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Multiple Testing in a Two-Stage Adaptive Design With Combination Tests Controlling FDR

Sanat K. SARKAR, Jingjing CHEN, and Wenge GUO

Testing multiple null hypotheses in two stages to decide which of these can be rejected or accepted at the first stage and which should be followed up for further testing having had additional observations is of importance in many scientific studies. We develop two procedures, each with two different combination functions, Fisher’s and Simes’, to combine p-values from two stages, given prespecified boundaries on the first-stage p-values in terms of the false discovery rate (FDR) and controlling the overall FDR at a desired level. The FDR control is proved when the pairs of first- and second-stage p-values are independent and those corresponding to the null hypotheses are identically distributed as a pair \((p_1, p_2)\) satisfying the p-claud property. We did simulations to show that (1) our two-stage procedures can have significant power improvements over the first-stage Benjamini–Hochberg (BH) procedure compared to the improvement offered by the ideal BH procedure that one would have used had the second stage data been available for all the hypotheses, and can continue to control the FDR under some dependence situations, and (2) can offer considerable cost savings compared to the ideal BH procedure. The procedures are illustrated through a real gene expression data. Supplementary materials for this article are available online.

KEY WORDS: Early acceptance and rejection boundaries; False discovery rate; Single-stage BH procedure; Stepdown test; Stepup test; Two-stage multiple testing.

1. INTRODUCTION

Gene association or expression studies that usually involve a large number of endpoints (i.e., genetic markers) are often quite expensive. Such studies conducted in a multistage adaptive design setting can be cost effective and efficient, since genes are screened in early stages and selected genes are further investigated in later stages using additional observations. Multiplicity in simultaneous testing of hypotheses associated with the endpoints in a multistage adaptive design is an important issue, as in a single-stage design. For addressing the multiplicity concern, controlling the familywise error rate (FWER), the probability of at least one Type I error among all hypotheses, is a commonly applied concept. However, these studies are often explorative, so controlling the false discovery rate (FDR), which is the expected proportion of Type I errors among all rejected hypotheses, is more appropriate than controlling the FWER (Weller et al. 1998; Benjamini and Hochberg 1995; Storey and Tibshirani 2003). Moreover, with large number of hypotheses typically being tested in these studies, better power can be achieved in a multiple testing method under the FDR framework than under the more conservative FWER framework.

Although adaptive designs with multiple endpoints have been considered in the literature under the FDR framework (Zehetmayer, Bauer, and Posch 2005, 2008; Victor and Hommel 2007; Posch, Zehetmayer, and Bauer 2009), the theory presented so far (see, e.g., Victor and Hommel 2007) toward developing an FDR controlling procedure in the setting of a two-stage adaptive design with combination tests does not seem to be as simple as one would hope for. Moreover, it does not allow setting boundaries on the first stage p-values in terms of FDR and operate in a manner that would be a natural extension of standard single-stage FDR controlling methods, like the BH (Benjamini and Hochberg 1995) or methods related to it, from a single-stage to a two-stage design setting. So, we consider the following to be our main problem in this article:

To construct an FDR controlling procedure for simultaneous testing of the null hypotheses associated with multiple endpoints in the following two-stage adaptive design setting: The hypotheses are sequentially screened at the first stage as rejected or accepted based on prespecified boundaries on their p-values in terms of the FDR, and those that are left out at the first stage are again sequentially tested at the second stage having determined their second-stage p-values based on additional observations and then using the combined p-values from the two stages through a combination function.

We propose two FDR controlling procedures, one extending the original single-stage BH procedure, which we call the BH-TSADC Procedure (BH-type procedure for two-stage adaptive design with combination tests), and the other extending an adaptive version of the single-stage BH procedure incorporating an estimate of the number of true null hypotheses, which we call the Plug-In BH-TSADC Procedure, from single-stage to a two-stage setting. Let \((p_{11}, p_{22})\) be the pair of first- and second-stage p-values corresponding to the \(i\)th null hypothesis. We provide a theoretical proof of the FDR control of the proposed procedures under the assumption that the \((p_{11}, p_{22})\)’s are independent and those corresponding to the true null hypotheses are identically distributed as \((p_1, p_2)\) satisfying the p-claud property (Brannath, Posch, and Bauer 2002), and some standard assumption on the combination function. We consider two special types of combination function, Fisher’s and Simes’, which are often used in multiple testing applications, and present explicit formulas for

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probabilities involving them that would be useful to carry out the proposed procedures at the second stage either using critical values that can be determined before observing the \( p \)-values or based on estimated FDR's that can be obtained after observing the \( p \)-values.

We carried out extensive simulations to investigate how well our proposed procedures perform in terms of FDR control and power under independence with respect to the number of true null hypotheses and the selection of early stopping boundaries. Simulations were also performed (1) to examine the cost savings our procedures can potentially offer relative to the maximum possible cost incurred ideally by the BH method one would have used had the second stage data been available for all the endpoints, and (2) to evaluate whether or not the proposed procedures can continue to control the FDR under different types of (positive) dependence among the underlying test statistics.

Results on the FDR control in a single-stage design in Section 2, present our proposed two-stage procedures in Section 3, discuss the results of simulations studies in Section 4, and illustrate the real data application in Section 5. We conclude the article in Section 6 with some remarks on the present work and brief discussions on some future research topics including those related to designing an FDR-based two-stage study.

Proofs of our main theorem and propositions are given in Appendix.

2. CONTROLLING THE FDR IN A SINGLE-STAGE DESIGN

Suppose that there are \( m \) endpoints and the corresponding null hypotheses \( H_i, i = 1, \ldots, m \), are to be simultaneously tested based on their respective \( p \)-values \( p_i, i = 1, \ldots, m \), obtained in a single-stage design. The FDR of a multiple testing method that rejects \( R \) and falsely rejects \( V \) null hypotheses is \( E(FDP) \), where \( FDP = V/\max(R, 1) \) is the false discovery proportion. Multiple testing is often carried out using a stepwise procedure defined in terms of \( p_{(i)} \leq \cdots \leq p_{(m)} \), the ordered \( p \)-values.

With \( H_0 \) the null hypothesis corresponding to \( p_{(i)} \), a stepup procedure with critical values \( \gamma_1 \leq \cdots \leq \gamma_m \) rejects \( H_0 \) for all \( i \leq k = \max\{j : p_{(j)} \leq \gamma_j \} \), provided the maximum exists; otherwise, it accepts all null hypotheses. A stepdown procedure, on the other hand, with these same critical values rejects \( H_0 \) for all \( i \leq k = \max\{j : p_{(i)} \leq \gamma_i \text{ for all } i \leq j \} \), provided the maximum exists, otherwise, accepts all null hypotheses. The following are formulas for the FDR’s of a stepup or single-step procedure (when the critical values are same in a stepup procedure) and a stepdown procedure in a single-stage design, which can guide us in developing stepwise procedures controlling the FDR in a two-stage design. We will use the notation \( \text{FDR}_1 \) for the FDR of a procedure in a single-stage design.

