

Physics 121 - Electricity and Magnetism

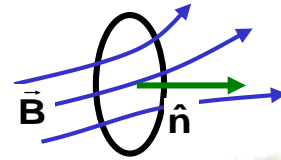
Lecture 12 - Inductance, RL Circuits

Y&F Chapter 30, Sect 1 - 4

- **Inductors and Inductance**
- **Self-Inductance**
- **RL Circuits – Current Growth**
- **RL Circuits – Current Decay**
- **Energy Stored in a Magnetic Field**
- **Energy Density of a Magnetic Field**
- **Mutual Inductance**
- **Summary**

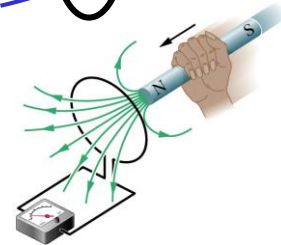
Induction: basics

- **Magnetic Flux:** $d\Phi_B \equiv \vec{B} \circ d\vec{A} = \vec{B} \circ \hat{n}dA$



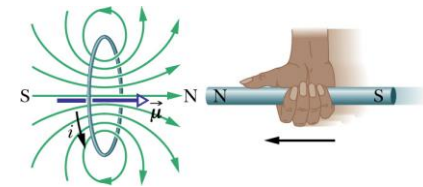
- **Faraday's Law:** A changing magnetic flux through a coil of wire induces an EMF in the wire, proportional to the number of turns, N .

$$\mathcal{E}_{\text{ind}} = -N \frac{d\Phi_B}{dt}$$



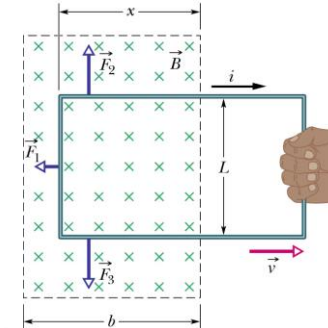
- **Lenz's Law:** The current driven by an induced EMF creates an induced magnetic field that opposes the flux change.

\vec{B}_{ind} & i_{ind} oppose changes in Φ_B

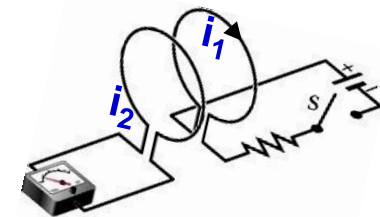


- **Induction and energy transfer:** The forces on the loop oppose the motion of the loop, and the power required to sustain motion provides electrical power to the loop.

$$\mathbf{P} = \vec{F} \cdot \vec{v} = Fv \quad \mathbf{P} = i\mathcal{E} \quad \mathcal{E} = -Blv$$



- **Transformer principle:** changing current i_1 in primary induces EMF and current i_2 in secondary coil.



- A changing magnetic flux creates a non-conservative electric field.

$$\mathcal{E} = \int \vec{E} \cdot d\vec{s} = -N \frac{d\Phi_B}{dt}$$

Changing magnetic flux induces electric fields: trivial transformer

A thin solenoid, cross section A , n turns/unit length

- zero field outside solenoid
- inside solenoid:

$$B = \mu_0 n i$$

Flux through a
conducting loop:

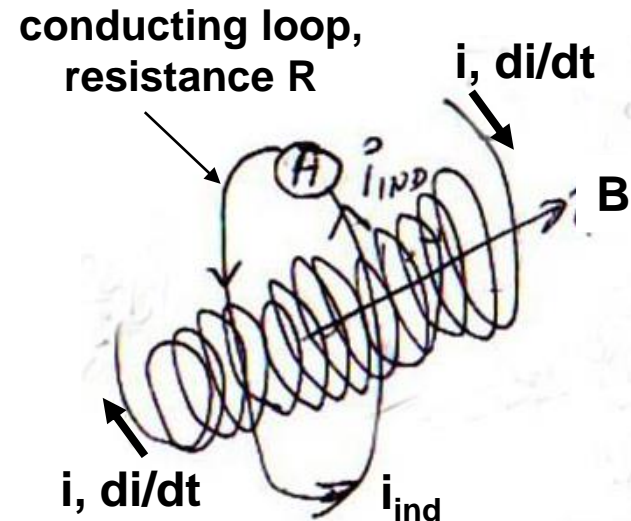
$$\Phi = BA = \mu_0 n i A$$

Current i varies with time, so flux varies and an EMF is induced in loop "A":

$$\mathcal{E}_{\text{ind}} = - \frac{d\Phi}{dt} = - \mu_0 n A \frac{di}{dt}$$

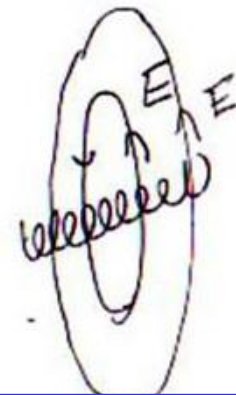
Current induced in the loop is: $i_{\text{ind}} = \frac{\mathcal{E}_{\text{ind}}}{R}$

If di/dt is positive, B is growing, then B_{ind} opposes change and i_{ind} is Counter-clockwise



What makes the current i_{ind} flow?

- $B = 0$ there so it's **not** the Lorentz force
- An induced electric field E_{ind} along the loop causes current to flow
- It is caused directly by dF/dt
- Electric field lines are loops that don't terminate on charge.
- E-field is there even without the conductor (no current flowing)
- E-field is non-conservative (not electrostatic) as the line integral around a closed path is not zero



$$\therefore \mathcal{E}_{\text{ind}} = \oint_{\text{loop}} \mathbf{E}_{\text{ind}} \circ d\vec{s} = - \frac{d\Phi_B}{dt}$$

Generalized Faradays' Law
Path must be constant

Example: Find the induced electric field

$$\mathcal{E}_{\text{ind}} = \oint_{\text{loop}} \vec{E}_{\text{ind}} \circ d\vec{s} = -\frac{d\Phi_B}{dt}$$

$$\oint \vec{B} \circ d\vec{s} = \mu_0 i_{\text{enc}}$$

In the right figure, $dB/dt = \text{constant}$, find the expression for the magnitude E of the induced electric field at points within and outside the magnetic field.

