## Math 222 Final Exam, December 16, 2016

Trigonometric identities:  $\sin(A+B) = \sin(A)\cos(B) + \sin(B)\cos(A)$ ,  $\cos(A+B) = \cos(A)\cos(B) - \sin(A)\sin(B)$ . Closed-book, show all your work, all phones off and no calculator.

- 1. (8 points) Find the solution of the IVP:  $x^2y'' 3xy' + 4y = 0$ , y(1) = 2, y'(1) = 3.
- 2. A function  $f(x) = \begin{cases} 0, & -\pi \le x < 0 \\ \sin(x), & 0 \le x < \pi \end{cases}$  is periodically extended as  $f(x + 2\pi) = f(x)$ .
  - (a) (5 points) Sketch three periods of this function.
  - (b) (10 points) Find the Fourier series of this function.
- 3. (15 points) Find the eigenvalues  $\lambda$  and eigenfunctions of the given boundary value problem

$$y'' + \lambda y = 0$$
,  $y(0) = y(2)$ ,  $y'(0) = y'(2)$ .

- 4. (a) Consider the ODE  $y' = (y^2 1)(y 3)$ . (6 points) First find the equilibrium solutions (i.e., y' = 0). (4 points) Then sketch the direction field.
  - (b) Consider the IVP:  $y' + \frac{2}{t}y = \frac{1}{t}$ , and the initial value is given at t = 1 as y(1) = 1. (10 points) Find the solution and describe its behavior as  $t \to \infty$ .
- 5. (a) (10 points) Solve the IVP:  $y'' + 4y' + 5y = 2e^{-t}$ , y(0) = 0, y'(0) = 1.
  - (b) (10 points) Find the general solution for the differential equation  $y'' + 4y = \sin(2t)$ .
- 6. (12 points) Use Laplace transform to find the solution of the IVP:  $y'' y = (t-1)u_1(t)$ , y(0) = 0, y'(0) = 1.  $u_1(t)$  is a unit step function that is zero when t < 1 and unity when  $t \ge 1$ .
- 7. (10 points) Consider two tanks, labeled tank A and tank B. Tank A contains 100 gal of water and 20 lb of salt. Tank B contains 200 gal of water and 40 lb of salt. Pure water flows into tank A at a rate of 5 gal/sec. There is a drain at the bottom of tank A. Solution leaves tank A via this drain at a rate of 5 gal/sec and flows immediately into tank B at the same rate. A drain at the bottom of tank B allows the solution to leave tank B, also at a rate of 5 gal/sec.
  - (a) Set up an IVP for the amount of salt in each tank by writing down two linear differential equations for the total amount of salt in tank A and tank B. Formulate the IVP as  $\mathbf{x}' = \mathbf{A}\mathbf{x}$ . Find the  $2 \times 2$  matrix  $\mathbf{A}$  and the initial condition  $\mathbf{x}(0)$ .
  - (b) Express the solution in terms of the eigenvectors of **A**. What is the total amount of salt in both tanks as functions of time?

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P. 0
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Grading Guidelines for Final Exam M222 Fall 2016

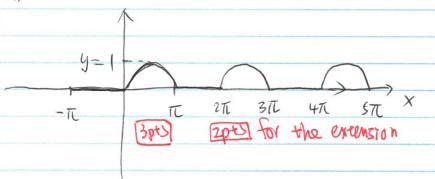
$$x^2y'' - 3xy' + 4y = 0$$
,  $y(1) = 2$ ,  $y(1) = 3$ 

$$y_{-} \times r_{-}$$
,  $r(r_{-}1) - 3r + 4 = 0$ ,  $r_{-}^{2} + 4r + 4 = 0$ ,

$$y'(1) = 3 = 2C_1 + C_2$$
  
 $y'(1) = 2 = 9$   $C_2 = 3 - 4 = -1$ 

$$y = 2x^2 - x^2 \ln x$$
 [2pts]

$$f(x) = \begin{cases} 0 & -\pi \leq x < 0 \\ \sin x & 0 \leq x < \pi \end{cases}$$