Result 1. (Sarkar 2008). Consider a stepup or stepdown method for testing \( m \) null hypotheses based on their \( p \)-values \( p_i, i = 1, \ldots, m \), and critical values \( \gamma_1 \leq \cdots \leq \gamma_m \) in a single-stage design. The FDR of this method is given by

\[
\text{FDR}_1 \leq \sum_{i \in J_0} E \left[ \frac{I(p_i \leq \gamma_{R^{-1}_i}(\gamma_1, \ldots, \gamma_m) + 1)}{R_{m-1}(\gamma_2, \ldots, \gamma_m) + 1} \right],
\]

with the equality holding in the case of stepup method, where \( I \) is the indicator function, \( J_0 \) is the set of indices of the true null hypotheses, and \( R_{m-1}(\gamma_2, \ldots, \gamma_m) \) is the number of rejections in testing the \( m - 1 \) null hypotheses other than \( H_i \) based on their \( p \)-values and using the same type of the stepwise method with the critical values \( \gamma_2 \leq \cdots \leq \gamma_m \).

With \( p_i \) having the cdf \( F(u) \) when \( H_i \) is true, the FDR of a stepup or stepdown method with the thresholds \( \gamma_i, i = 1, \ldots, m \), under independence of the \( p \)-values, satisfies the following:

\[
\text{FDR}_1 \leq \sum_{i \in J_0} E \left[ \frac{F(Y_{R^{-1}_i}(\gamma_1, \ldots, \gamma_m) + 1)}{R_{m-1}(\gamma_2, \ldots, \gamma_m) + 1} \right].
\]

When \( F \) is the cdf of \( U(0, 1) \) and these thresholds are chosen as \( \gamma_i = i\alpha/m, i = 1, \ldots, m \), the FDR equals \( \pi_0 \alpha/m \) for the stepup and is less than or equal to \( \pi_0 \alpha/m \) for the stepdown method, where \( \pi_0 \) is the proportion of true nulls, and hence the FDR is controlled at \( \alpha \). This stepup method is the so-called BH method (Benjamini and Hochberg 1995), the most commonly used FDR controlling procedure in a single-stage design. The FDR is bounded above by \( \pi_0 \alpha/m \) for the BH as well as its stepdown analog under certain type of positive dependence condition among the \( p \)-values (Benjamini and Yekutieli 2001; Sarkar 2002, 2008).

The idea of improving the FDR control of the BH method by plugging into it a suitable estimate \( \hat{\pi}_0 \) of \( \pi_0 \), that is, by considering the modified \( p \)-values \( \hat{p}_0 p_i \), rather than the original \( p \)-values, in the BH method, was introduced by Benjamini and Hochberg (2000), which was later brought into the estimation-based approach to controlling the FDR by Storey (2002). A number of such plugged-in versions of the BH method with proven and improved FDR control mostly under independence have been put forward based on different methods of estimating \( \hat{\pi}_0 \) (e.g., Storey, Taylor, and Siegmund 2004; Benjamini, Krieger, and Yekutieli 2006; Sarkar 2008; Blanchard and Roquain 2009; Gavrilov, Benjamini, and Sarkar 2009).
CONTROLLING THE FDR IN A TWO-STAGE ADAPTIVE DESIGN

Now suppose that the $m$ null hypotheses $H_i$, $i = 1, \ldots, m$, are to be simultaneously tested in a two-stage adaptive design setting. When testing a single hypothesis, say $H_i$, the theory of two-stage combination test can be described as follows: given $p_{1i}$, the $p$-value available for $H_i$ at the first stage, and two constants $\lambda < \lambda'$, make an early decision regarding the hypothesis by rejecting it if $p_{1i} \leq \lambda$, accepting it if $p_{1i} > \lambda'$, and continuing to test it at the second stage if $\lambda < p_{1i} \leq \lambda'$. At the second stage, combine $p_i$ with the additional $p$-value $p_{2i}$ available for $H_i$ using a combination function $C(p_{1i}, p_{2i})$ and reject $H_i$ if $C(p_{1i}, p_{2i}) \leq \gamma$, for some constant $\gamma$. The constants $\lambda$, $\lambda'$, and $\gamma$ are determined subject to a control of the Type I error rate at a prespecified level by the test.

For simultaneous testing, we consider a natural extension of this theory from single to multiple testing. More specifically, given the first-stage $p$-value $p_{1i}$ corresponding to $H_i$ for $i = 1, \ldots, m$, we first determine two thresholds $0 \leq \hat{\lambda} < \hat{\lambda}' \leq 1$, stochastic or nonstochastic, and make an early decision regarding the hypotheses at this stage by rejecting $H_i$ if $p_{1i} \leq \hat{\lambda}$, accepting $H_i$ if $p_{1i} > \hat{\lambda}'$, and continuing to test $H_i$ at the second stage if $\hat{\lambda} < p_{1i} \leq \hat{\lambda}'$. At the second stage, we use the additional $p$-value $p_{2i}$ available for a follow-up hypothesis $H_i$ and combine it with $p_{1i}$ using the combination function $C(p_{1i}, p_{2i})$. The final decision is taken on the follow-up hypotheses at the second stage by determining another threshold $\hat{\gamma}$, again stochastic or nonstochastic, and by rejecting the follow-up hypothesis $H_i$ if $C(p_{1i}, p_{2i}) \leq \hat{\gamma}$. Both first-stage and second-stage thresholds are to be determined in such a way that the overall FDR is controlled at the desired level $\alpha$.

Let $p_{1(i)} \leq \cdots \leq p_{1(m)}$ be the ordered versions of the first-stage $p$-values, with $H_{1(i)}$ being the null hypotheses corresponding to $p_{1(i)}, i = 1, \ldots, m$, and $q_1 = C(p_{1(i)}, p_{2(i)})$. We describe in the following a general multiple testing procedure based on the above theory, before proposing our FDR controlling procedures that will be of this type.

A General Stepwise Procedure.

1. For two nondecreasing sequences of constants $\lambda_1 \leq \cdots \leq \lambda_m$ and $\lambda'_1 \leq \cdots \leq \lambda'_m$, with $\lambda_i < \lambda'_i$ for all $i = 1, \ldots, m$, and the first-stage $p$-values $p_{1i}, i = 1, \ldots, m$, define two thresholds as follows: $R_1 = \max\{1 \leq i \leq m : p_{1(i)} \leq \lambda_i\}$ for all $1 \leq i \leq l$ and $S_1 = \max\{1 \leq i \leq m : p_{1(i)} \leq \lambda'_i\}$, where $0 \leq R_1 \leq S_1 \leq m$ and $R_1$ or $S_1$ equals zero if the corresponding maximum does not exist. Reject $H_{1(i)}$ for all $i \leq R_1$, accept $H_{1(i)}$ for all $i > S_1$, and continue testing $H_{1(i)}$ at the second stage for all $i$ such that $R_1 < i \leq S_1$.

2. At the second stage, consider $q_{1(i)}, i = 1, \ldots, S_1 - R_1$, the ordered versions of the combined $p$-values $q_i = C(p_{1(i)}, p_{2(i)}), i = 1, \ldots, S_1 - R_1$, for the follow-up null hypotheses, and find $R_2(R_1, S_1) = \max\{1 \leq i \leq S_1 - R_1 : q_{1(i)} \leq \gamma_{R_1+S_1}\}$, given another nondecreasing sequence of constants $\gamma_{1(i)} \leq \cdots \leq \gamma_{S_1}$, for every fixed $r_1 < s_1$. Reject the follow-up null hypothesis $H_{1(i)}$ corresponding to $q_{1(i)}$ for all $i \leq R_2$ if this maximum exists, otherwise, reject none of the follow-up null hypotheses.