Due to symmetry: $\oint \vec{E} \cdot d\vec{s} = \oint E ds = E \oint ds = E(2\pi r)$

For $r < R$: $\Phi_B = BA = B(\pi r^2)$

$$E = \frac{r}{2} \frac{dB}{dt}$$

So

$$E(2\pi r) = \pi r^2 \frac{dB}{dt}$$

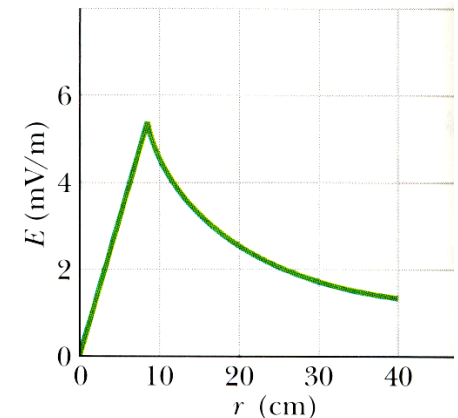
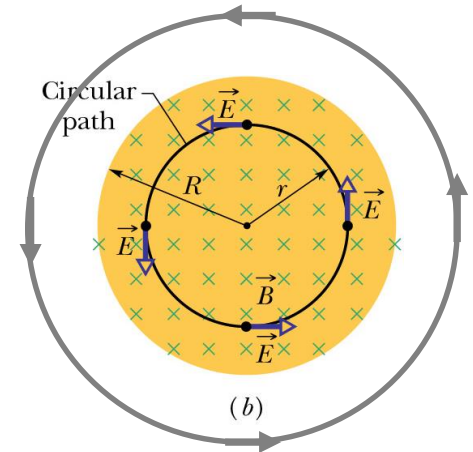
For $r > R$: $\Phi_B = BA = B(\pi R^2)$

$$E = \frac{R^2}{2r} \frac{dB}{dt}$$

So

$$E(2\pi r) = \pi R^2 \frac{dB}{dt}$$

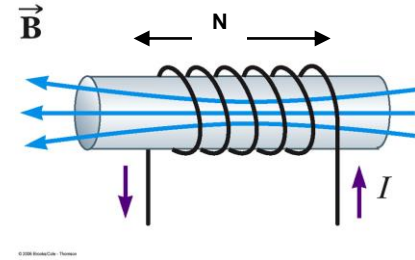
The magnitude of induced electric field grows linearly with r , then falls off as $1/r$ for $r > R$



Self-Inductance: Analogous to inertia

ANY magnetic flux change is resisted.

Changing current in a **single** coil induces a "back EMF" \mathcal{E}_{ind} in the **same** coil opposing the current change, an induced current i_{ind} , and a consistent induced field B_{ind} .



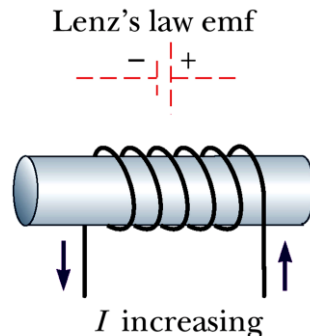
DISTINGUISH:

• **Mutual-induction:** di_1/dt in "transformer primary" also induces EMF and current i_2 in "linked" secondary coil (transformer principle).

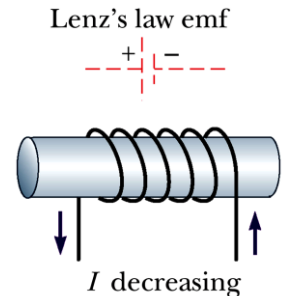
• **Self-induction** in a single Coil: di/dt produces "back EMF" due to Lenz & Faraday Laws: Φ_{ind} opposes $d\Phi/dt$ due to current change. \mathcal{E}_{ind} opposes di/dt .

- Changing current in a single coil causes magnetic field and flux created by this current to change in the same sense
- Flux Change induces flux opposing the change, along with opposing EMF and current.
- This back emf limits the rate of current (flux) change in the circuit

• For increasing current, back EMF limits the rate of increase



• For decreasing current, back EMF sustains the current



Inductance measures opposition to the rate of change of current

Definition of Self-inductance



Joseph Henry
1797 – 1878

Recall capacitance: depends only on geometry
It measures energy stored in the E field

$$C \equiv \frac{Q}{V}$$

Self-inductance depends only on coil geometry
It measures energy stored in the B field

$$L \equiv \frac{\text{linked flux}}{\text{unit current}}$$

number of turns \rightarrow

self-inductance \rightarrow

$$L \equiv \frac{N \Phi_B}{i}$$

flux through one turn depends on current & all N turns

cancels current dependence in flux above

SI unit of inductance:

$$1 \text{ Henry} \equiv 1 \text{ H.} \equiv 1 \text{ T.m}^2 / \text{Ampere} = 1 \text{ Weber} / \text{Ampere} \\ = 1 \text{ Volt.sec} / \text{Ampere} \quad (\Omega.\text{sec})$$

Why choose this definition?

Cross-multiply

$$Li = N \Phi_B$$

Take time derivative

$$L \frac{di}{dt} = N \frac{d\Phi_B}{dt} = - \mathcal{E}_L$$

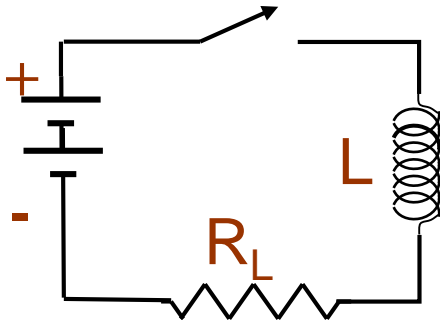


$$\mathcal{E}_L \equiv -L \frac{di}{dt}$$

- L contains all the geometry
- \mathcal{E}_L is the "back EMF"

Another form of Faraday's Law!

Example: Find the Self-Inductance of a solenoid



Field: $\mathbf{B} = \mu_0 i \mathbf{n}$ where $\mathbf{n} \equiv \frac{\mathbf{N}}{\ell} = \frac{\text{\# turns}}{\text{unit Length}}$

Flux in just one turn: $\Phi_B \equiv \mathbf{B} \mathbf{A} = \mu_0 i \frac{\mathbf{N} \mathbf{A}}{\ell}$

ALL N turns contribute to self-flux through ONE turn

Apply definition of self-inductance:

- N turns
- Area A
- Length ℓ
- Volume $V = A\ell$

$$\therefore L \equiv \frac{N \Phi_B}{i} = \mu_0 \frac{N^2 A}{\ell} = \mu_0 n^2 V$$

- Depends on geometry only, like capacitance.
- Proportional to N^2 !

