PHYS 121H122-Lecture 12: Electromagnetic Induction

Today: Chap 29:

a) Faraday's Law

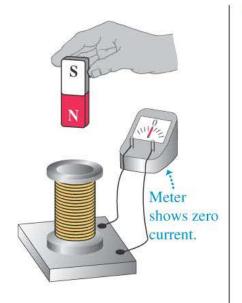
Maxwell's Laws [almost complete!]

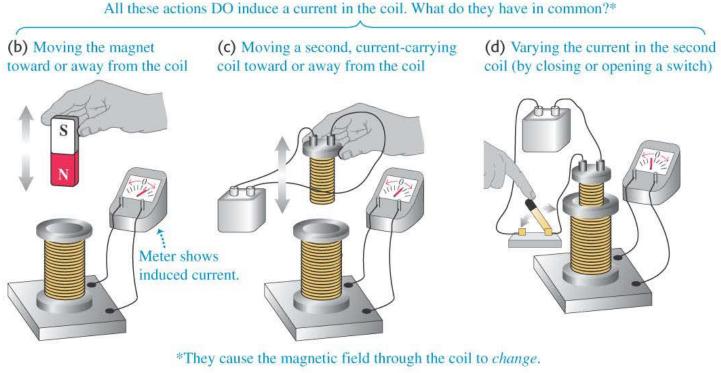
- b) Lenz's Law
- c) Examples
- d) Correction to Ampere's Law

Induced current

- A changing magnetic flux causes an *induced current*. See Figure 29.1 below.
- The *induced emf* is the corresponding emf causing the current.

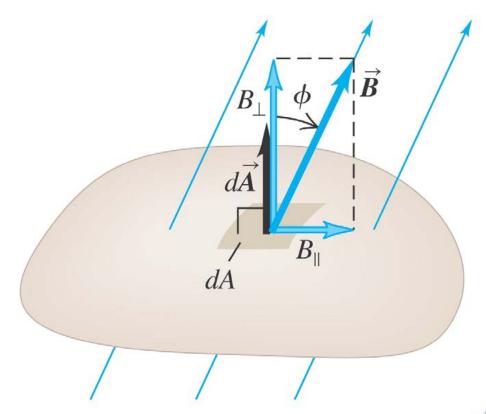
(a) A stationary magnet does NOT induce a current in a coil.





Magnetic flux through an area element

• Figure 29.3 below shows how to calculate the magnetic flux through an element of area.

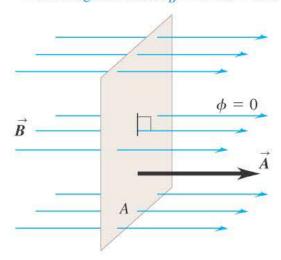


Magnetic flux through element of area $d\vec{A}$: $d\Phi_B = \vec{B} \cdot d\vec{A} = B_{\perp} dA = B dA \cos \phi$

- The flux depends on the orientation of the surface with respect to the magnetic field. See Figure 29.4 below.
- Faraday's law: The induced emf in a closed loop equals the negative of the time rate of change of magnetic flux through the loop, or $\xi = -d\Phi_B/dt$.

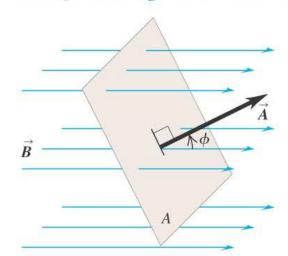
Surface is face-on to magnetic field:

- \vec{B} and \vec{A} are parallel (the angle between \vec{B} and \vec{A} is $\phi = 0$).
- The magnetic flux $\Phi_B = \vec{B} \cdot \vec{A} = BA$.



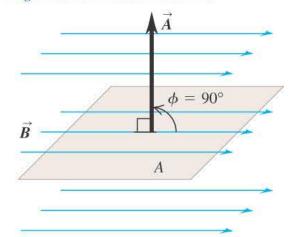
Surface is tilted from a face-on orientation by an angle ϕ :

- The angle between \vec{B} and \vec{A} is ϕ .
- The magnetic flux $\Phi_B = B \cdot A = BA \cos \phi$.



