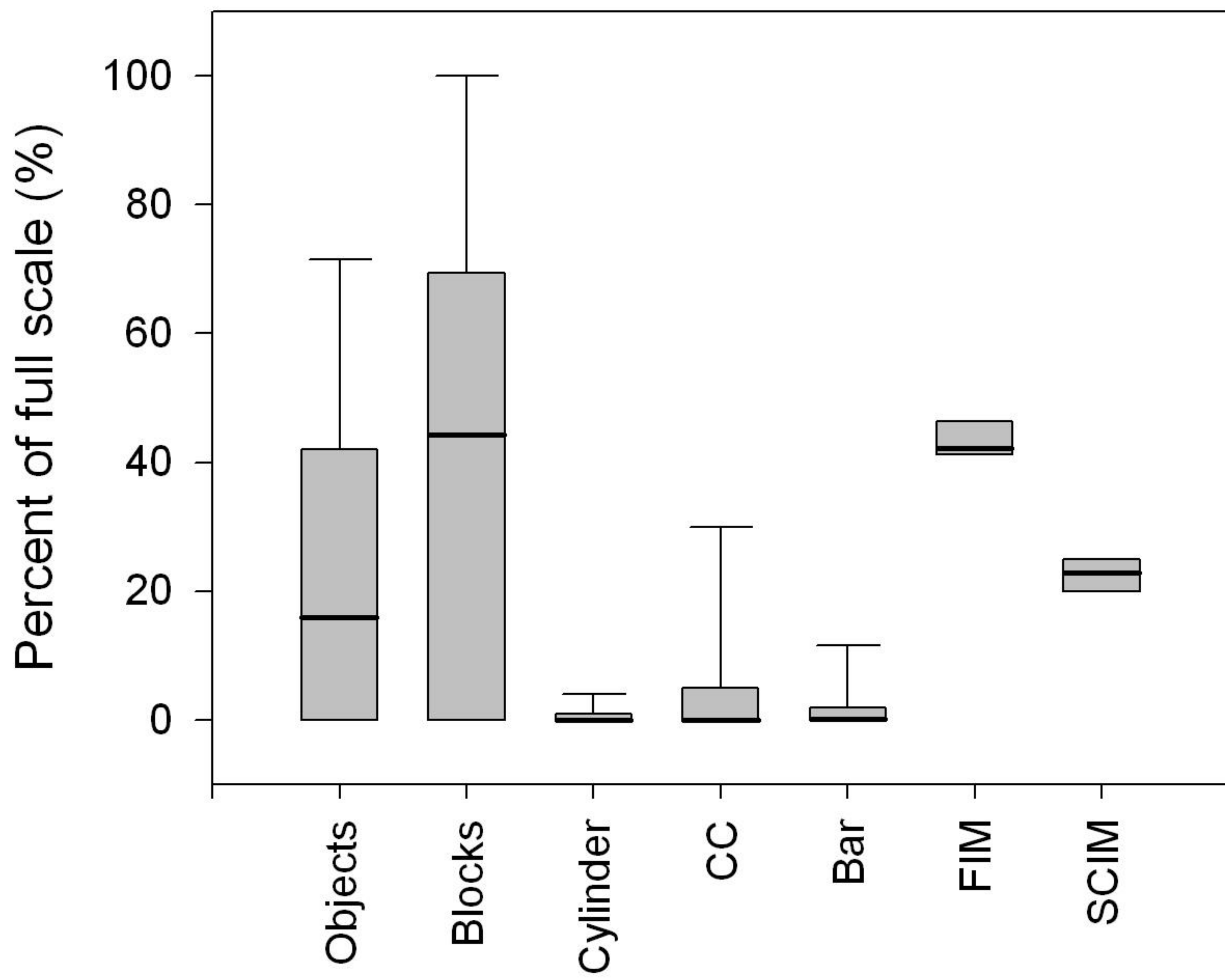
Control group - end



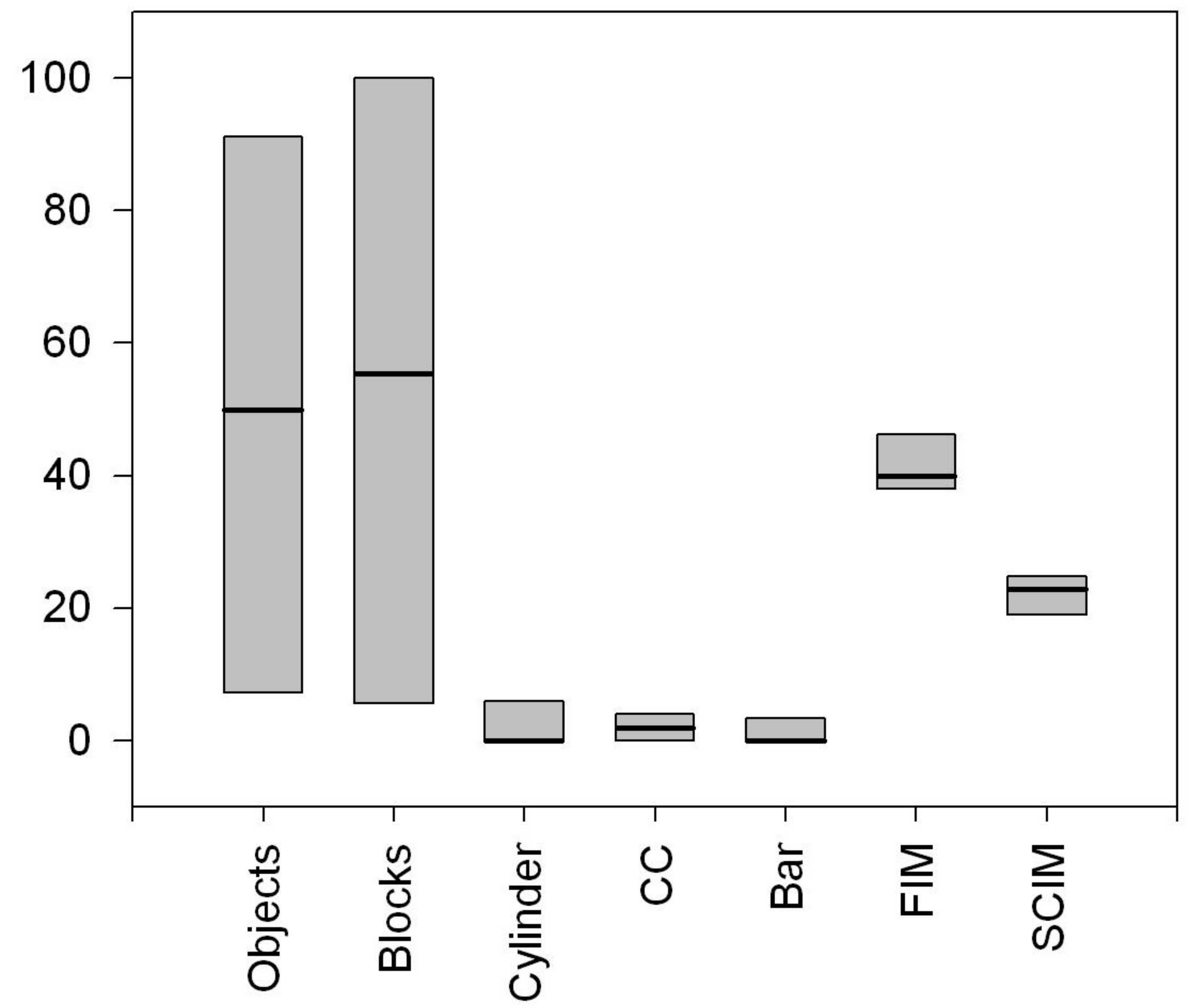