Check: Same L if you start with Faraday's Law for F_B :

$$\mathcal{E}_{\text{ind}} = -N \frac{d\Phi_B}{dt}$$



for solenoid use Φ_B above

$$\mathcal{E}_{\text{ind}} = -N \cdot \left(\mu_0 \frac{N A}{\ell} \frac{di}{dt} \right) = \frac{-\mu_0 N^2 A}{\ell} \cdot \frac{di}{dt} \equiv -L \frac{di}{dt}$$

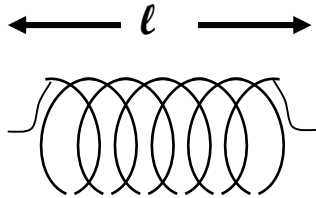
Note: Inductance per unit length has same dimensions as m_0

$$\frac{L}{\ell} = \mu_0 N^2 \frac{A}{\ell^2}$$

$$[\mu_0] = \frac{\text{T.m}}{\text{A.}} = \frac{\text{H}}{\text{m}}$$

Example: calculate self-inductance L for an ideal solenoid

$N = 1000$ turns, radius $r = 0.5$ m, length $\ell = 0.2$ m



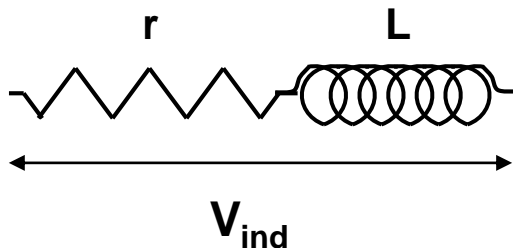
$$L = \frac{\mu_0 N^2 A}{\ell} = \frac{4\pi \times 10^{-7} \times 10^6 \times \pi \times (5 \times 10^{-2})^2}{0.2}$$

$$\therefore L = 49.4 \times 10^{-3} \text{ Henrys} = 49.4 \text{ milli - Henrys}$$

**Ideal inductor
(abstraction):**

- Internal resistance $r = 0$ (recall ideal battery)
- $B = 0$ outside
- $B = \mu_0 i n$ inside (ideal solenoid)

**Non-ideal inductors have
internal resistance:**

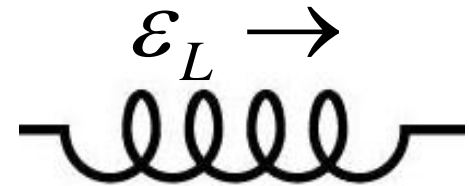


- $V_{\text{IND}} = \mathcal{E}_L - ir = \text{measured voltage}$
- Direction of ir depends on current
- Direction of \mathcal{E}_L depends on di/dt
- **If current i is constant, then induced $\mathcal{E}_L = 0$
Inductor behaves like a wire with resistance r**

Induced EMF in an Inductor

12 – 1: Which statement describes the **current** through the inductor below, if the induced EMF is as shown?

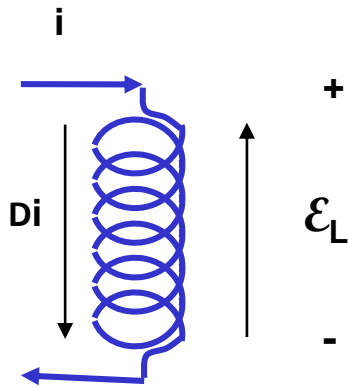
- A. Rightward and constant.
- B. Leftward and constant.
- C. Rightward and increasing.
- D. Leftward and decreasing.
- E. Leftward and increasing.



$$\mathcal{E}_L \equiv -L \frac{di}{dt}$$



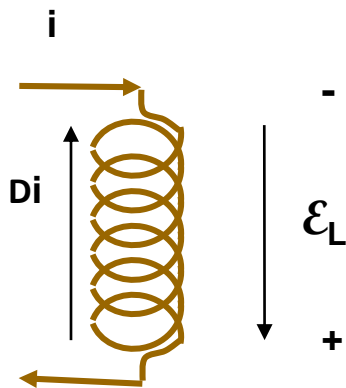
Lenz's Law applied to Back EMF



If i is increasing: $\frac{d\Phi_B}{dt} > 0$

$\therefore \mathcal{E}_L$ opposes increase in i

Power is being stored in B field of inductor



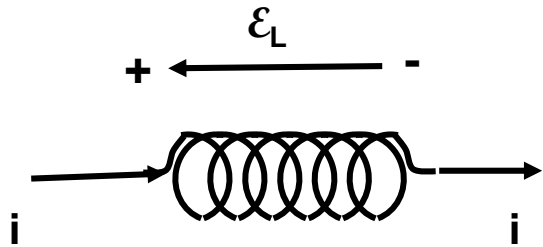
If i is decreasing: $\frac{d\Phi_B}{dt} < 0$

$\therefore \mathcal{E}_L$ opposes decrease in i

Power is being tapped from B field of inductor

What if CURRENT i is constant?

Example: Current I increases uniformly from 0 to 1 A. in 0.1 seconds. Find the induced voltage (back EMF) across a 50 mH (milli-Henry) inductance.



i defines positive direction

$\frac{di}{dt} > 0$ means that current i is increasing
and toward the right

Apply: $\epsilon_L = -L \frac{di}{dt}$

Substitute: $\frac{\Delta i}{\Delta t} = \frac{+1 \text{ Amp}}{0.1 \text{ sec}} = 10 \frac{\text{Amp}}{\text{sec}}$

$$\epsilon_L = -50 \text{ mH} \cdot 10 \frac{\text{Amp}}{\text{sec}} = -0.5 \text{ Volts}$$

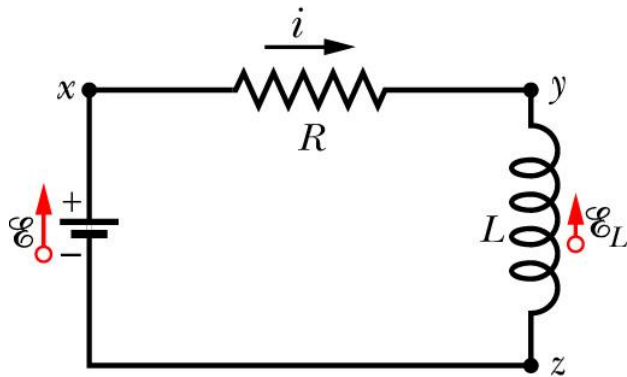
Negative result means that induced EMF is opposed to both di/dt and i .

Inductors in Circuits—The RL Circuit

- Inductors, sometimes called “coils”, are common circuit components.
- Insulated wire is wrapped around a core.
- They are mainly used in AC filters and tuned (resonant) circuits.