Surface is edge-on to magnetic field:

- \vec{B} and \vec{A} are perpendicular (the angle between \vec{B} and \vec{A} is $\phi = 90^{\circ}$).
- The magnetic flux $\Phi_B = \vec{B} \cdot \vec{A} = BA \cos 90^\circ = 0.$



$$V = -\frac{\delta}{\delta t} \Phi$$

with
$$\int \vec{B} \cdot d\vec{A} = \Phi_B$$

$$V = -\frac{\delta}{\delta t} \Phi$$

with
$$\int \vec{B} \cdot d\vec{A} = \Phi_B$$

$$\oint \vec{E} \cdot d\vec{\ell} = V = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$V = -\frac{\delta}{\delta t} \Phi$$

with
$$\int \vec{B} \cdot d\vec{A} = \Phi_B$$

$$\oint \vec{E} \cdot d\vec{\ell} = V = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$\oint \vec{E} \cdot d\vec{\ell} = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$V = -\frac{\delta}{\delta t} \Phi$$

with
$$\int \vec{B} \cdot d\vec{A} = \Phi_B$$

$$\oint \vec{E} \cdot d\vec{\ell} = V = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$\oint \vec{E} \cdot d\vec{\ell} = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$\oint (\nabla \times \vec{E}) \cdot d\vec{A} = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$V = -\frac{\delta}{\delta t} \Phi$$

with
$$\int \vec{B} \cdot d\vec{A} = \Phi_B$$

$$\oint \vec{E} \cdot d\vec{\ell} = V = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$\oint \vec{E} \cdot d\vec{\ell} = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$\oint (\nabla \times \vec{E}) \cdot d\vec{A} = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$\nabla \times \vec{E} = -\frac{\delta B}{\delta t}$$

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{enc}}{\epsilon_o}$$

$$\oint \vec{B} \cdot d\vec{A} = 0$$

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_o I_{enc}$$

$$V = -\frac{\delta}{\delta t} \Phi$$

$$\oint \vec{E} \cdot d\vec{\ell} = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{enc}}{\epsilon_o}$$

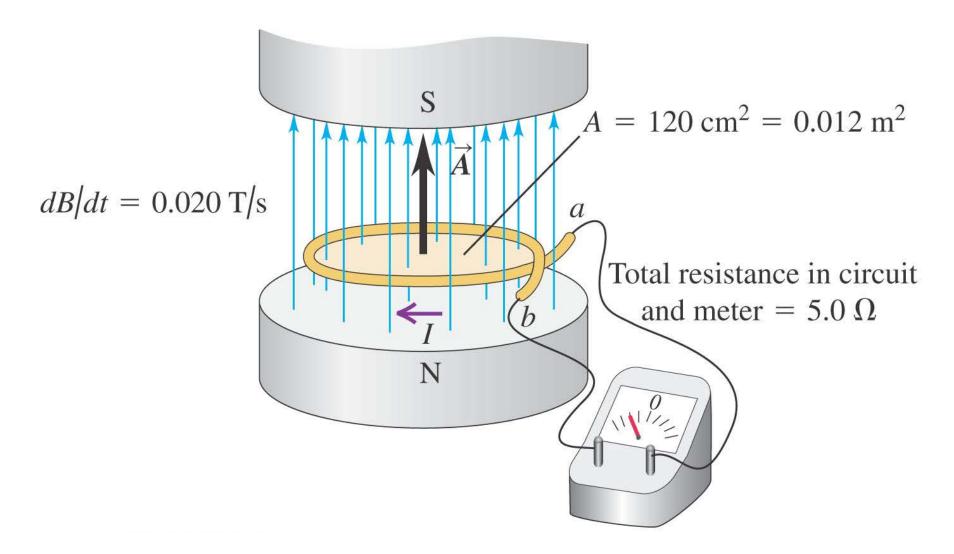
$$\oint \vec{B} \cdot d\vec{A} = 0$$

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_o I_{enc}$$

$$\oint \vec{E} \cdot d\vec{\ell} = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

Emf and the current induced in a loop

• Follow Example 29.1 using Figure 29.5 below.

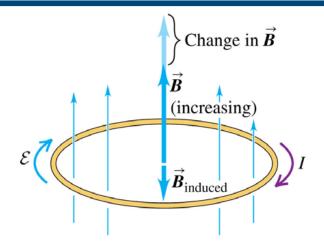


Lenz's law

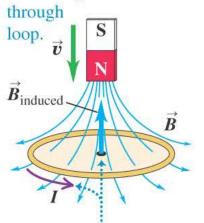
- Lenz's law: The direction of any magnetic induction effect is such as to oppose the cause of the effect.
- Follow Conceptual Example 29.7.