Remark 1. We should point out that the above two-stage procedure screens out the null hypotheses at the first stage by accepting those with relatively large $p$-values through a stepup procedure and by rejecting those with relatively small $p$-values through a stepdown procedure. At the second stage, it applies a stepup procedure to the combined $p$-values. Conceptually, one could have used any type of multiple testing procedure to screen out the null hypotheses at the first stage and to test the follow-up null hypotheses at the second stage. However, the particular types of stepwise procedure we have chosen at the two stages provide flexibility in terms of developing a formula for the FDR and eventually determining explicitly the thresholds we need to control the FDR at the desired level.

Let $V_1$ and $V_2$ denote the total numbers of falsely rejected among all the $R_1$ null hypotheses rejected at the first stage and the $R_2$ follow-up null hypotheses rejected at the second stage, respectively, in the above procedure. Then, the overall FDR in this two-stage procedure is given by

$$\text{FDR}_{12} = \mathbb{E}\left[\frac{V_1 + V_2}{\max\{R_1 + R_2, 1\}}\right].$$

The following theorem (to be proved in Appendix) will guide us in determining the first- and second-stage thresholds in the above procedure that will provide a control of $\text{FDR}_{12}$ at the desired level. This is the procedure that will be one of those we propose in this article. Before stating the theorem, we need to define the following notations.

- $R_{1(i)}^\text{(-i)}$: Defined as $R_1$ in terms of the $m - 1$ first-stage $p$-values $\{p_{11}, \ldots, p_{1m}\} \setminus \{p_{1i}\}$ and the sequence of constants $\lambda_2 \leq \cdots \leq \lambda_m$.
- $S_{1(i)}^\text{(-i)}$: Defined as $S_1$ in terms of $\{p_{11}, \ldots, p_{1m}\} \setminus \{p_{1i}\}$ and the sequence of constants $\lambda'_2 \leq \cdots \leq \lambda'_m$.
- $R_{1(i)}^\text{(-i)}$: Defined as $R_1$ in terms of $\{p_{11}, \ldots, p_{1m}\} \setminus \{p_{1i}\}$ and the sequence of constants $\lambda_1 \leq \cdots \leq \lambda_{m-1}$.
- $R_{1(i)}^\text{(-i)}$: Defined as $R_2$ with $R_1$ replaced by $R_{1(i)}^\text{(-i)}$ and $S_1$ replaced by $S_{1(i)}^\text{(-i)} + 1$ and noting the number of rejected follow-up null hypotheses based on all the combined $p$-values except the $q_i$ and the critical values other than the first one; that is,

$$R_{1(i)}^\text{(-i)} \equiv R_{1(i)}^\text{(-i)}(R_{1(i)}^\text{(-i)}, S_{1(i)}^\text{(-i)} + 1) = \max\{1 \leq j \leq S_{1(i)}^\text{(-i)} - R_{1(i)}^\text{(-i)} : q_{1(j)}^\text{(-i)} \leq \gamma_{R_1 + j + 1, S_1(i) + 1}\},$$

where $q_{1(j)}^\text{(-i)}$s are the ordered versions of the combined $p$-values for the follow-up null hypotheses except $q_i$.

Theorem 1. The FDR of the above general multiple testing procedure satisfies the following inequality:

$$\text{FDR}_{12} \leq \sum_{i \in J_0} \mathbb{E}\left[\frac{I(p_{1i} \leq \lambda_{R_{1(i)}^\text{(-i)} + 1}}{R_{1(i)}^\text{(-i)} + 1}\right] + \sum_{i \in J_0} \mathbb{E}\left[\frac{I(\lambda_{R_{1(i)}^\text{(-i)} + 1} < p_{1i} \leq \lambda'_{S_{1(i)}^\text{(-i)} + 1} : q_{1(i)} \leq \gamma_{R_{1(i)}^\text{(-i)} + R_{1(i)}^\text{(-i)} + 1, S_{1(i)}^\text{(-i)} + 1}}{R_{1(i)}^\text{(-i)} + \lambda_{S_{1(i)}^\text{(-i)} + 1} + 1}\right].$$

The theorem is proved in Appendix.

3.1 BH-type Procedures

We are now ready to propose our FDR controlling multiple testing procedures in a two-stage adaptive design setting with
combination function. Before that, let us state some assumptions we need.

**Assumption 1.** The combination function \( C(p_1, p_2) \) is non-decreasing in both arguments.

**Assumption 2.** The pairs \((p_{i1}, p_{i2}), i = 1, \ldots, m\), are independently distributed and the corresponding pairs to the null hypotheses are identically distributed as \((p_1, p_2)\) with a joint distribution that satisfies the “p-cloud” property (Brannath, Posch, and Bauer 2002), that is,

\[
\Pr(p_1 \leq u) \leq u \quad \text{and} \quad \Pr(p_2 \leq u | p_1) \leq u \quad \text{for all} \quad 0 \leq u \leq 1.
\]

Let us define the function

\[
H(c; t, t') = \int_0^t \int_0^1 I(C(u_1, u_2) \leq c) du_2 du_1, \quad 0 < c < 1.
\]

When testing a single hypothesis based on the pair \((p_1, p_2)\) using \(t\) and \(t'\) as the first-stage rejection and acceptance thresholds, respectively, and \(c\) as the second-stage rejection threshold, \(H(c; t, t')\) is the chance of this hypothesis to be followed up and rejected in the second stage when it is null.

**Definition 1.** (BH-TSADC Procedure).

1. Given the level \( \alpha \) at which the overall FDR is to be controlled, three sequences of constants \( \lambda_i = i\lambda/m, i = 1, \ldots, m, \lambda'_i = i\lambda'/m, i = 1, \ldots, m, \) for some prefixed \( \lambda < \lambda' \), and \( y_{r_1+1, \lambda} \leq \cdots \leq y_{r_1, R_1} \), satisfying

\[
H(y_{r_1+1, \lambda}; \gamma_{r_1}, \lambda'_i) = \frac{(r_1 + i)(\alpha - \lambda)}{m},
\]

\(i = 1, \ldots, s_1 - r_1,\) for every fixed \( 1 \leq r_1 < s_1 \leq m \), find \( R_1 = \max\{1 \leq i \leq m : p_{i1}(j) \leq \lambda_j\} \) for all \( j \leq i \) and \( S_1 = \max\{1 \leq i \leq m : p_{i2}(j) \leq \lambda'_i\} \), with \( R_1 \) or \( S_1 \) being equal to zero if the corresponding maximum does not exist.

2. Reject \( H_{(i)} \) for \( i \leq R_1; \) accept \( H_{(i)} \) for \( i > S_1; \) and continue testing \( H_{(i)} \) for \( R_1 < i \leq S_1 \), if \( R_1 < S_1 \), making use of the additional \( p\)-values \( p_{22} \), available for all such follow-up hypotheses at the second stage.