Analysis of series RL circuits:

- A battery with EMF \mathcal{E} drives a current around the loop, producing a back EMF \mathcal{E}_L in the inductor.
- Derive circuit equations: apply Kirchoff's loop rule, convert to differential equations (as for RC circuits) and solve.

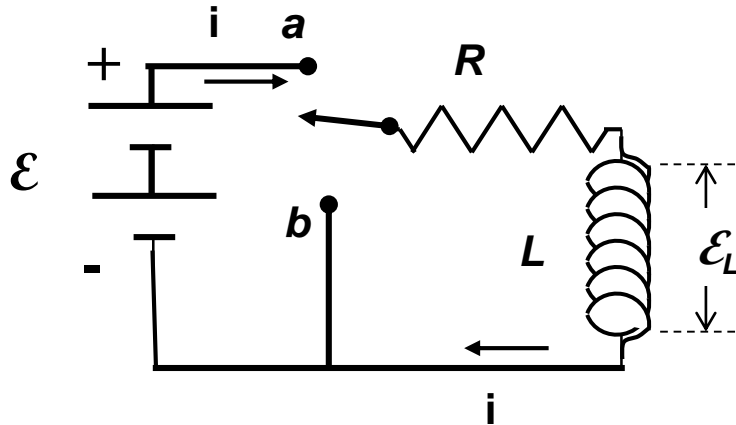


New rule: when traversing an inductor in the same direction as the assumed current, insert:

$$\mathcal{E}_L \equiv -L \frac{di}{dt}$$

copying

Series LR circuits



- Inductance & resistance + EMF
- Find time dependent behavior
- Use Loop Rule & Junction Rule
- Treat \mathcal{E}_L as an EMF along current

$$\mathcal{E}_L \equiv -L \frac{di}{dt}$$

ALWAYS

Given \mathcal{E} , R , L : Find i , \mathcal{E}_L , U_L for inductor as functions of time

Growth phase, switch to "a". Loop equation:

$$\mathcal{E} - iR - L \frac{di}{dt} = 0$$

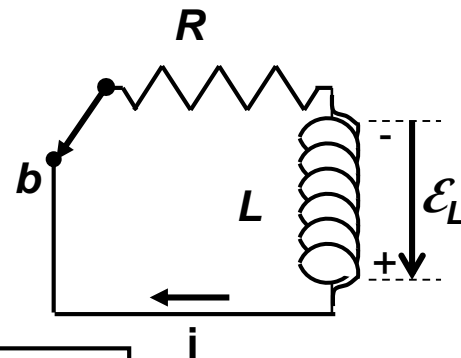
Decay phase, switch to "b", exclude \mathcal{E} ,
Loop equation:

$$-iR - L \frac{di}{dt} = 0$$

- i through R is clockwise and growing: \mathcal{E}_L opposes \mathcal{E}
- At $t = 0$, rapidly growing current but $i = 0$, $\mathcal{E}_L = \mathcal{E}$
 L acts like a broken wire
- As $t \rightarrow$ infinity, large stable current, $di/dt \rightarrow 0$
Back EMF $\mathcal{E}_L \rightarrow 0$, $i \rightarrow \mathcal{E}/R$,
 L acts like an ordinary wire
- Energy is stored in L & dissipated in R
- Energy stored in L now dissipated in R
- Current through R is still clockwise, but collapsing
- \mathcal{E}_L now acts like a battery maintaining current
- Current i at $t = 0$ equals \mathcal{E}/R
- Current $\rightarrow 0$ as $t \rightarrow$ infinity – energy depleted

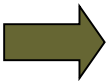
LR circuit: decay phase solution

- After growth phase equilibrium, switch from a to b, battery out
- Current $i_0 = \mathcal{E} / R$ initially still flowing CW through R
- Inductance tries to maintain current using stored energy
- Polarity of \mathcal{E}_L **reverses** versus growth. Eventually $\mathcal{E}_L \rightarrow 0$



Loop Equation is : $-iR + \mathcal{E}_L = 0$

Substitute : $\mathcal{E}_L(t) = -L \frac{di}{dt}$



Circuit Equation:

$$\frac{di}{dt} = -\frac{R}{L} i$$

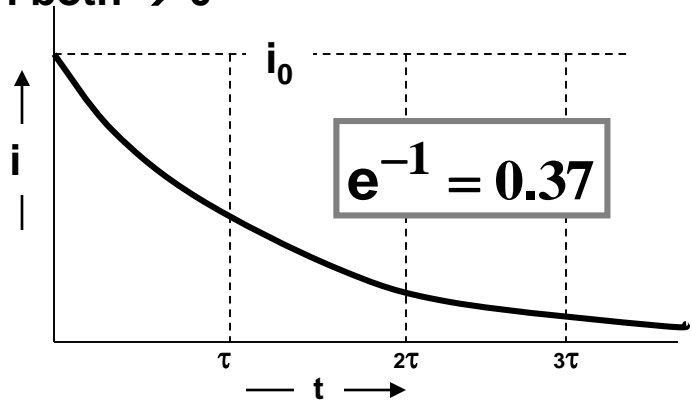
$di/dt < 0$
during decay,
opposite to
current

- First order differential equation with simple exponential solution
- At $t = 0$: large current implies large di / dt , so \mathcal{E}_L is large
- As $t \rightarrow$ infinity: current stabilizes, di / dt and current i both $\rightarrow 0$

Current decays exponentially:

$$i(t) = i_0 e^{-t/\tau_L} \quad i_0 \equiv \frac{\mathcal{E}}{R}$$

$$\tau_L \equiv L/R \equiv \text{inductivetime constant}$$



Back EMF \mathcal{E}_L and V_R decay exponentially:

$$\frac{di}{dt} = -\frac{\mathcal{E}}{R\tau_L} e^{-t/\tau_L} \Rightarrow$$

$$\mathcal{E}_L = +\mathcal{E} e^{-t/\tau_L}$$

$$V_R = -\mathcal{E}_L = -iR$$

Compare to RC circuit, decay

$$Q(t) = C\mathcal{E} e^{-t/RC}$$

$RC \equiv$ capacitive time constant

LR circuit: growth phase solution

Loop Equation is : $\mathcal{E} - iR + \mathcal{E}_L = 0$

Substitute : $\mathcal{E}_L(t) = -L \frac{di}{dt}$



Circuit Equation:

$$i + \frac{L}{R} \frac{di}{dt} = \frac{\mathcal{E}}{R}$$

- First order differential equation again - saturating exponential solutions
- As $t \rightarrow$ infinity, di/dt approaches zero, current stabilizes at $i_{\text{inf}} = \mathcal{E}/R$
- At $t = 0$: current is small, di/dt is large, back EMF opposes battery.