Lenz's law and the direction of induced current

Follow Example 29.8
 using Figures 29.13
 (right) and 29.14 (below).

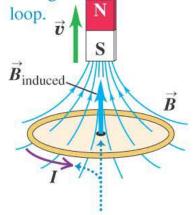


(a) Motion of magnet causes increasing downward flux through



(b) Motion of magnet causes

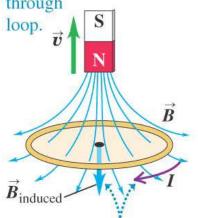
decreasing upward flux
through



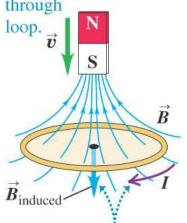
The induced magnetic field is *upward* to oppose the flux change. To produce this induced field, the induced current must be *counterclockwise* as seen from above the loop.

(c) Motion of magnet causes

decreasing downward flux
through



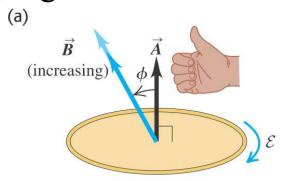
(d) Motion of magnet causes increasing upward flux through



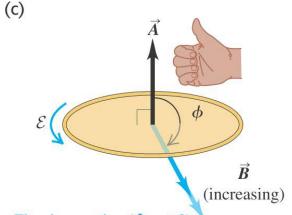
The induced magnetic field is *downward* to oppose the flux change. To produce this induced field, the induced current must be *clockwise* as seen from above the loop.

Direction of the induced emf

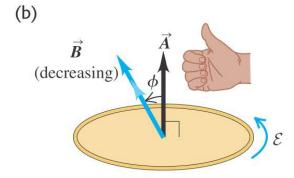
• Follow the text discussion on the direction of the induced emf, using Figure 29.6 below.



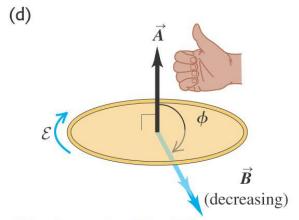
- Flux is positive ($\Phi_B > 0$) ...
- ... and becoming more positive $(d\Phi_B/dt > 0)$.
- Induced emf is negative ($\mathcal{E} < 0$).



- Flux is negative ($\Phi_B < 0$) ...
- ... and becoming more negative $(d\Phi_B/dt < 0)$.
- Induced emf is positive ($\mathcal{E} > 0$).



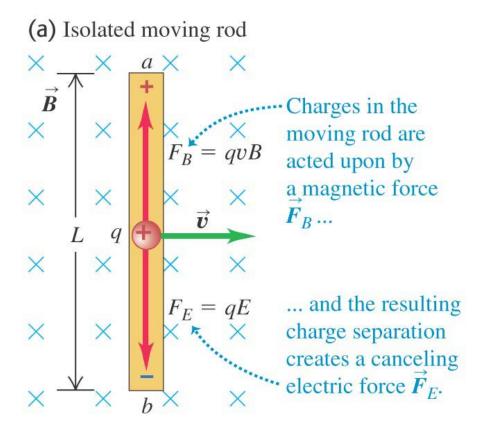
- Flux is positive ($\Phi_B > 0$) ...
- ... and becoming less positive $(d\Phi_B/dt < 0)$.
- Induced emf is positive ($\mathcal{E} > 0$).



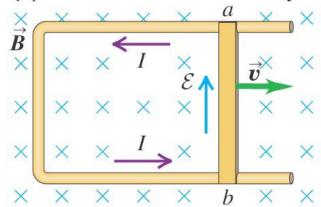
- Flux is negative ($\Phi_R < 0$) ...
- ... and becoming less negative $(d\Phi_R/dt > 0)$.
- Induced emf is negative ($\mathcal{E} < 0$).

Motional electromotive force

- The motional electromotive force across the ends of a rod moving perpendicular to a magnetic field is $\xi = vBL$. Figure 29.15 below shows the direction of the induced current.
- Follow the general form of motional emf in the text.