3. At the second stage, consider the combined \( p\)-values \( q_i = C(p_{i1}, p_{i2}) \) for the follow-up null hypotheses. Let \( q_{(i)}, i = 1, \ldots, S_1 - R_1, \) be their ordered versions. Reject \( H_{(i)} \) (the null hypothesis corresponding to \( q_{(i)} \)) for all \( i \leq R_2(R_1, S_1) = \max\{1 \leq j \leq S_1 - R_1 : q_{(j)} \leq y_{R_1+1, R_1} \} \), provided this maximum exists, otherwise, reject none of the follow-up null hypotheses.

**Proposition 1.** Let \( \hat{\pi}_0 \) be the proportion of true null hypotheses. Then, the FDR of the BH-TSADC method is less than or equal to \( \hat{\pi}_0 \alpha \), and hence controlled at \( \alpha \), if Assumptions 1 and 2 hold.

The proposition is proved in Appendix.

The BH-TSADC procedure can be implemented alternatively, and often more conveniently, in terms of some FDR estimates at both stages. With \( R^{(1)}(t) = \#\{i : p_{i1} \leq t\} \) and \( R^{(2)}(c; t, t') = \#\{i : t < p_{i1} \leq t', C(p_{i1}, p_{i2}) \leq c\} \), let us define

\[
\hat{\text{FDR}}_1(t) = \begin{cases} \frac{mt}{R^{(1)}(t)} & \text{if } R^{(1)}(t) > 0 \\ 0 & \text{if } R^{(1)}(t) = 0, \end{cases}
\]

and

\[
\hat{\text{FDR}}_2(c; t, t') = \begin{cases} \frac{mH(c; t, t')}{R^{(1)}(t) + R^{(2)}(c; t, t')} & \text{if } R^{(2)}(c; t, t') > 0 \\ 0 & \text{if } R^{(2)}(c; t, t') = 0. \end{cases}
\]

Then, we have the following:

**The BH-TSADC procedure: An alternative definition.** Reject \( H_{(i)} \) for all \( i \leq R_1 = \max\{1 \leq k \leq m : \hat{\text{FDR}}_1(p_{i1}(j)) \leq \lambda\} \) for all \( j \leq k \); accept \( H_{(i)} \) for all \( i > S_1 = \max\{1 \leq k \leq m : \hat{\text{FDR}}_2(p_{i1}(j)) \leq \lambda'\} \); continue to test \( H_{(i)} \) at the second stage for all \( i \) such that \( R_1 < i \leq S_1 \), if \( R_1 < S_1 \). Reject \( H_{(i)} \), the follow-up null hypothesis corresponding to \( q_{(i)} \), at the second stage for all \( i \leq R_2(R_1, S_1) = \max\{1 \leq k \leq S_1 - R_1 : \hat{\text{FDR}}_2(q_{(k)}; R_1, S_1) \leq \lambda\} \).

**Remark 2.** The BH-TSADC procedure is an extension of the BH procedure, from a method of controlling the FDR in a single-stage design to that in a two-stage adaptive design with combination tests. When \( \lambda = 0 \) and \( \lambda' = 1 \), that is, when we have a single-stage design based on the combined \( p\)-values, this method reduces to the usual BH method. Note that \( \hat{\text{FDR}}_1(t) \) is a conservative estimate of the FDR of the single-step test with the rejection \( p_i \leq t \) for each \( H_i \). So, the BH-TSADC procedure screens out those null hypotheses as being rejected (or accepted) at the first stage the estimated FDR’s at whose \( p\)-values are all less than or equal to \( \lambda \) (or greater than \( \lambda' \)).

Clearly, the BH-TSADC procedure can potentially be improved in terms of having a tighter control over its FDR at \( \alpha \) by plugging a suitable estimate of \( \pi_0 \) into it while choosing the second-stage thresholds, similar to what is done for the BH method in a single-stage design. As said in Section 2, there are different ways of estimating \( \pi_0 \), each of which has been shown to provide the ultimate control of the FDR, of course when the \( p\)-values are independent, by the resulting plugged-in version of the single-stage BH method (see, e.g., Sarkar 2008). However, we will consider the following estimate of \( \pi_0 \), which is of the type considered in Storey, Taylor, and Siegmund (2004) and seems natural in the context of the present adaptive design setting where \( m - S_1 \) of the null hypotheses are accepted as being true at the first stage:

\[
\hat{\pi}_0 = \frac{m - S_1 + 1}{m(1 - \lambda')}. \]

The following theorem gives a modified version of the BH-TSADC procedure using this estimate.

**Definition 2.** (Plug-In BH-TSADC Procedure).

Consider the BH-TSADC procedure with \( R_1 \) and \( S_1 \) based on the sequences of constants \( \lambda_i = i\lambda/m, i = 1, \ldots, m, \) and \( \lambda'_i = i\lambda'/m, i = 1, \ldots, m, \) given \( 0 \leq \lambda < \lambda' \leq 1 \), and the second-stage critical values \( y^*_R_{R_1+1, R_1} \), \( i = 1, \ldots, S_1 - R_1 \), given by the equations

\[
H\left(y^*_R_{R_1+1, R_1} ; \gamma_{R_1}, \lambda'_i \right) = \frac{(r_1 + i)(\alpha - \lambda)}{m\hat{\pi}_0},
\]

for \( i = 1, \ldots, s_1 - r_1 \).

**Proposition 2.** The FDR of the Plug-In BH-TSADC method is less than or equal to \( \alpha \) if Assumptions 1 and 2 hold.
Figure 2. Comparison of simulated average powers of BH-TSADC and Plug-In BH-TSADC procedures with simulated average powers of first-stage and full-data BH procedures, with $m = 100$, $\lambda = 0.005$, 0.010, and 0.025, $\lambda' = 0.5$, and $\alpha = 0.05$. The online version of this figure is in color.

**Simes’ combination function:**

$$C(p_1, p_2) = \min \{2 \min(p_1, p_2), \max(p_1, p_2)\}.$$  

$$H_{\text{Simes}}(c; t, t') = \int_0^t \int_0^1 I(C(u_1, u_2) \leq c) \, du_2 \, du_1$$

$$= \begin{cases} 
\frac{c}{2}(t' - t) & \text{if } c \leq t \\
\frac{c}{2}(t' - t) + \frac{c^2}{2} & \text{if } t < c \leq \min(2t, t') \\
c(t' - t) & \text{if } t' < c \leq 2t \\
\frac{c}{2}(1 + t') - t & \text{if } 2t < c \leq t' \\
\frac{c}{2}(1 + 2t') - \frac{c^2}{2} - t & \text{if } \max(2t, t') \leq c \leq 2t' \\
t' - t & \text{if } c \geq 2t', 
\end{cases}$$

for $c \in (0, 1)$.

See also Brannath, Posch, and Bauer (2002) for formula (2). These formulas can be used to determine the critical values $\gamma_i$’s before observing the combined $p$-values or to estimate the FDR after observing the combined $p$-values at the second stage in the BH-TSADC and Plug-In BH-TSADC procedures with Fisher’s and Simes’ combination functions. Of course, for large values of $m$, it is numerically more challenging to determine the $\gamma_i$’s than estimating the FDR at the second stage, and so in that case we would recommend using the alternative versions of these procedures.

