Blocking and non-blocking MPI communications

Blocking and non-blocking sends

- Blocking: return only when the buffer is ready to be reused.
- Non-blocking: return immediately.
- Buffering: data is kept until it is received.
- Synchronization: when a send is completed.
- Collective communications in MPI are always blocking.

Examples:

MPI_Send (): Blocking send. Will not return until you can use the send buffer.

MPI_Isend (): Nonblocking send. But not necessarily

asynchronous. You CANNOT reuse the send buffer until either a successful wait/test or you certainly KNOW that the message has been received. An immediate send must return to the user without requiring a matching receive at the destination.

Example of a deadlock:

Both ranks wait for the other one to receive the message.

```
#include "mpi.h"
#include <math.h>
int main(int argc, char** argv) {
 MPI Status status;
 int num:
 MPI Init(&aroc. &arov):
 MPI Comm rank(MPI COMM WORLD,&num);
 double d = 100.0:
 int tag = 1:
 if(num==0) {
   /* synchronous send: returns when the destination
      has started to receive the message */
   MPI_Ssend(&d,1,MPI_DOUBLE,1,tag,MPI_COMM_WORLD);
   MPI Recv (&d,1,MPI DOUBLE,1,taq,MPI COMM WORLD,&status);
  }
 else {
   MPI Ssend(&d.1.MPI DOUBLE.0.tag.MPI COMM WORLD):
   MPI Recv (&d.1.MPI DOUBLE.0.tag.MPI COMM WORLD.&status):
 MPI Finalize():
return 0:
}
```

Blocking vs. non-blocking

A remedy: use standard send & receive

```
if(num==0) {
    /* Standard send: can be synchronous or buffered,
    depending on message size */
    MPI_send(&d,1,MPI_DOUBLE,1,tag,MPI_COMM_WORLD);
    MPI_Recv (&d,1,MPI_DOUBLE,1,tag,MPI_COMM_WORLD,&status);
    }
    else {
        MPI_Send(&d,1,MPI_DOUBLE,0,tag,MPI_COMM_WORLD);
        MPI_Recv (&d,1,MPI_DOUBLE,0,tag,MPI_COMM_WORLD);
    }
}
```

For such a small message MPI will always buffer it when using a standard send. However, the deadlock may still occur depending on the size of the buffer.

Blocking vs. non-blocking

Use non-blocking MPI send & receive

Example: Nearest neighbor exchange in a ring topology

┶᠐≠1≠2≠3≠4≠5≠∞≠N∓

```
#include "mpi.h"
#include <stdio.h>
```

```
main(int argc, char *argv[]) {
    int nuntasks, rank, next, prev, buf[2], tag1=1, tag2=2;
    MPI_Request reqs[4]; // required variable for non-blocking calls
    MPI_status stats[4]; // required variable for Waitall routine
```

```
MPI_Init(&argc,&argv);
MPI_Comm_size(MPI_COMM_WORLD, &numtasks);
MPI_Comm_rank(MPI_COMM_WORLD, &rank);
```

```
// determine left and right neighbors
prev = rank-1;
next = rank+1;
if (rank == 0) prev = numtasks - 1;
if (rank == (numtasks - 1)) next = 0;
```

```
// post non-blocking receives and sends for neighbors
MPI_Irecv(&buf[0], 1, MPI_INT, prev, tag1, MPI_COMM_WORLD, &reqs[0]);
MPI_Irecv(&buf[1], 1, MPI_INT, next, tag2, MPI_COMM_WORLD, &reqs[1]);
```

```
MPI_Isend(&rank, 1, MPI_INT, prev, tag2, MPI_COMM_WORLD, &reqs[2]);
MPI_Isend(&rank, 1, MPI_INT, next, tag1, MPI_COMM_WORLD, &reqs[3]);
```

```
// do some work while sends/receives progress in background
```

```
// wait for all non-blocking operations to complete
MPI_Waitall(4, reqs, stats);
```

```
// continue - do more work
```

```
MPI_Finalize();
```

• Use the MPI non-blocking message passing and rewrite the heat_mpi.c example with a non-blocking neighbor communication.