Current starts from zero, grows as a saturating exponential.

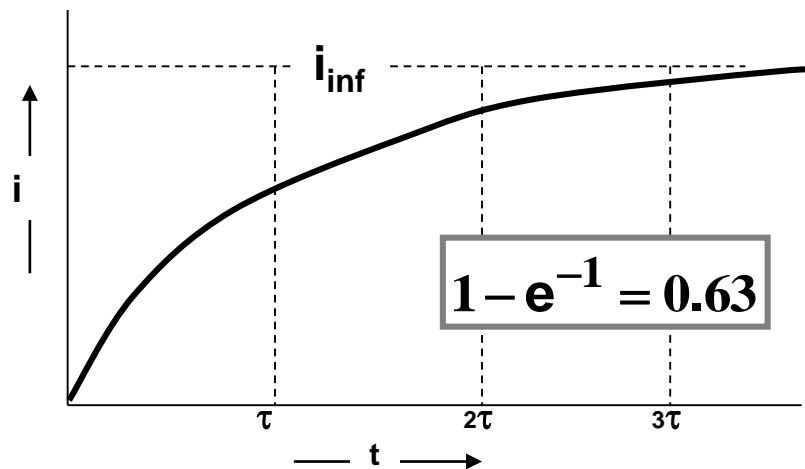
$$i(t) = i_{\text{inf}} \left(1 - e^{-t/\tau_L} \right) \quad i_{\text{inf}} \equiv \frac{\mathcal{E}}{R}$$
$$\tau_L \equiv L/R \equiv \text{inductive time constant}$$

- $i = 0$ at $t = 0$ in above equation $\rightarrow di/dt = \mathcal{E}/L$
fastest rate of change, largest back EMF

Back EMF \mathcal{E}_L decays exponentially

$$\frac{di}{dt} = \frac{\mathcal{E}}{R \tau_L} e^{-t/\tau_L} \Rightarrow \mathcal{E}_L = -\mathcal{E} e^{-t/\tau_L}$$

Voltage drop across resistor $V_R = -iR$



Compare to RC circuit, charging

$$Q(t) = C\mathcal{E} \left(1 - e^{-t/RC} \right)$$

$RC \equiv$ capacitive time constant

Example: For growth phase find back EMF \mathcal{E}_L as a function of time

Use growth phase solution $i(t) = \frac{\mathcal{E}}{R}(1 - e^{-t/\tau_L})$

At $t = 0$: current = 0

$$i(t = 0) = \frac{\mathcal{E}}{R}(1 - e^0) = 0$$

Back EMF is \sim to rate of change of current

Derivative: $\frac{di}{dt} = \frac{\mathcal{E}}{R} \frac{(-)(-)}{\tau_L} e^{-t/\tau_L}$ where $\tau_L = \frac{L}{R}$

$$\mathcal{E}_L = -L \frac{di}{dt} = -\mathcal{E} e^{-t/\tau_L}; \quad \text{At } t = 0: \mathcal{E}_L = -\mathcal{E}$$

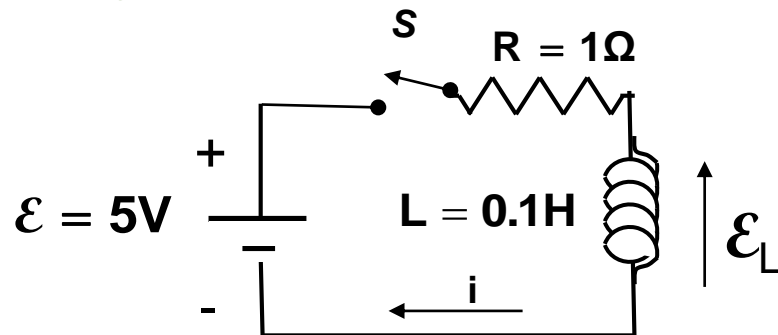
- Back EMF \mathcal{E}_L equals the battery potential causing current i to be 0 at $t = 0$
- iR drop across $R = 0$
- **L acts like a broken wire at $t = 0$**

After a very long (infinite) time:

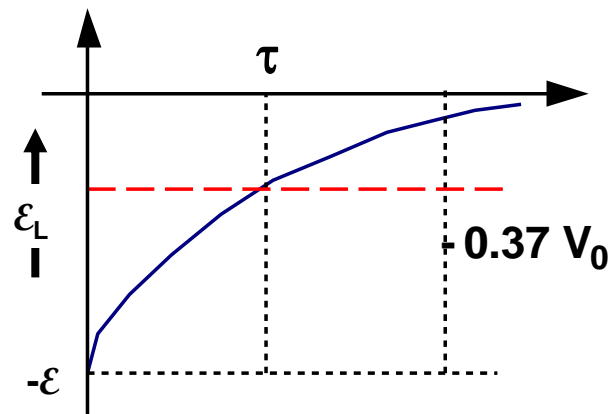
- **Current stabilizes, back EMF=0**

$$i_\infty = \frac{\mathcal{E}}{R} = 5A$$

- **L acts like an ordinary wire at $t = \text{infinity}$**



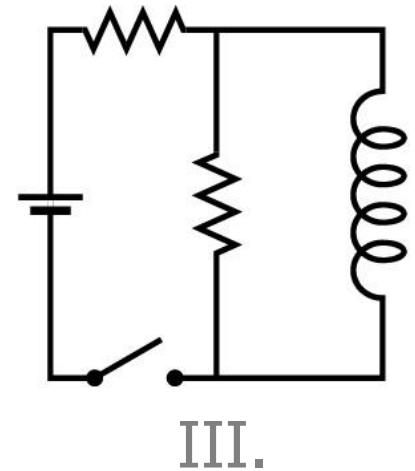
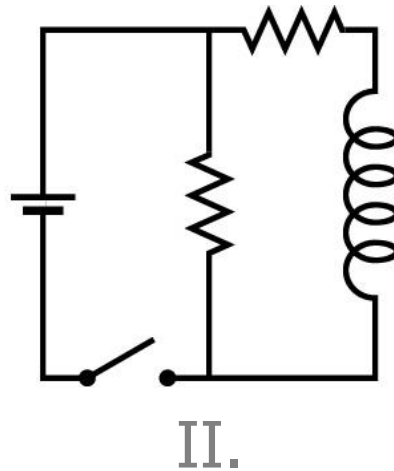
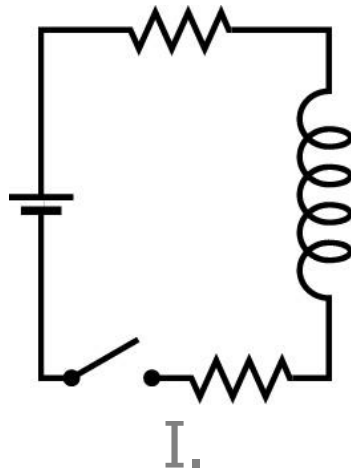
$$\tau_L = \frac{L}{R} = \frac{0.1H}{1\Omega} = 0.1 \text{ sec}$$



Current through the battery - 1

12 – 2: The three loops below have identical inductors, resistors, and batteries. Rank them in terms of current through the battery just after the switch is closed, greatest first.