Given the $p$-values from the two stages, Fisher’s combination function allows us to give equal importance to the evidences from both stages before forming a composite evidence toward deciding on the corresponding null hypothesis. Simes’ combination function, on the other hand, allows us to make this decision based on the strength of evidence provided by each individual $p$-value relative to the other.

4. SIMULATION STUDIES

There are a number of important issues related to our proposed procedures that are worth investigating. Modifying the
first-stage BH method to make it more powerful in the present two-stage adaptive design setting relative to the ideal BH method that would have been used had the second stage data been collected for all the hypotheses, without losing the ultimate control over the FDR, is an important rationale behind developing our proposed methods. Hence, it is important to numerically investigate how well the proposed procedures control the FDR and how powerful they can potentially be compared to both the first-stage and ideal BH methods. Since the ultimate control over the FDR has been theoretically established for our methods only under independence, it would be worthwhile to provide some insight through simulations into their FDRs under some dependence situations. The consideration of cost efficiency is as essential as that of improved power performance while choosing a two-stage multiple testing procedure over its single-stage version, and so it is also important to provide numerical evidence of how much cost savings our procedures can potentially offer relative to the maximum possible cost incurred by using the ideal BH method. We conducted our simulation studies addressing these issues. More details about these studies and conclusions derived from them are given in the following subsections.

4.1 FDR and Power Under Independence

To investigate how well our procedures perform relative to the first-stage and full-data BH methods under independence, we (1) generated two independent sets of $m$ uncorrelated random variables $Z_i \sim N(\mu_i, 1)$, $i = 1, \ldots, m$, one for Stage 1 and the other for Stage 2, having set $m\pi_0$ of these $\mu_i$’s at zero and the rest at 2; (2) tested $H_i : \mu_i = 0$ against $K_i : \mu_i > 0$, simultaneously for $i = 1, \ldots, m$, by applying each of the following procedures at $\alpha = 0.05$ to the generated data: The (alternative versions of) BH-TSADC and Plug-In BH-TSADC procedures, each with Fisher’s and Simes’ combination functions, the first-stage BH method, and the BH method based on combining the data from two stages (which we call the full-data BH method); and (3) noted the false discovery proportion and the proportion of
false nulls that are rejected. We repeated Steps 1–3 1000 times and averaged out the above proportions over these 1000 runs to obtain the final simulated values of FDR and average power (the expected proportion of false nulls that are rejected) for each of these procedures.

The simulated FDRs and average powers of these procedures for different values of $\pi_0$ and selections of early stopping boundaries have been graphically displayed in Figures 1–8. Figures 1 and 3 compare the BH-TSADC and Plug-In BH-TSADC procedures based on both Fisher’s and Simes combination functions with the first-stage and full-data BH procedures in terms of the FDR control for $m = 100$ (Figure 1) and 1000 (Figure 3), the early rejection boundary $\lambda = 0.005, 0.010, 0.025$, and the early acceptance boundary $\lambda' = 0.5$; whereas, Figures 2 and 4 do the same in terms of the average power. Figures 5–8 are reproductions of Figures 1–4, respectively, with different selections of early rejection and acceptance boundaries: $\lambda = 0.025$ and $\lambda' = 0.5, 0.8,$ or $0.9$.

### 4.2 FDR Under Dependence

We considered three different scenarios for dependent $p$-values in our simulation study to investigate the FDR control of our procedures under dependence. In particular, we generated two independent sets of $m = 100$ correlated normal random variables $Z_i \sim N(\mu_i, 1), i = 1, \ldots, m$, one for Stage 1 and the other for Stage 2, with $m\pi_0$ of the $\mu_i$’s being equal to 0 and the rest being equal to 2, and a correlation matrix exhibiting one of the three different types of dependence—equal, clumpy, and AR(1) dependence. In other words, the $Z_i$’s were assumed to have a common, nonnegative correlation $\rho$ in case of equal dependence, were broken up into 10 independent groups with 10 of the $Z_i$’s within each group having a common, nonnegative correlation $\rho$ in case of clumpy dependence, and were assumed to have correlations $\rho_{ij} = \text{Cor}(Z_i, Z_j)$ of the form $\rho_{ij} = \rho^{|i-j|}$ for all $i \neq j = 1, \ldots, m$, and some nonnegative $\rho$ in case of AR(1) dependence. We then applied the (alternative versions of) the BH-TSADC and Plug-In BH-TSADC procedures at level...
4.3 Cost Saving

Let us consider determining the cost saving in the context of a genome-wide association study. Because of high cost of genotyping hundreds of thousands of markers on thousands of subjects, such genotyping is often carried out in a two-stage format. A proportion of the available samples are genotyped on a large number of markers in the first stage, and a small proportion of these markers are selected and then followed up by genotyping them on the remaining samples in the second stage.

Suppose that $c$ is the unit cost of genotyping one marker for each patient, $n$ is the total number of patients assigned across stages 1 and 2, and $m$ is the total number of markers for each patient. Then, if we had to apply the full-data BH method, the total cost of genotyping for all these patients would be $n \times m \times c$. Whereas, if we apply our proposed methods with a fraction $f$ of the $n$ patients assigned to stage 1, then the expected total cost would be $f \times n \times m \times c + (1 - f) \times n \times [m - E(S(f))] \times c$, where $S(f)$ is the total number of rejected and accepted hypotheses in the first stage. Thus, for our proposed methods, the expected proportion of saving from the maximum possible cost of using the full-data BH method is

$$\frac{(1 - f) \times n \times E(S(f)) \times c}{m \times n \times c} = \frac{(1 - f)E(S(f))}{m}.$$ 

Table 1 presents the simulated values of this expected proportion of cost saving for our proposed two-stage methods in multiple testing of $m$ ($= 100, 1000, \text{or} 5000$) independent normal means in the present two-stage setting with a fraction $f$.
Figure 6. Comparison of simulated average powers of BH-TSADC and Plug-In BH-TSADC procedures with simulated average powers of first-stage and full-data BH procedures, with $m = 100$, $\lambda = 0.025$, $\lambda' = 0.5$, 0.8, 0.9, and $\alpha = 0.05$. The online version of this figure is in color.

(= 0.25, 0.50, or 0.75) of the total number of patients being allocated to the first stage.