Intervention group - end



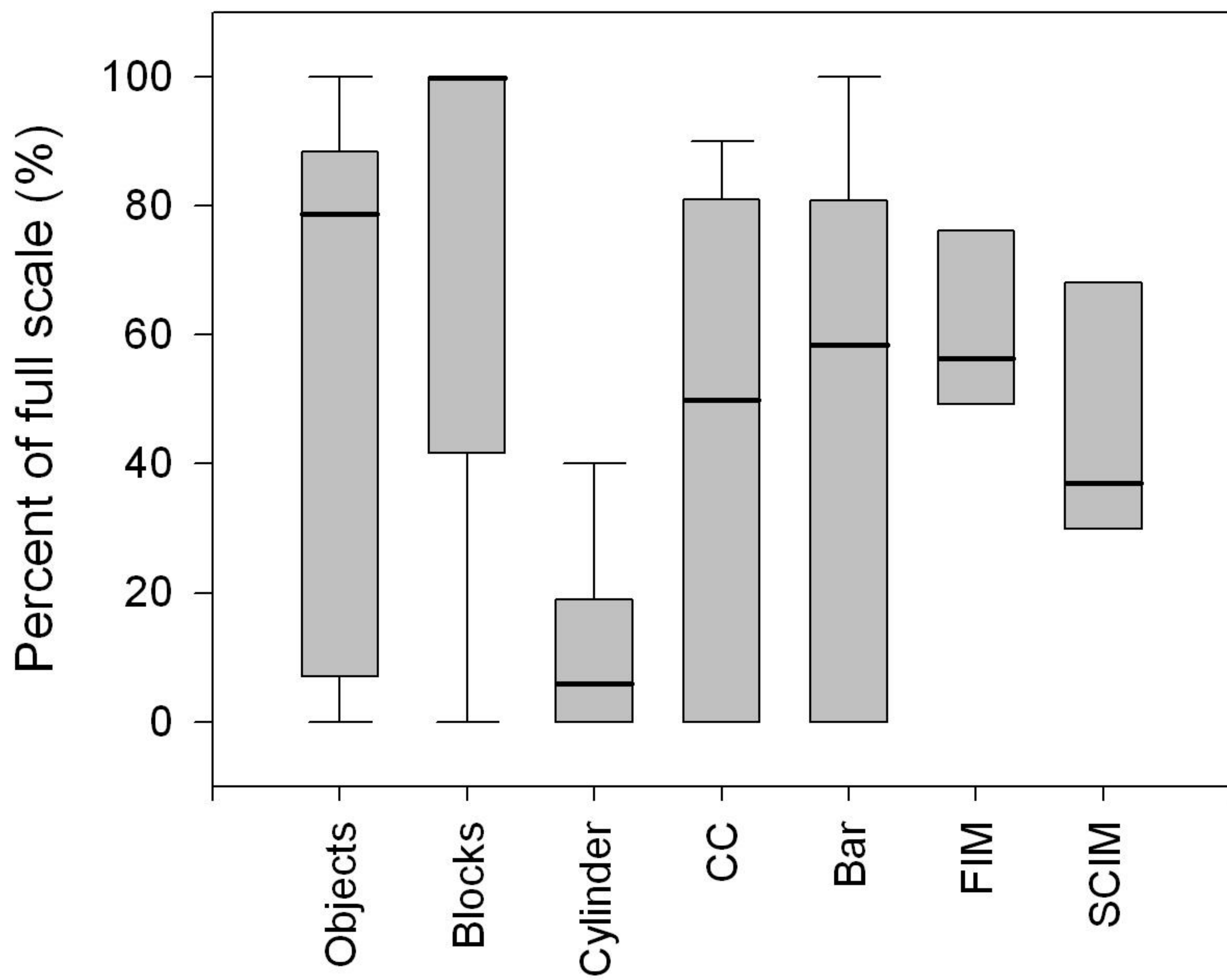
Control group - baseline



Intervention group - baseline



Control group - end



Intervention group - end