(b) 
$$f(x) = \frac{a_0}{2} + \sum_{n=1}^{\infty} a_n \cos \frac{n\pi x}{L} + b_n \sin \frac{n\pi x}{L}$$
,  $L = \pi L$ 

$$Q_0 = \frac{1}{L} \int_{-L}^{L} f(x) dx = \frac{1}{\pi L} \int_{-R}^{\pi} f(x) dx = \frac{1}{\pi L} \int_{-R}^{0} o dx + \int_{0}^{\pi} sin x dx$$

$$= -\frac{1}{\pi}\cos x \Big|_{0}^{\pi} = -\frac{1}{\pi}\left(\cos \pi - \cos x\right) = \frac{2}{\pi}\left(\frac{2pts}{2}\right)$$

$$Q_n = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cdot \cos^n \pi x \, dx = \frac{1}{\pi} \int_{0}^{\pi} \sin^n x \cos n x \, dx$$

$$G_{II} = \frac{1}{1\pi} \int_{0}^{\pi} \frac{1}{2} \left( \sin \left( \frac{1+n}{2} \right) x + \sin \left( \frac{1+n}{2} \right) y \right) dx$$

$$= \frac{1}{2\pi L} \left( -\frac{1}{1+n} \left( \cos \left( \frac{1+n}{2} \right) x - \frac{1}{1-n} \cos \left( \frac{1+n}{2} \right) x \right) \right)^{\frac{1}{L}}$$

$$= \frac{1}{2\pi L} \left( -\frac{1}{1+n} \left( \frac{1+n}{2} \right) x - \frac{1}{1-n} \left( \frac{1+n}{2} \right) x \right) - \frac{1}{1-n} \left( \frac{1+n}{2} \right) x \right)$$

$$= \frac{1}{2\pi L} \int_{0}^{\pi} \left( -\frac{1}{1+n} \right) \left( \frac{1+n}{2} \right) x - \frac{1}{2\pi L} \left( \frac{1+n}{2} \right) \left( \frac{1+n}{2} \right) x \right)$$

$$= \frac{1}{2\pi L} \int_{0}^{\pi} \left( \cos \left( \frac{1+n}{2} \right) x - \cos \left( \frac{1+n}{2} \right) x \right) dx$$

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$$= \frac{1}{2\pi L} \int_{0}^{\pi} \left( \cos \left( \frac{1+n}{2} \right) x - \cos \left( \frac{1+n}{2} \right) x - \cos \left( \frac{1+n}{2} \right) x \right) dx$$

$$= \frac{1}{2\pi L} \int_{0}^{\pi} \left( \cos \left( \frac{1+n}{2} \right) x - \cos \left( \frac{1+n}{2} \right) x$$

$$\lambda > 0, \quad y = \zeta_1 \text{ costs} \times + \zeta_2 \text{ sints} \times$$

$$y' = \sqrt{\lambda} \left( -\zeta_1 \text{ sints} \times + \zeta_2 \text{ costs} \times \right)$$

$$y(0) = \zeta_1 = y(2) = \zeta_1 \left( \cos \sqrt{\lambda} + \zeta_2 \text{ sints} \times \right)$$

$$\left( | - (\cos 2\sqrt{\lambda}) | \zeta_1 - \sin \sqrt{\lambda} | \zeta_2 = 0 \right) = \sqrt{\lambda} \left( -\zeta_1 \text{ sints} \times + \zeta_2 \text{ sints} \times \right)$$

$$\left( | - (\cos 2\sqrt{\lambda}) | \zeta_1 - \cos \sqrt{\lambda} | \zeta_2 = 0 \right) = \sqrt{\lambda} \left( -\zeta_1 \text{ sints} \times + \zeta_2 \text{ costs} \times \right)$$

$$\left( | - (\cos 2\sqrt{\lambda}) | \zeta_1 + (| - (\cos 2\sqrt{\lambda}) | \zeta_2 = 0 \right) = \sqrt{\lambda}$$

$$\left( | - (\cos 2\sqrt{\lambda}) | + (| - (\cos 2\sqrt{\lambda}) | \zeta_2 = 0 \right) = \sqrt{\lambda}$$

$$\left( | - (\cos 2\sqrt{\lambda}) | + (| - (\cos 2\sqrt{\lambda}) | \zeta_2 = 0 \right)$$

$$\left( | - (\cos 2\sqrt{\lambda}) | + (| - (\cos 2/\lambda) |$$

(1-e2/M) (, - (1-e2/M) (, =0

Problem 4

$$y' = (y^2 - 1)(y - 3)$$

(a) 
$$y = 0$$
  $(y^2 - 1)(y - 3) = 0$ ,  $y = \pm 1$ , 3 [6pts]