- A. I, II, III.
- B. II, I, III.
- C. III, I, II.
- D. III, II, I.
- E. II, III, I.



Hint: what kind of wire does L act like?

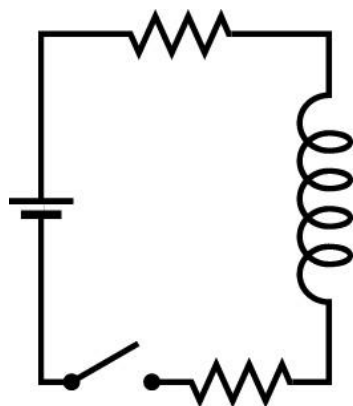
$$i(t) = i_{\text{inf}}(1 - e^{-t/\tau_L}) \quad i_{\text{inf}} \equiv \frac{\mathcal{E}}{R_{\text{eq}}} \quad \tau_L \equiv L/R_{\text{eq}} \equiv \text{inductive time constant}$$



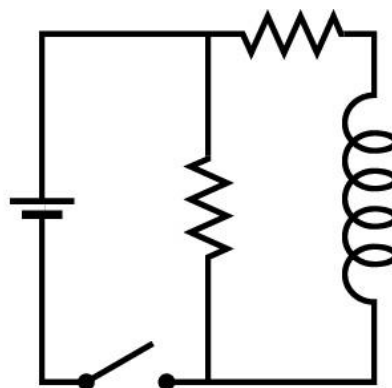
Current through the battery - 2

12 – 3: The three loops below have identical inductors, resistors, and batteries. Rank them in terms of current through the battery a long time after the switch is closed, greatest first.

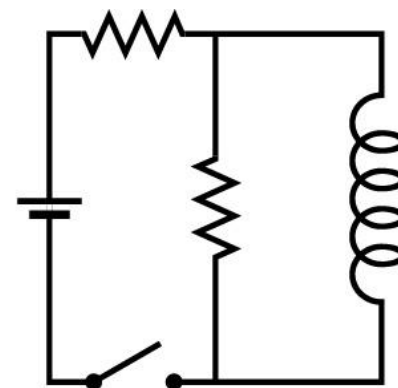
- A. I, II, III.
- B. II, I, III.
- C. III, I, II.
- D. III, II, I.
- E. II, III, I.



I.



II.



III.

Hint: what kind of wire does L act like?

$$i(t) = i_{\text{inf}} \left(1 - e^{-t/\tau_L} \right) \quad i_{\text{inf}} \equiv \frac{\mathcal{E}}{R_{\text{eq}}} \quad \tau_L \equiv L/R_{\text{eq}} \equiv \text{inductive time constant}$$



Summarizing RL circuits growth phase

- When t is large: $i = \frac{\mathcal{E}}{R}$ Inductor acts like a wire.

$$i = \frac{\mathcal{E}}{R}(1 - e^{-Rt/L})$$

- When t is small (zero), $i = 0$. Inductor acts like an open circuit.

- The current starts from zero and increases up to a maximum of $i = \mathcal{E}/R$ with a time constant given by

$$\tau_L = \frac{L}{R} \quad \text{Inductive time constant}$$

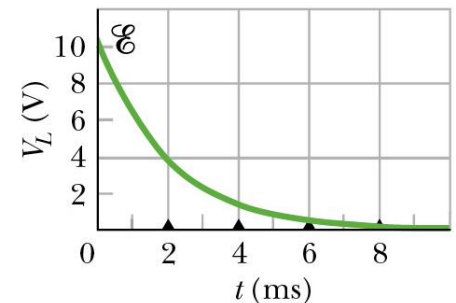
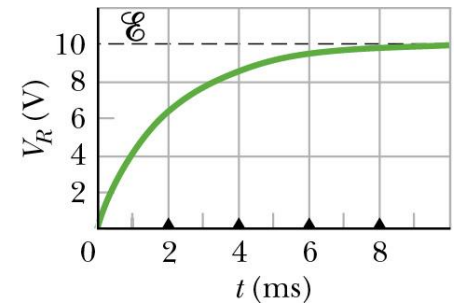
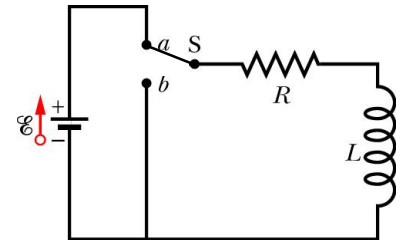
Compare: $\tau_C = RC$ Capacitive time constant

- The voltage across the resistor is

$$V_R = -iR = -\mathcal{E}(1 - e^{-Rt/L})$$

- The voltage across the inductor is

$$V_L = -\mathcal{E} - V_R = -\mathcal{E} + \mathcal{E}(1 - e^{-Rt/L}) = -\mathcal{E} e^{-Rt/L}$$



Summarizing RL circuits decay phase

The switch is thrown from *a* to *b*

- Kirchoff's Loop Rule for growth was:

$$\varepsilon - iR - L \frac{di}{dt} = 0$$

- Now it is:

$$iR + L \frac{di}{dt} = 0$$

- The current decays exponentially:

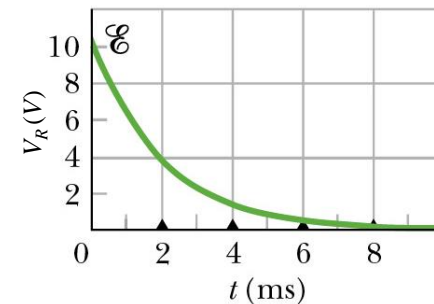
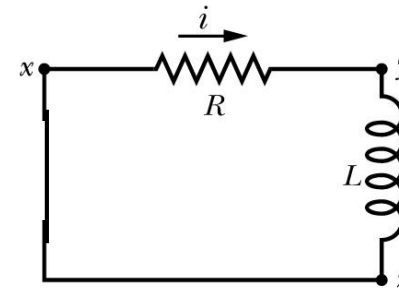
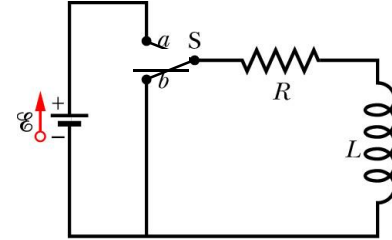
$$i = \frac{\varepsilon}{R} e^{-Rt/L}$$