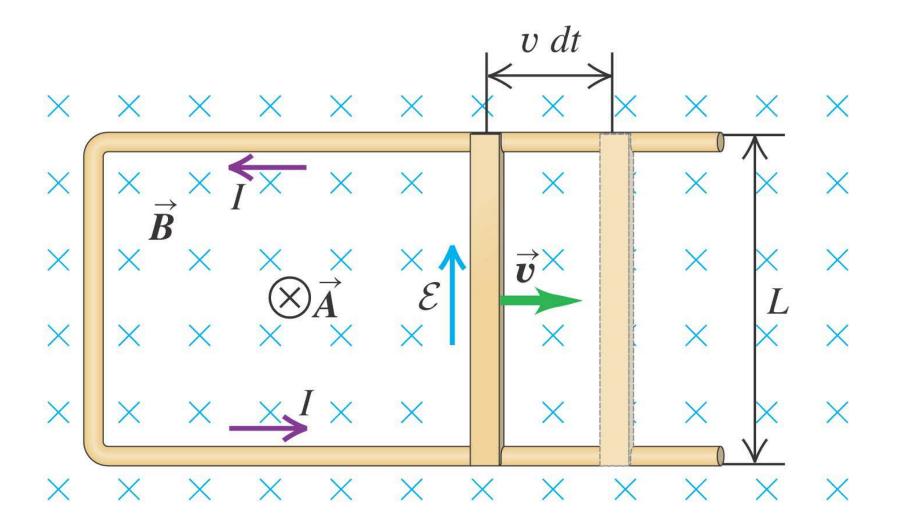
(b) Rod connected to stationary conductor



The motional emf \mathcal{E} in the moving rod creates an electric field in the stationary conductor.

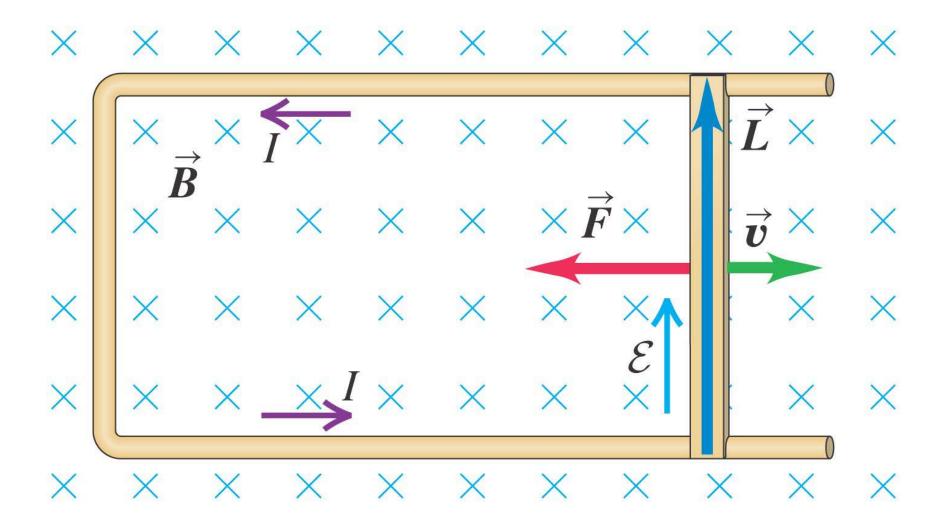
Slidewire generator

• Follow Example 29.5 using Figure 29.11 below.



Work and power in the slidewire generator

• Follow Example 29.6 using Figure 29.12 below.





