Numerical Analysis Previous Qual - May 2018.

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This work is based on the course textbook [1], the material discussed in lectures and office hours related to our course MAT614 and additional references.

1 Problem May 2018 1 -

1.1 1a

Let A be a real symmetric 3×3 matrix with eigenvalues 0,3,5 and corresponding eigenvectors $\mathbf{u}, \mathbf{v}, \mathbf{w}$.

1.1.1 REDACTED

By definition, the nullspace of A is spanned by $c\mathbf{u}$, c any arbitrary scalar. Similarly, the column space is spanned by $d\mathbf{v}$, $e\mathbf{w}$ d, e any arbitrary scalars.

1.1.2 REDACTED

Given that u spans the nullspace, there is no solution for Ax = u.

1.1.3 REDACTED

Given that A is rank deficient, since it has one eigenvalue of 0, A is singular and not invertible, it is not full rank.

1.2 1b - REDACTED

1.2.1 Show they have the same determinant

We have that:

$$A = SBS^{-1}.$$
$$AS = SB.$$

$$det(AS) = det(SB).$$
$$det(A) det(S) = det(S) det(B).$$
$$det(A) = det(B).$$

1.2.2 REDACTED. We have that:

$$A = SBS^{-1}.$$

$$A - \lambda I = SBS^{-1} - \lambda I.$$

$$AS - \lambda IS = SB - \lambda IS.$$

$$\det((A - \lambda I)S) = \det(S(B - \lambda I)).$$

$$\det(A - \lambda I) \det(S) = \det(S) \det(B - \lambda I)).$$

$$\det(A - \lambda I) = \det(B - \lambda I).$$

Thus, the characteristic polynomial of A, $\det(A - \lambda I) = 0$ is the same as $\det(B - \lambda I) = 0$.

2 Problem 2

- 2.1 2a
- 2.2 2b

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3 Problem August 2018 3 - REDACTED

$$y' = 5y_1 - 6y_2.$$

 $y' = 3y_1 - 4y_2.$

3.1 Study notes:

For IVP problems of this type, we have that our standard solutions relative to eigenvalues $\lambda = \mu + i\nu$ are:

$$y = e^{\mu t} (\alpha \sin (\nu t) + \beta \cos (\nu t)).$$

3.2 Solution proof

We have that our corresponding matrix representation for this system is:

$$A = \begin{bmatrix} 5 & -6 \\ 3 & -4 \end{bmatrix}$$
$$\begin{bmatrix} 5 & -6 \\ 3 & -4 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

We calculate the eigenvalues of A by solving $det(A - \lambda I) = 0 \implies (5 - \lambda)(-4 - \lambda) - (3(-6)) = 0 \implies \lambda^2 - \lambda - 2 = 0$. We use these two eigenvalues to solve $(A - \lambda I)v = 0$ to find the corresponding eigenvalues:

For
$$\lambda_1 = 2, v_1 = \begin{bmatrix} 2\\ 1 \end{bmatrix}$$
.
For $\lambda_2 = -1, v_2 = \begin{bmatrix} 1\\ 1 \end{bmatrix}$.

We thus have our general solution:

$$y_{gen} = \alpha e^{2t} \begin{bmatrix} 2\\1 \end{bmatrix} + \beta e^{-t} \begin{bmatrix} 1\\1 \end{bmatrix}$$

We find our particular solution to this IVP by using the initial condition provided:

$$y_{part} = \alpha e^{20} \begin{bmatrix} 2\\1 \end{bmatrix} + \beta e^{-0} \begin{bmatrix} 1\\1 \end{bmatrix} = \begin{bmatrix} 4\\1 \end{bmatrix}.$$

We solve this system of equations to determine that $\alpha = 3, \beta = -2$. Thus, our final particular solution to this particular initial value problem is:

$$y_{(part.final)} = 3e^{2t} \begin{bmatrix} 2\\1 \end{bmatrix} - 2e^{-t} \begin{bmatrix} 1\\1 \end{bmatrix}.$$

Or, equivalently:

$$\therefore y_{(part.final)} = y_1 + y_2, y_1 = 6e^{2t} - 2e^{-t}, y_2 = 3e^{2t} - 2e^{-t}.\checkmark$$

4 Conclusion

Thank you to Prof. Hamfeldt, neé Froese, for reading this work, for her instruction, lectures and future office hours efforts. I look forward to any feedback and learning more of the material in this course.

References

[1] Kendall E Atkinson. An introduction to numerical analysis. John wiley & sons, 2008.