4.4 Conclusions

Our simulations in Sections 4.1 and 4.2 mimic the scenarios with equal allocation of sample size between the two stages. So, if we measure the performance of a two-stage procedure by how much power improvement it can offer over the first-stage BH method relative to that offered by the ideal, full-data BH method, then our proposed two-stage FDR controlling procedures with Fisher’s combination function are seen from Figures 1 to 8 to do much better under such equal allocation, at least when the $p$-values are independent both across the hypotheses and stages, than those based on Simes’ combination function. Of course, our procedures based on Simes’ combination function are doing reasonably well in terms of this measure of relative power improvement. Its performance is roughly between those

<table>
<thead>
<tr>
<th></th>
<th>$\pi_0 = 0.5$</th>
<th>$\pi_0 = 0.9$</th>
<th>$\pi_0 = 0.5$</th>
<th>$\pi_0 = 0.9$</th>
<th>$\pi_0 = 0.5$</th>
<th>$\pi_0 = 0.9$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$f = 0.25$</td>
<td>0.4321</td>
<td>0.5653</td>
<td>0.4337</td>
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<tr>
<td>$f = 0.50$</td>
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<td>0.4325</td>
<td>0.2442</td>
<td>0.4401</td>
<td>0.2442</td>
<td>0.4407</td>
</tr>
<tr>
<td>$f = 0.75$</td>
<td>0.1075</td>
<td>0.2300</td>
<td>0.1082</td>
<td>0.2319</td>
<td>0.1090</td>
<td>0.2320</td>
</tr>
</tbody>
</table>

Table 1. Simulated values of the expected proportion of cost saving (with $\lambda = 0.025$ and $\lambda' = 0.5$)
of the first-stage and the full-data BH methods. Between our two proposed procedures, whether it is based on Fisher’s or Simes’ combination function, the BH-TSADC appears to be the better choice when \( \pi_0 \) is large, like more than 50%, which is often the case in practice. It controls the FDR not only under independence, which is theoretically known, but also the FDR control seems to be maintained even under different types of positive dependence, as seen from Figures 9 to 11. If, however, \( \pi_0 \) is not large, the Plug-In BH-TSADC procedure provides a better control of the FDR, although it might lose the FDR control when the statistics generating the \( p \)-values exhibit equal but moderate to high dependence. Also seen from Figures 1 to 8, there is no appreciable difference in the power performances of the proposed procedures over different choices of the early stopping boundaries. From Table 1, we notice that our two-stage methods can provide large cost savings. For instance, with 90% true nulls and half of the total sample size allocated to the first stage, our procedures can offer 44% saving from the maximum cost of using the ideal, full-data BH method. This proportion gets larger with increasing proportion of true nulls or decreasing proportion of the total sample size allocated to the first stage.

5. A REAL DATA APPLICATION

To illustrate how the proposed procedures can be implemented in practice, we reanalyzed a dataset taken from an experiment by Tian et al. (2003) and post-processed by Jeffery, Higgins, and Culhance (2006). Zehetmayer, Bauer, and Posch (2008) considered these data for a different purpose. In this dataset, multiple myeloma samples were generated with Affymetrix Human U95A chips, each consisting 12,625 probe sets. The samples were split into two groups based on the presence or the absence of focal lesions of bone.

The original dataset contains gene expression measurements of 36 patients without and 137 patients with bone lytic lesions. However, for the illustration purpose, we used the gene expression measurements of 36 patients with bone lytic lesions and a control group of the same sample size without such lesions. We
considered these data in a two-stage framework, with the first 18 subjects per group for Stage 1 and the next 18 subjects per group for Stage 2. We prefixed the Stage 1 early rejection boundary $\lambda$ at 0.005, 0.010, or 0.015, and the early acceptance boundary $\lambda'$ at 0.5, 0.8, or 0.9, and applied the proposed (alternatives versions of) BH-TSADC and plug-in BH-TSADC procedures at the FDR level of 0.025.

In particular, we considered all $m = 12,625$ probe set gene expression measurements for the first stage data of 36 patients (18 patients per group) and the full data of 72 patients (36 patients per group) across two stages, and analyzed them based on a stepdown procedure with the critical values $\lambda_i = i\lambda/m$, $i = 1, \ldots, m$, and a stepup procedure with the critical values $\lambda'_i = i\lambda'/m$, $i = 1, \ldots, m$, using the corresponding $p$-values generated from one-sided $t$-tests applied to the first-stage data. We noted the probe sets that were rejected by the stepdown procedure and those that were accepted by the stepup procedure. With these numbers being $r_1$ and $m - s_1$, respectively, we took the probe sets that were neither rejected by the stepdown procedure nor accepted by the stepup procedure, that is, the probe sets with the first-stage $p$-values more than $r_1\lambda/m$ but less than or equal to $s_1\lambda'/m$, for further analysis using estimated FDR based on their first-stage and second-stage $p$-values combined through Fisher's and Simes’ combination functions as described in the alternative versions of the BH-TSADC and plug-in BH-TSADC procedures.

The results of this analysis are reported in Table 2. As seen from this table, the BH-TSADC with Fisher’s combination function is doing the best. For instance, with $\lambda = 0.005$ and $\lambda' = 0.9$, the proportion of additional discoveries it makes over the first-stage BH method is $104/125 = 83.2\%$ of such additional discoveries that the ideal, full-data BH method could make, whereas these percentages are $52/125 = 41.6\%$, $32/125 = 25.6\%$, and $16/125 = 12.8\%$ for the BH-TSADC with Simes’ combination function, the Plug-In BH-TSADC with Fisher’s combination function, and the Plug-In BH-TSADC
Figure 9. Comparison of simulated FDRs of BH-TSADC and Plug-In BH-TSADC procedures under equal dependence with \( m = 100, \lambda = 0.025, \lambda' = 0.5, \) and \( \alpha = 0.05. \) The online version of this figure is in color.

With Simes’ combination function, respectively. This pattern of dominance of the BH-TSADC with Fisher’s combination function over the other procedures is noted for other values of \( \lambda \) and \( \lambda' \) as well.

This table provides some additional insights into our procedures. For instance, under positive dependence across hypotheses, which can be assumed to be the case for this dataset, it appears that the BH-TSADC procedure, with either Fisher’s or Simes’ combination function, tend to become steadily more powerful with increasing \( \lambda' \) but fixed \( \lambda \) or with decreasing \( \lambda \) but fixed \( \lambda' \). Note that we did not have the opportunity to get this insight from our simulation studies.

Table 2. The numbers of discoveries made out of 12625 probe sets in the Affymetrix Human U95A Chips data from Tian et al. (2003) by the BH-TSADC and Plug-In BH-TSADC procedures, each with either Fisher’s or Simes’ combination function, at the FDR level of 0.025.
Figure 10. Comparison of simulated FDRs of BH-TSADC and Plug-In BH-TSADC procedures under clumpy dependence with $m = 100$, $\lambda = 0.025$, $\lambda' = 0.5$, and $\alpha = 0.05$. The online version of this figure is in color.

Figure 11. Comparison of simulated FDRs of BH-TSADC and Plug-In BH-TSADC procedures under AR(1) dependence with $m = 100$, $\lambda = 0.025$, $\lambda' = 0.5$, and $\alpha = 0.05$. The online version of this figure is in color.
6. CONCLUDING REMARKS

This article has been motivated by the need to have a two-stage strategy for testing multiple null hypotheses, not known before, that allows making early decisions on the null hypotheses in terms of rejection, acceptance, or continuation to the second stage for further testing with more observations, and eventually controls the FDR in a nonasymptotic setting, as the first step toward designing an FDR based two-stage study. We have produced two such strategies by generalizing the classical BH method and its adaptive version from single-stage to the present two-stage setting. We have proved their FDR control under independence and provided simulation evidence showing their meaningful improvements over the first-stage BH method relative to those ideally offered by the full-data BH method in terms of both power and cost savings, and given an example of their utilities in practice. We also have presented numerical evidence that the proposed strategies can maintain a control over the FDR even under some dependence situations.

