

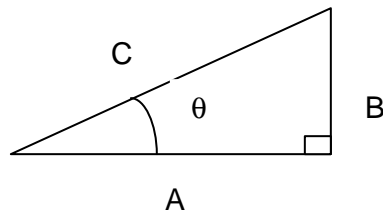
Name: \_\_\_\_\_

## CONSTANTS AND TRIGONOMETRY

$g = 9.80 \text{ m/s}^2$

$$\sin \theta = \frac{B}{C} \quad \cos \theta = \frac{A}{C} \quad \tan \theta = \frac{B}{A}$$

$$C = \sqrt{A^2 + B^2}$$



## MOTION ALONG A STRAIGHT LINE

$v = v_0 + at$

$x - x_0 = v_0 t + \frac{1}{2} at^2$

$$x - x_0 = \frac{1}{2}(v_0 + v)t \quad v^2 = v_0^2 + 2a(x - x_0)$$

## TWO-DIMENSIONAL MOTION:

$$\mathbf{r} = (v_{0x}t + \frac{1}{2}a_x t^2)\mathbf{i} + (v_{0y}t + \frac{1}{2}a_y t^2)\mathbf{j}; \quad \mathbf{v} = (v_{0x} + a_x t)\mathbf{i} + (v_{0y} + a_y t)\mathbf{j}; \quad \mathbf{a} = \frac{v_x - v_{0x}}{t}\mathbf{i} + \frac{v_y - v_{0y}}{t}\mathbf{j}$$

## PROJECTILE MOTION

$$\mathbf{n}_{0x} = \mathbf{n}_0 \cos \theta_0 \quad \mathbf{n}_{0y} = \mathbf{n}_0 \sin \theta_0 \quad \Delta x = v_{0x}t \quad \mathbf{n}_y = \mathbf{n}_{0y} - gt$$

$$\Delta y = \mathbf{n}_{0y}t - \frac{1}{2}gt^2 \quad \mathbf{n}_y^2 = \mathbf{n}_{0y}^2 - 2g(\Delta y)$$

$$\Delta y = \frac{v_y^2 - v_{0y}^2}{-2g} \quad \Delta y = \frac{a_y v_{0y} + v_y}{2} \frac{v_y - v_{0y}}{a_y}$$

## FORCE AND MOTION

$$\mathbf{F}_{\text{net}} = m\mathbf{a} \quad F_g = mg \quad f_{s,\text{max}} = \mu_s N \quad f_k = \mu_k N$$

Uniform circular motion: centripetal acceleration:  $a = v^2/r$   
centripetal force:  $F = mv^2/r$

## WORK AND ENERGY:

$$W = Fd(\cos\theta) \quad W = F_x d_x + F_y d_y + F_z d_z \quad W_{\text{net}} = \Delta K \quad W_{\text{spring}} = -\frac{1}{2}k(x_f^2 - x_i^2) = \frac{1}{2}k(x_i^2 - x_f^2)$$

$$K = \frac{1}{2}mv^2 \quad \Delta U_{\text{grav}} = mg(y_f - y_i)$$

$$\text{Spring: } F_s = -kx \quad \Delta U_s = \frac{1}{2}k(x_f^2 - x_i^2)$$

$$\text{Power: } P_{\text{avg}} = \frac{W}{\Delta t}$$

## CONSERVATION OF ENERGY

$$W = \Delta E_{\text{mec}} + \Delta E_{\text{th}} \quad \Delta E_{\text{mec}} = \Delta K + \Delta U$$

Or

Work due to *nonconservative* forces:  $W_{\text{nc}} = \Delta E_{\text{mec}}$

$$W_{\text{nc}} = \Delta K + \Delta U_{\text{g}} + \Delta U_{\text{s}} \quad \text{or} \quad K_{\text{i}} + U_{\text{gi}} + U_{\text{si}} + W_{\text{nc}} = K_{\text{f}} + U_{\text{gf}} + U_{\text{sf}}$$

If the system is isolated (no friction or applied forces do work on system):

$$0 = \Delta K + \Delta U_{\text{g}} + \Delta U_{\text{s}} \quad \text{or} \quad K_{\text{i}} + U_{\text{gi}} + U_{\text{si}} = K_{\text{f}} + U_{\text{gf}} + U_{\text{sf}}$$

## CENTER OF MASS:

$$x_{\text{com}} = \frac{1}{M} \sum_{i=1}^n m_i x_i \quad y_{\text{com}} = \frac{1}{M} \sum_{i=1}^n m_i y_i$$

## LINEAR MOMENTUM:

$$\vec{p} = m\vec{v} \quad \text{Impulse: } \vec{F}_{\text{avg}} \Delta t = \Delta \vec{p} = m\vec{v}_f - m\vec{v}_o$$

$$\text{For system of particles: } \Delta \vec{p}_{\text{sys}} = \sum (m\vec{v})_f - \sum (m\vec{v})_o$$