- Voltage across resistor also decays:

$$V_R = -iR = -\varepsilon e^{-Rt/L}$$

- Voltage across inductor:

$$V_L = +L \frac{di}{dt} = +L \frac{\varepsilon}{R} \frac{d}{dt} e^{-Rt/L} = -\varepsilon e^{-Rt/L}$$



Energy stored in inductors

Recall: Capacitors store energy in their electric fields

$U_E \equiv$ electrostatic potential energy

$$U_E \equiv \frac{1}{2} \frac{Q^2}{C} = \frac{1}{2} CV^2$$

$u_E \equiv$ electrostatic energy density

$$u_E \equiv \frac{U_E}{\text{Volume}} = \frac{1}{2} \epsilon_0 E^2$$

derived
using p-p
capacitor

Inductors also store energy, but in their magnetic fields

Magnetic PE Derivation - consider power into or from inductor

$$\text{Power} \equiv \frac{dU_B}{dt} \equiv \mathcal{E}i = Li \frac{di}{dt} \Rightarrow U_B = \int dU_B = L \int i di = \frac{1}{2} Li^2$$

$U_B \equiv$ magnetic potential energy

$$U_B = \frac{1}{2} Li^2$$

$u_B \equiv$ magnetic energy density

$$u_B \equiv \frac{U_B}{\text{Volume}} = \frac{B^2}{2\mu_0}$$

derived
using
solenoid

- U_B grows as current increases, absorbing energy
- When current is stable, U_B and u_B are constant
- U_B diminishes when current decreases. It powers the persistent EMF during the decay phase for the inductor

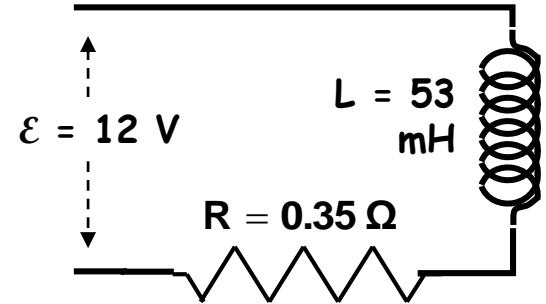
Sample problem: energy storage in magnetic field of an inductor during growth phase

a) At equilibrium (infinite time) how much energy is stored in the coil?

$$i_{\infty} = \frac{\mathcal{E}}{R} \quad (\text{Coil acts like a wire}) = \frac{12}{0.35} = 34.3 \text{ A}$$

$$U_{\infty} = \frac{1}{2} L \cdot i_{\infty}^2 = \frac{1}{2} \times 53 \times 10^{-3} \times (34.3)^2$$

$$U_{\infty} = 31 \text{ J}$$



b) How long ($t_{1/2}$) does it take to store half of this energy?

$$\text{At } t_{1/2} : U_B = \frac{1}{2} U_{\infty} \Rightarrow \frac{1}{2} L i_{1/2}^2 = \frac{1}{2} \cdot \frac{1}{2} \cdot L \cdot i_{\infty}^2 \Rightarrow i_{1/2} = \frac{i_{\infty}}{\sqrt{2}}$$



$$i_{1/2} = \frac{i_{\infty}}{\sqrt{2}} = i_{\infty} (1 - e^{-t_{1/2}/\tau_L})$$

$$e^{-t_{1/2}/\tau_L} = \frac{\sqrt{2}}{\sqrt{2}} - \frac{1}{\sqrt{2}} = 1 - 1/\sqrt{2}$$

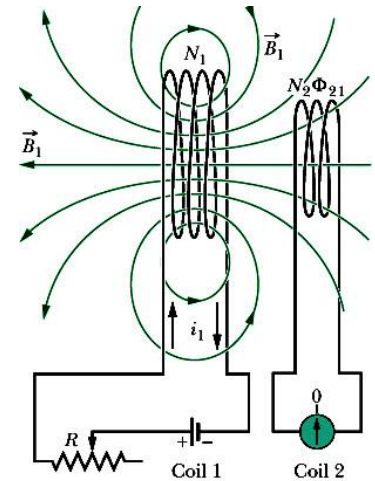
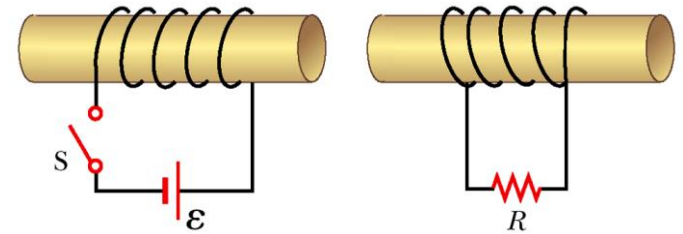
take natural log of both sides

$$t_{1/2} = -\tau_L \ln(1 - 1/\sqrt{2}) = 1.23 \tau$$

$$\tau_L \equiv L/R = 53 \times 10^{-3} / 0.35 = 0.15 \text{ sec.}$$

Mutual Inductance

- Example: a pair of co-axial coils
- di/dt in the first coil induces current in the second coil, in addition to self-induced effects.
- M_{21} depends on *geometry only*, as did L and C
- *Changing current in primary (i_1) creates varying flux through coil 2 \rightarrow induced EMF in coil 2*



Definition:

number of turns
in coil 2

mutual
inductance

$$M_{21} \equiv \frac{N_2 \Phi_{21}}{i_1}$$

flux through one turn
of coil 2 due to all N_1
turns of coil 1
current in coil 1

cross-multiply

$$M_{21} i_1 = N_2 \Phi_{21}$$

time derivative

$$M_{21} \frac{di_1}{dt} = N_2 \frac{d\Phi_{21}}{dt}$$



$$\mathcal{E}_2 \equiv -M_{21} \frac{di_1}{dt}$$

- M_{21} contains all the geometry
- \mathcal{E}_2 is EMF induced in 2 by 1

Another form of Faraday's Law!