$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{enc}}{\epsilon_o}$$

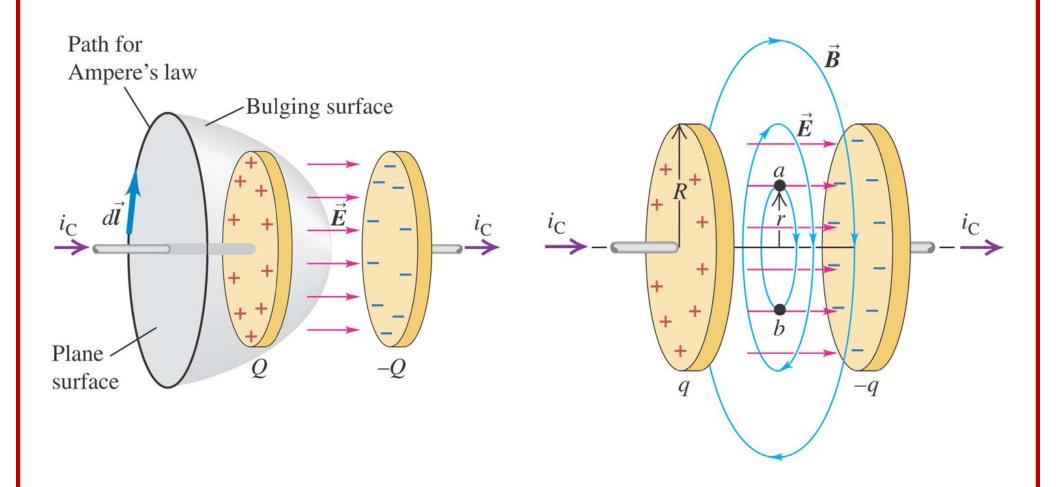
$$\oint \vec{B} \cdot d\vec{A} = 0$$

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_o I_{enc}$$

$$\oint \vec{E} \cdot d\vec{\ell} = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

Displacement current

• Follow the text discussion displacement current using Figures 29.21 and 29.22 below.



$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{enc}}{\epsilon_o}$$

$$\oint \vec{B} \cdot d\vec{A} = 0$$

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_o I_{enc}$$

$$\oint \vec{E} \cdot d\vec{\ell} = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{e_enc}}{\epsilon_o}$$

$$\oint \vec{B} \cdot d\vec{A} = 0$$

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_o I_{e_enc}$$

$$\oint \vec{E} \cdot d\vec{\ell} = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{e_enc}}{\epsilon_o}$$

$$\oint \vec{B} \cdot d\vec{A} = \frac{Q_{m_enc}}{\mu_o}$$

$$\oint \vec{B} \cdot d\vec{A} = \frac{Q_{m_enc}}{\mu_o}$$

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_o I_{e_enc}$$

$$\oint \vec{E} \cdot d\vec{\ell} = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

Gauss' Law

"No Name Law"

Ampere's Law

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{e_enc}}{\epsilon_o}$$

Gauss' Law

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{e_enc}}{\epsilon_o}$$

$$\oint \vec{B} \cdot d\vec{A} = \frac{Q_{m_enc}}{\mu_o}$$

"No Name Law"

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_o I_{e_enc}$$

Ampere's Law

$$\oint \vec{E} \cdot d\vec{\ell} = \epsilon_o I_{m_enc} - \frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{e_enc}}{\epsilon_o}$$

$$\oint \vec{B} \cdot d\vec{A} = \frac{Q_{m_enc}}{\mu_o}$$

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_o I_{e_enc} - \frac{\delta}{\delta t} \int \vec{E} \cdot d\vec{A}$$

$$\oint \vec{E} \cdot d\vec{\ell} = \epsilon_o I_{m_enc} - \frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{e_enc}}{\epsilon_o}$$

Gauss' Law

$$\oint \vec{B} \cdot d\vec{A} = \frac{Q_{m_enc}}{\mu_o}$$

"No Name Law"

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_o I_{e_enc} - \epsilon_o \,\mu_o \,\frac{\delta}{\delta t} \int \vec{E} \cdot d\vec{A}$$

Ampere's Law

$$\oint \vec{E} \cdot d\vec{\ell} = \epsilon_o I_{m_enc} - \frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{e_enc}}{\epsilon_o}$$

$$\oint \vec{B} \cdot d\vec{A} = \frac{Q_{m_enc}}{\mu_o}$$

Gauss' Law

$$\oint \vec{B} \cdot d\vec{A} = \frac{Q_{m_enc}}{\mu_o}$$

"No Name Law"

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_o I_{e_enc} - \epsilon_o \,\mu_o \,\frac{\delta}{\delta t} \int \vec{E} \cdot d\vec{A}$$

Ampere's Law

$$\oint \vec{E} \cdot d\vec{\ell} = \epsilon_o I_{m_enc} - \frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

Faraday's Law

But no magnetic monopoles have been found! So no magnetic current!

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q_{e_enc}}{\epsilon_o}$$

Gauss' Law

$$\oint \vec{B} \cdot d\vec{A} = 0$$

"No Name Law"

$$\oint \vec{B} \cdot d\vec{\ell} = \mu_o I_{e_enc} - \epsilon_o \,\mu_o \,\frac{\delta}{\delta t} \int \vec{E} \cdot d\vec{A}$$

Ampere's Law w/ Maxwell's Correction

$$\oint \vec{E} \cdot d\vec{\ell} = -\frac{\delta}{\delta t} \int \vec{B} \cdot d\vec{A}$$

Faraday's Law

But no magnetic monopoles have been found! So no magnetic current!