(b) 
$$y' + \frac{2}{t}y = \frac{1}{t}$$
,  $y(y=1)$ 

$$\mu = e^{\int \frac{2\pi}{t} dt} = e^{\int \frac{2\pi}{t} dt} = e^{\int \frac{2\pi}{t} dt} = e^{\int \frac{2\pi}{t} dt}$$
 [4pts]

$$(t^{2}y)'=t$$
,  $t^{2}y=\frac{t^{2}}{2}+c$ ,  $y=\frac{1}{2}+\frac{c}{4}$ 

$$J(1)=1=\frac{1}{2}+\frac{C}{1}, C=\frac{1}{2}$$

(a) 
$$y'' + 4y' + 5y = 2e^{-t}$$
  $y(0) = 0$ ,  $y'(0) = 1$ 

$$y_{10} = C_{1} + 1 = 0, \quad C_{1} = -1$$

$$y'_{1}(t) = -1e^{2t}(C_{1}OSt + C_{1}Smt) + C_{2}(OSt) - e^{2t}$$

$$y'_{1}(t) = -2e^{2t}(C_{1}) + 1 \cdot 1 \cdot C_{1} - 1 = 1, \quad C_{1} = -1$$

$$2 + C_{1} - 1 = 1, \quad C_{2} = 0,$$

$$y_{1}(t) = -e^{2t}COSt + e^{2t}$$

$$y'_{1} = C_{2}OSt + e^{2t}COSt + e^{2t}$$

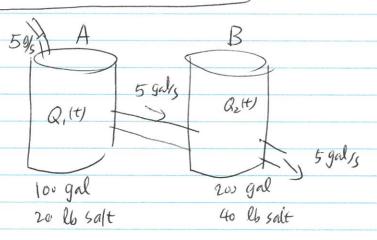
$$y'_{2} = C_{2}OSt + e^{2t}COSt +$$

$$(s^{2}-1)Y = 1 + \frac{e^{s}}{s^{2}}, Y = \frac{1}{s^{2}-1} + \frac{e^{-s}}{s^{2}(s^{2}-1)}$$

$$Y = 2[\frac{1}{s^{2}-1} + \frac{e^{s}}{s^{2}(s^{2}-1)}]$$

$$= 2\left[\frac{1}{S^{\frac{1}{2}}}\right] + 2\left[\frac{e^{5}}{S^{2}(S^{\frac{1}{2}})}\right]$$

$$J\left[\frac{1}{S^{2}(S^{2}-1)}\right] = J\left[-\frac{1}{S^{2}} + \frac{1}{S^{2}-1}\right] = -t + Sinht = f(t)$$
 [4.pt]



$$\frac{dV_A}{dt} = 5.5=0 \qquad V_A = const. = 100 \text{ gal}$$

$$\frac{dV_B}{dt} = 5-5=0, \quad V_B = \omega nst = 200 \text{ gal}$$

$$Q_1' = in - out = 0 - \frac{Q_1}{100} \times 5 = -\frac{Q_1}{20}$$

$$Q_{2}^{'} = \frac{Q_{1}x5}{100} - \frac{Q_{2}}{200}x5 = \frac{Q_{1}}{20} - \frac{Q_{2}}{40}$$

$$\begin{array}{c}
\left(\begin{array}{c}Q_{1}\\Q_{2}\end{array}\right)^{2} = \begin{pmatrix} -\frac{1}{2} & 0 \\ +\frac{1}{2} & -\frac{1}{4} & 0 \end{pmatrix} \begin{pmatrix} Q_{1}\\Q_{2}\end{pmatrix} \underbrace{\begin{array}{c} \mathcal{S} \text{ pti} \\ Q_{2} \end{array}}_{2} \\
\left(\begin{array}{c}-\frac{1}{2} & 0 \\ -\frac{1}{2} & -\frac{1}{4} & 0 \end{array}\right) \begin{pmatrix} \mathcal{Q}_{1}\\Q_{2} \end{pmatrix} \underbrace{\begin{array}{c} \mathcal{S} \text{ pti} \\ Q_{2} \end{pmatrix}}_{2} \\
\left(\begin{array}{c}-\frac{1}{2} & -\lambda \\ -\frac{1}{2} & -\frac{1}{4} & 0 \end{array}\right) \begin{pmatrix} \mathcal{Q}_{1}\\Q_{2} \end{pmatrix} = \begin{pmatrix} 0 \\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{1}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{1}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{1}\\Q_{2} \end{pmatrix} = \begin{pmatrix} 0 \\Q_{2}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{1}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{2}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{1}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{2}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{1}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{2}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{1}\\Q_{2}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{2}\\Q_{2}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{1}\\Q_{2}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{2}\\Q_{2}\\Q_{2}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{1}\\Q_{2}\\Q_{2}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{2}\\Q_{2}\\Q_{2}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{1}\\Q_{2}\\Q_{2}\\Q_{2}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{2}\\Q_{2}\\Q_{2}\\Q_{2}\\Q_{2}\\Q_{2} \end{pmatrix} \begin{pmatrix} \mathcal{Q}_{1}\\Q_{2}\\$$