Now that we know how to test multiple hypotheses in the present two-stage adaptive design format controlling the FDR, we can get to addressing issues related to designing FDR based two-stage studies. One such issue is optimal allocation of sample sizes to the two stages. Let us briefly outline the steps one can take toward addressing this issue.

Suppose that we have a study involving m genes, and our problem is to identify the differentially expressed genes between two independent groups by simultaneously testing \(H_i: \delta_i = 0\) against \(K_i: \delta_i \neq 0\) for \(i = 1, \ldots, m\), where \(\delta_i = (\mu_{i1} - \mu_{i2})/\sigma_i\) is the (standardized) effect size defined in terms of \(\mu_{i1}\) and \(\mu_{i2}\), the group means, and \(\sigma_i^2\), the common group variance, for the \(i\)th gene, given that we decide to have the maximum \(N\) number of observations per gene for all the groups and stages combined and choose some fixed early stopping boundaries \(\lambda < \lambda'\). Assume that the observed expression levels for each group follow normal distributions, with proper normalization, so that we can apply the two-sample \(t\) test once such observations are available. We consider using equal sample size per group for this test. An optimal FDR based two-stage design based on our method of multiple testing can be constructed as follows.

Assume that we take \(n_1 = Nf/2\) observations per group for each gene at the first stage, for some fraction \(0 < f < 1\), and additional \(n_2 = N(1 - f)/2\) observations per group for each of the \(m - S(f)\) follow-up genes, where \(S(f)\) denotes (as in Section 3.4) the total number of rejected and accepted null hypotheses at the first stage. Let \(\bar{x}_{i1}\) and \(\bar{y}_{i1}\) be the estimates of \(\mu_{i1}\) and \(\mu_{i2}\), respectively, and \(s^2_{i1}\) be the pooled estimate of \(\sigma_i^2\) for the \(i\)th gene based on the first-stage observations, and \(\bar{x}_{i2}\), \(\bar{y}_{i2}\), and \(s^2_{i2}\) be those estimates based on the additional observations for the \(i\)th follow-up gene. Let \(t_{ij} = (\bar{x}_{ij} - \bar{y}_{ij})/s_{ij}\sqrt{2/n_{ij}} = \delta_i\sqrt{n_{ij}/2}\), where \(\delta_{ij} = (\bar{x}_{ij} - \bar{y}_{ij})/s_{ij}\), for \(i = 1, \ldots, m, j = 1, 2\). Then, \(p_{i1} = 2[1 - G_i(|t_{i1}|)]\) is the first-stage \(p\)-value for the \(i\)th gene, for \(i = 1, \ldots, m\), and \(p_{i2} = 2[1 - G_j(|t_{i2}|)]\) is the second-stage \(p\)-value for the \(i\)th follow-up gene, where \(G_j\) is the cumulative distribution function of the central \(t\) distribution with \(n_j - 2\) degrees of freedom.

Now, if we find the \(f\) for which our proposed two-stage method of multiple testing based on these first- and second-stage \(p\)-values maximize the average power at specified alternatives for some targeted genes, then that \(f\) will provide a good FDR based two-stage design, given \(N, \lambda\) and \(\lambda'\). Of course, it brings forth some newer and interesting theoretical issues that need to be addressed.

We have proposed our FDR controlling procedures in this article considering a nonasymptotic setting. However, one may consider developing procedures that would asymptotically control the FDR by taking the following approach toward finding the first- and second-stage thresholds subject to the early boundaries \(\lambda < \lambda'\) and the final boundary \(\alpha\) on the FDR. Given two constants \(t < t'\), consider making an early decision regarding \(H_i\) by rejecting it if \(p_{i1} \leq t\), accepting it if \(p_{i1} > t'\), and continuing to test it at the second stage if \(t < p_{i1} \leq t'\). At the second stage, reject \(H_i\) if \(C(p_{i1}, p_{i2}) \leq c\). Storey’s (2002) estimate of the FDR at the first-stage is given by

\[
FDR_1(t) = \left\{ \begin{array}{ll}
m_{p_1}t/R(1)(t) & \text{if } R(1)(t) > 0 \\ 0 & \text{if } R(1)(t) = 0, \end{array} \right.
\]

for some estimate \(\hat{m}_0\) of \(m_0\). Similarly, the cumulative FDR at the second stage can be estimated as follows:

\[
FDR_2(c, t, t') = \left\{ \begin{array}{ll}
m_{\delta_2}[t + H(c; t, t')] & \text{if } R(1)(t) + R(2)(c; t, t') > 0 \\ R(1)(t) + R(2)(c; t, t') & \text{if } R(1)(t) + R(2)(c; t, t') = 0. \end{array} \right.
\]

Let

\[
\hat{\pi}_c(t) = \sup_{t' : FDR_1(t') \leq \lambda} \{t' : FDR_1(t') > \lambda' \text{ for all } t' > t\},
\]

and

\[
\hat{c}_\alpha(\lambda, \lambda') = \sup\{c : FDR_2(c, \hat{\pi}_c(t), \hat{\pi}_c(t')) \leq \alpha\}.
\]

Then, reject \(H_i\) if \(p_{i1} \leq \hat{\pi}_c(t)\) or if \(\hat{\pi}_c(t) < p_{i1} \leq \hat{\pi}_c(t')\) and \(C(p_{i1}, p_{i2}) \leq \hat{c}_\alpha(\lambda, \lambda')\). This may control the overall FDR asymptotically under the weak dependence condition and the consistency property of \(\hat{m}_0\) (as in Storey, Taylor, and Siegmund 2004).

The foregoing discussion also suggests how to estimate the FDR for each hypothesis in a completed two-stage design of the present form. For instance, for hypothesis with the pair of \(p\)-values \((p_1, p_2)\), the estimated FDR is \(FDR_1(p_1)\) if \(p_1 \leq \hat{\pi}_c(t)\), or \(p_1 \geq \hat{\pi}_c(t')\), and is \(FDR_2(c(p_{i1}, p_{i2}), \hat{\pi}_c(t), \hat{\pi}_c(t'))\) if \(\hat{\pi}_c(t) < p_{i1} < \hat{\pi}_c(t')\).

There is another important issue related to the present problem which we have not touched in this article but hope to address in a different communication. There are other combination functions, such as Fisher’s weighted product (Fisher 1932) and weighted inverse normal (Mosteller and Bush 1954); their performances would be worth investigating.