The smaller coil radius determines how much flux is linked, so.....

$$\mathcal{E}_1 \equiv -M_{12} \frac{di_2}{dt}$$

$$M_{12} = M_{21} \equiv M$$

proof not obvious

Calculating the mutual inductance M

Let coil 1 (outer) be a short loop of N_1 turns, not a long Solenoid

$B_1 \equiv$ Field inside loop 1 near center

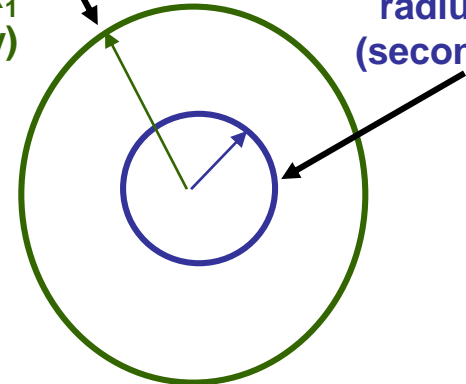
$$= \frac{\mu_0 i_1 N_1}{2R_1} \quad (\text{assume uniform})$$

Flux through Loop 2 – depends on area A_2 & B_1

$$\Phi_{21} = B_1 A_2 = \frac{\mu_0 i_1 N_1}{2R_1} \pi R_2^2 \quad (\text{foreach loop in coil 2})$$

large coil 1
 N_1 turns
radius R_1
(primary)

small coil 2
 N_2 turns
radius R_2
(secondary)



If current in Loop 1 is changing:

$$\mathcal{E}_2 \equiv \text{induced voltage in loop 2} = -N_2 \frac{d\Phi_{21}}{dt} = -\frac{\mu_0 N_1 N_2 \pi R_2^2}{2R_1} \frac{di_1}{dt} \equiv -M_{21} \frac{di_1}{dt}$$

$$\therefore M_{21} \equiv M = \frac{\mu_0 N_1 N_2}{2R_1} \pi R_2^2$$

smaller radius (R_2)
determines the linkage

Summarizing
results for mutual
inductance:

$$\mathcal{E}_2 = -M_{21} \frac{di_1}{dt} \quad M_{21} = \frac{N_2 \Phi_{21}}{i_1}$$

$$M_{21} = M = \frac{N_2 \Phi_{21}}{i_1} = \frac{N_1 \Phi_{12}}{i_2}$$

Summary: Lecture 12 Chapter 30 – Induction II – LR Circuits

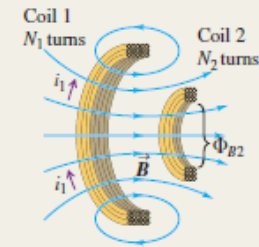
CHAPTER 30 SUMMARY

Mutual inductance: When a changing current i_1 in one circuit causes a changing magnetic flux in a second circuit, an emf \mathcal{E}_2 is induced in the second circuit. Likewise, a changing current i_2 in the second circuit induces an emf \mathcal{E}_1 in the first circuit. If the circuits are coils of wire with N_1 and N_2 turns, the mutual inductance M can be expressed in terms of the average flux Φ_{B2} through each turn of coil 2 caused by the current i_1 in coil 1, or in terms of the average flux Φ_{B1} through each turn of coil 1 caused by the current i_2 in coil 2. The SI unit of mutual inductance is the henry, abbreviated H. (See Examples 30.1 and 30.2.)

$$\mathcal{E}_2 = -M \frac{di_1}{dt} \quad \text{and}$$

$$\mathcal{E}_1 = -M \frac{di_2}{dt} \quad (30.4)$$

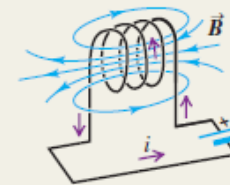
$$M = \frac{N_2 \Phi_{B2}}{i_1} = \frac{N_1 \Phi_{B1}}{i_2} \quad (30.5)$$



Self-inductance: A changing current i in any circuit causes a self-induced emf \mathcal{E} . The inductance (or self-inductance) L depends on the geometry of the circuit and the material surrounding it. The inductance of a coil of N turns is related to the average flux Φ_B through each turn caused by the current i in the coil. An inductor is a circuit device, usually including a coil of wire, intended to have a substantial inductance. (See Examples 30.3 and 30.4.)

$$\mathcal{E} = -L \frac{di}{dt} \quad (30.7)$$

$$L = \frac{N \Phi_B}{i} \quad (30.6)$$

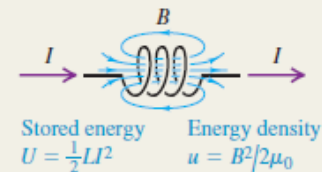


Magnetic-field energy: An inductor with inductance L carrying current I has energy U associated with the inductor's magnetic field. The magnetic energy density u (energy per unit volume) is proportional to the square of the magnetic field magnitude. (See Example 30.5.)

$$U = \frac{1}{2} LI^2 \quad (30.9)$$

$$u = \frac{B^2}{2\mu_0} \quad (\text{in vacuum}) \quad (30.10)$$

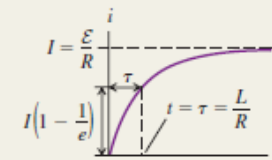
$$u = \frac{B^2}{2\mu} \quad (\text{in a material with magnetic permeability } \mu) \quad (30.11)$$



R-L circuits: In a circuit containing a resistor R , an inductor L , and a source of emf, the growth and decay of current are exponential. The time constant τ is the time required for the current to approach within a fraction $1/e$ of its final value. (See Examples 30.6 and 30.7.)

$$\tau = \frac{L}{R}$$

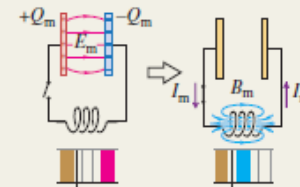
(30.16)



L-C circuits: A circuit that contains inductance L and capacitance C undergoes electrical oscillations with an angular frequency ω that depends on L and C . This is analogous to a mechanical harmonic oscillator, with inductance L analogous to mass m , the reciprocal of capacitance $1/C$ to force constant k , charge q to displacement x , and current i to velocity v_x . (See Examples 30.8 and 30.9.)

$$\omega = \sqrt{\frac{1}{LC}}$$

(30.22)



L-R-C series circuits: A circuit that contains inductance, resistance, and capacitance undergoes damped oscillations for sufficiently small resistance. The frequency ω' of damped oscillations depends on the values of L , R , and C . As R increases, the damping increases; if R is greater than a certain value, the behavior becomes overdamped and no longer oscillates. (See Example 30.10.)

$$\omega' = \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}$$

(30.29)