APPENDIX

Proof of Theorem 1.

\[
FDR_{12} = E\left[ \frac{V_1 + V_2}{\max[R_1 + R_2, 1]} \right] \leq E\left[ \frac{V_1}{\max[R_1, 1]} \right] + E\left[ \frac{V_2}{\max[R_1 + R_2, 1]} \right].
\]
Now,
\[
E \left[ \frac{V_1}{\max(R_1, 1)} \right] = \sum_{i \in h} E \left[ \frac{I(p_i \leq \lambda R_i)}{\max(R_1, 1)} \right] 
\leq \sum_{i \in h} E \left[ \frac{I(p_i \leq \lambda R_i^{-1})}{R_i^{-1} + 1} \right],
\]
(as shown in Sarkar 2008; see also Result 1). And,
\[
E \left[ \frac{V_2}{\max(R_1 + R_2, 1)} \right] = \sum_{i \in h} E \left[ \frac{I(\lambda R_i < p_i \leq \lambda_{i}^\prime, q_i \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0)}{R_1 + R_2} \right] 
\times \left[ I(\lambda_{i+1} < p_i \leq \lambda_{i}^\prime, q_i \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0) \right] 
= \sum_{i \in h} \sum_{j=1}^m \sum_{r=1}^{R_1} \sum_{s=1}^{R_2} E \left[ \frac{I(\lambda R_i < p_i \leq \lambda_{i}^\prime, q_i \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0)}{R_1 + R_2} \right] 
\times \left[ I(\lambda_{i+1} < p_i \leq \lambda_{i}^\prime, q_i \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0) \right] 
= \sum_{i \in h} \sum_{j=1}^m \sum_{r=1}^{R_1} \sum_{s=1}^{R_2} E \left[ \frac{I(\lambda R_i < p_i \leq \lambda_{i}^\prime, q_i \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0)}{R_1 + R_2} \right] 
\times \left[ I(\lambda_{i+1} < p_i \leq \lambda_{i}^\prime, q_i \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0) \right].
\]
Writing \( R_2 \) more explicitly in terms of \( R_1 \) and \( S_1 \), we see that the expression in Equation (3) is equal to
\[
\sum_{i \in h} \sum_{j=1}^m \sum_{r=1}^{R_1} \sum_{s=1}^{R_2} E \left[ \frac{I(\lambda_{i+1} < p_i \leq \lambda_{i}^\prime, q_i \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0)}{R_1 + R_2} \right] 
\times \left[ I(\lambda_{i+1} < p_i \leq \lambda_{i}^\prime, q_i \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0) \right] \]
\[
= \sum_{i \in h} \sum_{j=1}^m \sum_{r=1}^{R_1} \sum_{s=1}^{R_2} \left[ I(\lambda_{i+1} < p_i \leq \lambda_{i}^\prime, q_i \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0) \right] 
\times \left[ I(\lambda_{i+1} < p_i \leq \lambda_{i}^\prime, q_i \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0) \right].
\]
Thus, the theorem is proved. \( \square \)

**Proof of Proposition 1.**

\[
\text{FDR}_{12} \leq \sum_{i \in h} \left[ \frac{\Pr_H \left( p_i \leq \lambda R_i^{-1} \right)}{R_i^{-1} + 1} \right] + \sum_{i \in h} \left[ \frac{\Pr_H \left( \lambda R_i^{-1} < p_i \leq \lambda_{i}^\prime S_i^{-1} + C(p_1, p_2) \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0 \right)}{R_i^{-1} + R_2^{-1}} \right] 
\leq \sum_{i \in h} \left[ \frac{\lambda R_i^{-1} + 1}{R_i^{-1} + 1} \right] + \sum_{i \in h} \left[ \frac{\Pr \left( \lambda R_i^{-1} < p_i \leq \lambda_{i}^\prime S_i^{-1} + C(u_1, u_2) \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0 \right)}{R_i^{-1} + R_2^{-1}} \right] 
\times \left[ \frac{\lambda R_i^{-1} + 1}{R_i^{-1} + R_2^{-1}} \right].
\]
(A.2)

The first sum in Equation (4) is less than or equal to \( \pi_0 \lambda \), since \( \lambda R_i^{-1} + 1 = R_i^{-1} + 1 / m \), and the second sum is less than or equal to \( \pi_0 (\alpha - \lambda) \), since the probability in the numerator in this sum is equal to
\[
H \left( y_{R_i+R_2, S_i}, \lambda R_i^{-1}, \lambda_{i}^\prime S_i^{-1} + C(u_1, u_2) \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0 \right) \]
\[
\frac{\lambda R_i^{-1} + 1}{R_i^{-1} + R_2^{-1}} (\alpha - \lambda).
\]
Thus, the proposition is proved. \( \square \)

**Proof of Proposition 2.** This can be proved as in Proposition 1. More specifically, first note that the FDR here, which we call the \( \text{FDR}_{12} \), satisfies the following:
\[
\text{FDR}_{12} \leq \sum_{i \in h} \left[ \frac{\Pr_H \left( p_i \leq \lambda R_i^{-1} \right)}{R_i^{-1} + 1} \right] + \sum_{i \in h} \left[ \frac{\Pr_H \left( \lambda R_i^{-1} < p_i \leq \lambda_{i}^\prime S_i^{-1} + C(p_1, p_2) \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0 \right)}{R_i^{-1} + R_2^{-1}} \right] 
\times \left[ \frac{\lambda R_i^{-1} + 1}{R_i^{-1} + R_2^{-1}} \right],
\]
(A.3)
where
\[
R_2^{-1} = R_2^{-1} (R_i^{-1}, S_i^{-1} + 1) = \max \left\{ 1 \leq j \leq S_i^{-1} - R_i^{-1} : q_j^{(i)} \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0 \right\},
\]
with \( q_j^{(i)} \) being the ordered versions of the combined \( p \)-values except the \( q_i \). As in Proposition 1, the first sum in Equation (5) is less than or equal to \( \pi_0 \lambda \). Before working with the second sum, first note that the \( \gamma^* \)-satisfying Equation (1), that is, the following equation:
\[
H \left( y_{R_i+R_2, S_i}, \lambda R_i^{-1}, \lambda_{i}^\prime S_i^{-1} + C(p_1, p_2) \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0 \right) \]
\[
\frac{\lambda R_i^{-1} + 1}{R_i^{-1} + R_2^{-1}} (\alpha - \lambda),
\]

is less than or equal to the \( \gamma^{**} \) satisfying
\[
H \left( y_{R_i+R_2, S_i}, \lambda R_i^{-1}, \lambda_{i}^\prime S_i^{-1} + C(p_1, p_2) \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0 \right) \]
for any fixed \( j = 1, \ldots, m \). So, the second sum in Equation (5) is less than or equal to
\[
\sum_{i \in h} \left[ \frac{\Pr \left( \lambda R_i^{-1} < p_i \leq \lambda_{i}^\prime S_i^{-1} + C(p_1, p_2) \leq y_{R_i+R_2, S_i}, S_i > R_1, R_2 > 0 \right)}{R_i^{-1} + R_2^{-1}} \right] 
\times \left[ \frac{\lambda R_i^{-1} + 1}{R_i^{-1} + R_2^{-1}} \right] 
\leq (\alpha - \lambda) \sum_{i \in h} \left[ \frac{1 - \lambda_{i}^\prime}{m - s_i^{-1}} \right] \leq \alpha - \lambda,
\]
since \( \sum_{i \in h} E \left[ \frac{1 - \lambda_{i}^\prime}{m - s_i^{-1}} \right] \leq 1 \); see, for instance, Sarkar (2008, p. 151). Hence, \( \text{FDR}_{12} \leq \pi_0 \lambda + \alpha - \lambda \leq \alpha \), which proves the proposition. \( \square \)

**SUPPLEMENTARY MATERIALS**

As suggested by one of the reviewers, we have examined the performance of our proposed procedures in a complicated genetic mode with exponentially decreasing effect sizes. The simulation results can be found in the supplementary materials.

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**REFERENCES**


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